



Institut
Mines-Télécom

Remote Sensing imaging

IMA207

Basics of remote sensing
Florence Tupin, Jean Marie Nicolas



Introduction

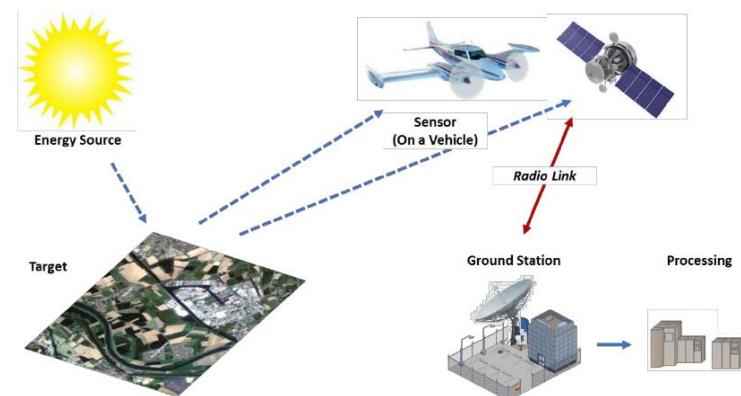
■ Remote sensing

- « Acquisition of information about an object or phenomenon without making any physical contact with the object in contrast to on site observation»
- Use of satellite or aircraft based sensor technologies to detect and classify objects on earth



■ Milestones

- 1844: first photos from balloons
- 1900-1960 : aerial photos
- 1960-: space sensors





The New Space



Bloostar launcher
(Zero 2 Infinity)



New Shepard for spatial
Tourism (**Blueorigin**)



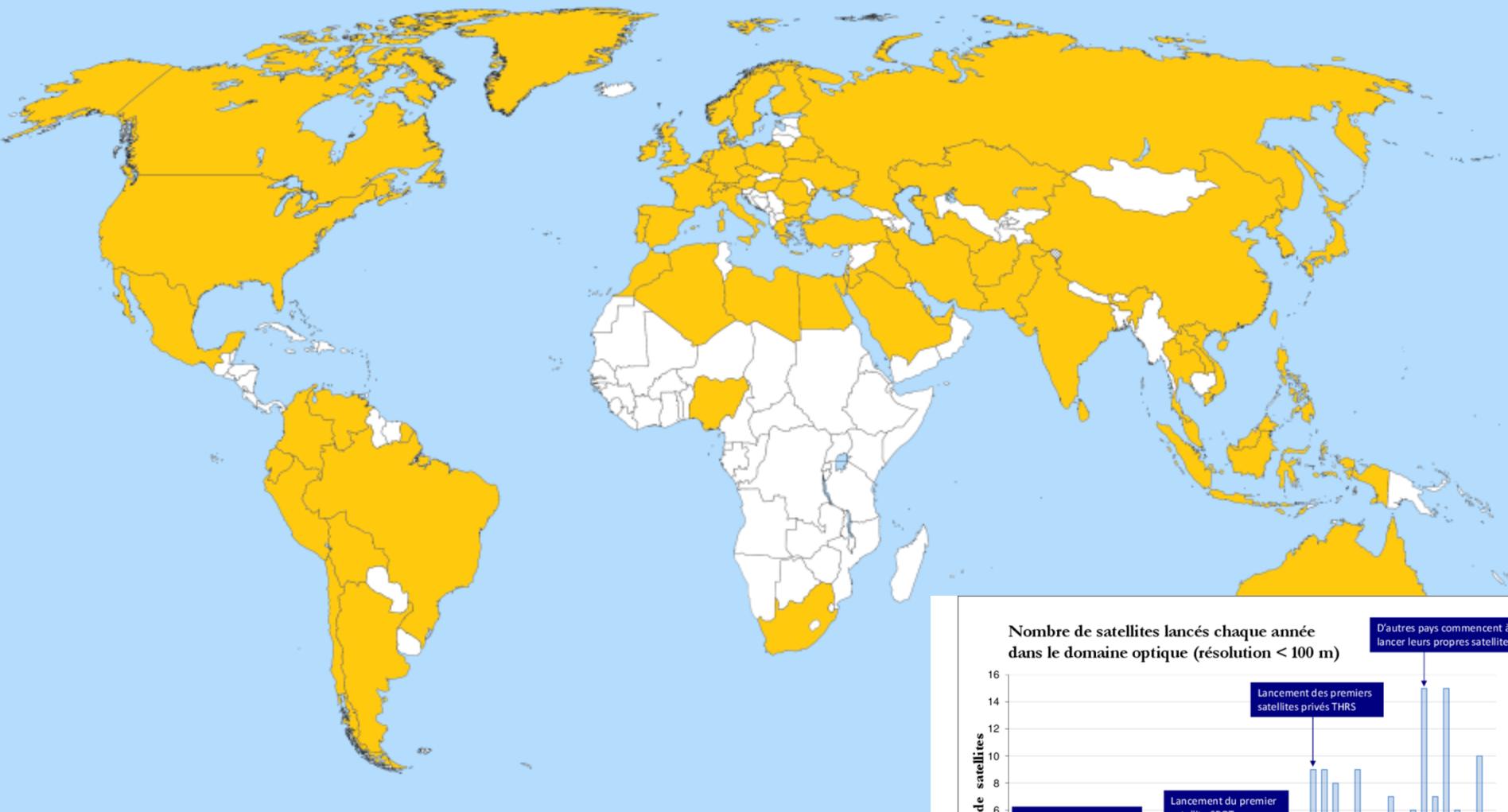
Red Dragon for
Mars Exploration



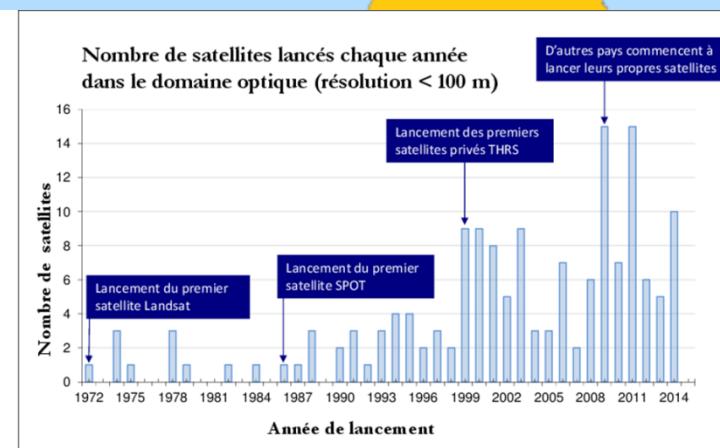
Landing of a Flacon-9
(SpaceX)

“Congress declares that the general welfare of the United States requires that the Administration seek and encourage, to the maximum extent possible, the fullest commercial use of space. » (2010)

The New Space



1966: 4 countries with satellites, today: 70 countries



2018 : le bilan des lancements orbitaux



Overview of the course

- Short history of remote sensing
- Satellites and orbits
- Imaging systems
- Applications





First satellite: 83 kg

1957 : Sputnik 1



Sputnik-2 : 584 kg

1957 : Sputnik 1
1957 : Sputnik 2

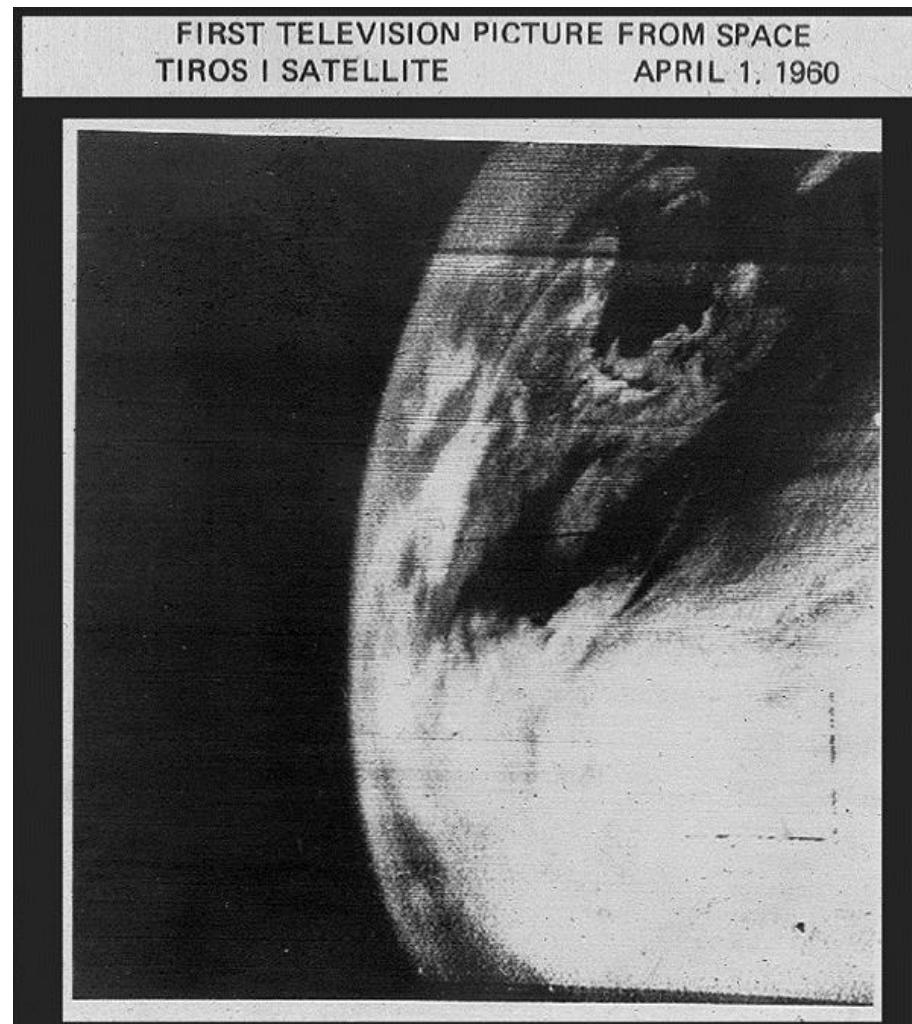


First (civilian) image from the earth (1960)

1957 : Sputnik 1

.....

1960 : Tiros 1



Nimbus (1964): first (civilian) meteorological satellite (sun synchronus)

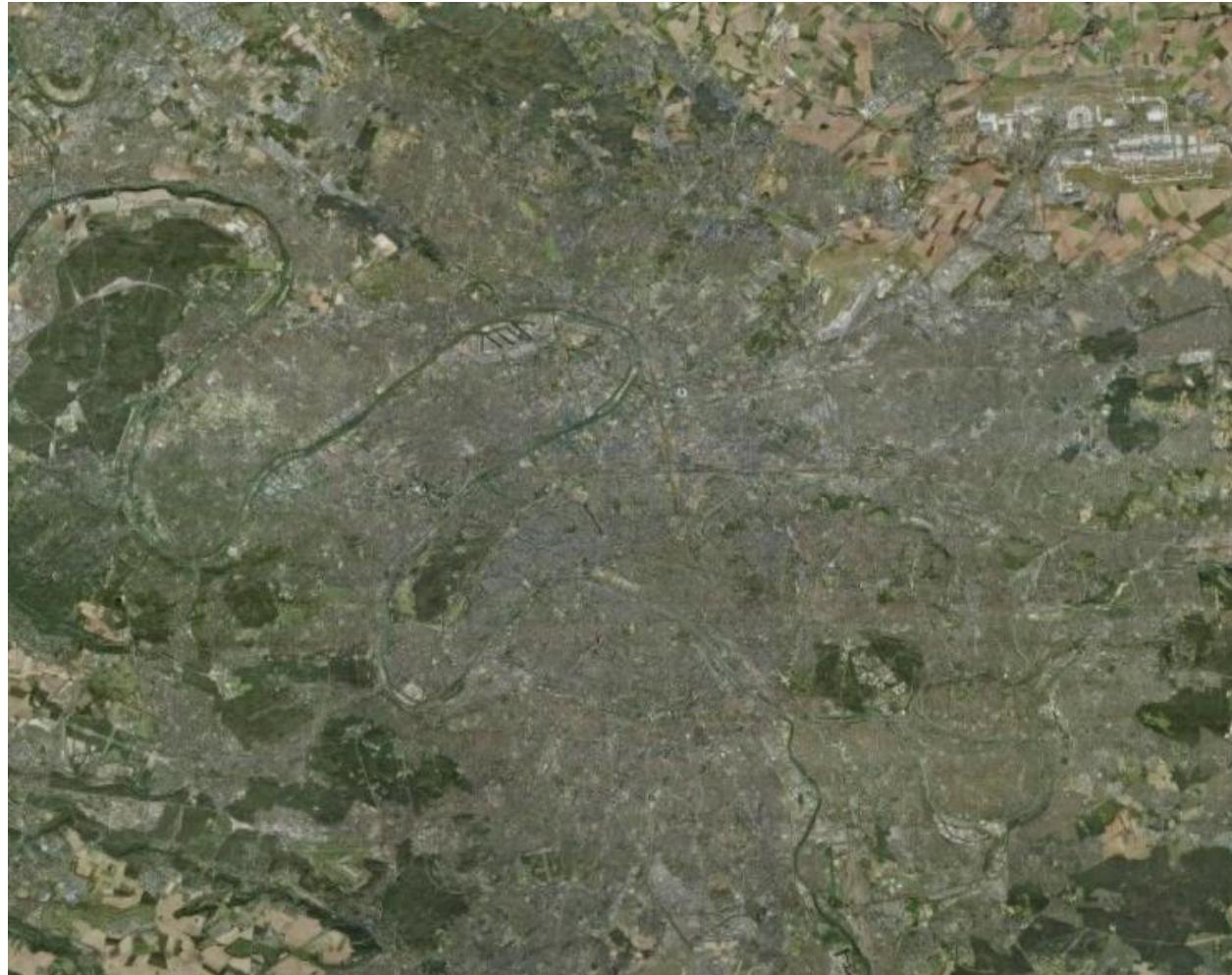
1957 : Sputnik 1

.....
1964 : Nimbus 1



Landsat-1 (1972) : regional images pixel = 30m

1957 : Sputnik 1
.....
1972 : Landsat 1



■ Landsat 8 (2013)

SPOT-1 (1986)

Pixel of 10 m

1957 : Sputnik 1
.....
1972 : Landsat 1
.....
1986 : Spot 1



■ SPOT-7 (2014), pixel of 1,5m

Quickbird-2 (2001) pixel = 61 cm

1957 : Sputnik 1

.....
1972 : Landsat 1

.....
1986 : Spot 1

.....
2001 : Quickbird 2

Metric images



TerraSAR-X (2007) : radar imaging Metric pixel, lateral viewing

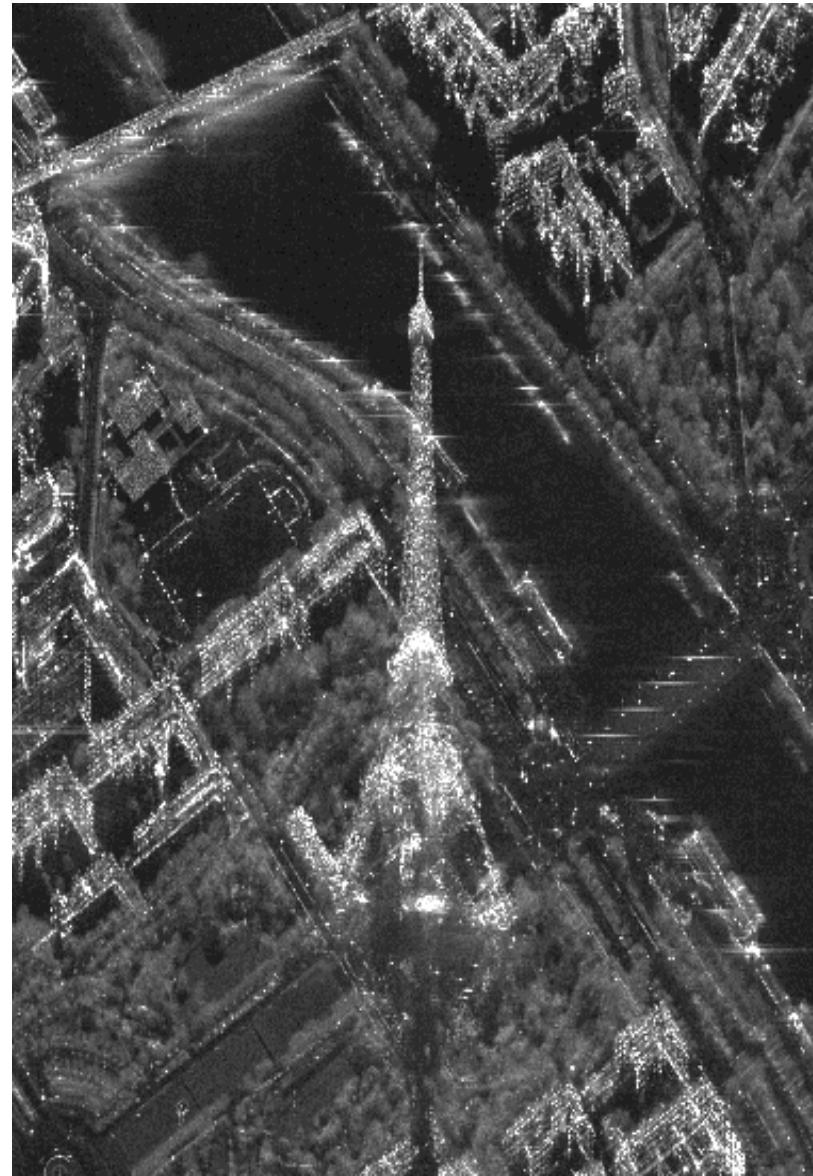
1957 : Sputnik 1

.....
1972 : Landsat 1

.....
1986 : Spot 1

.....
2001 : Quickbird 2

.....
2007 : Terrasar-X



RapidEye constellation (2008)

5 satellites (pixel ~ 6m)

1957 : Sputnik 1

.....
1972 : Landsat 1

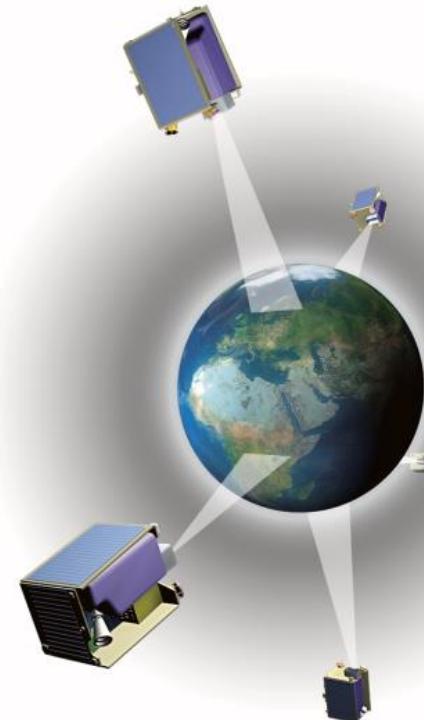
.....
1986 : Spot 1

.....
2001 : Quickbird 2

.....
2008 : Rapid Eye

Constellations

- Daily visit of any point on earth



Constellation Orfeo-Pleiades

4 radar sensors (CSK), 2 (+2) optic sensors

1957 : Sputnik 1

.....
1972 : Landsat 1

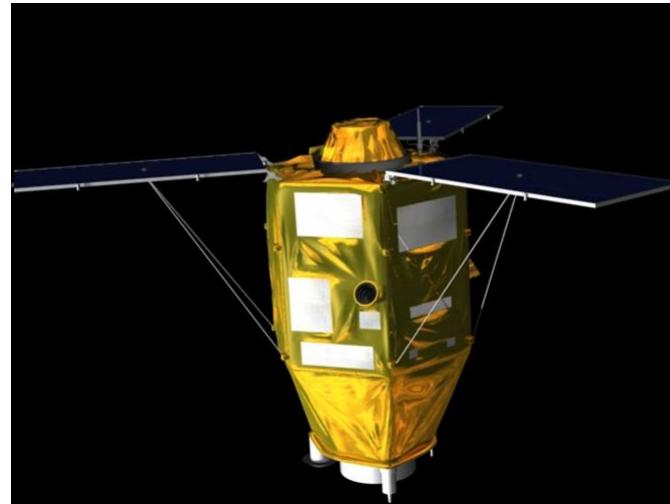
.....
1986 : Spot 1

.....
2001 : Quickbird 2

.....
2007 : Terrasar-X

.....
2012 : Orfeo Pleiades

- Daily image anywhere on earth
- Metric resolution



2017: hyperconstellations

Planet (> 300 microsatellites, 5 kg)

1957 : Sputnik 1

.....
1972 : Landsat 1

.....
1986 : Spot 1

.....
2001 : Quickbird 2

.....
2007 : Terrasar-X

.....
2012 : Orfeo Pleiades





Space actors

■ From space agencies....:

- Cost of space missions (1 launched satellite = 100-200 ME)
- Earth observation theamics :
 - Public issues (meteo, climate, earth survey, disasters management, ...)
 - Defense

■ To private industries:

- American strategy (supporting US industry in space developement)
- New challenges: spatial tourism, planet exploration and exploitation, ...
- New markets: activity monitoring, agriculture, ...



Space actors and data policy

■ Data from space agencies:

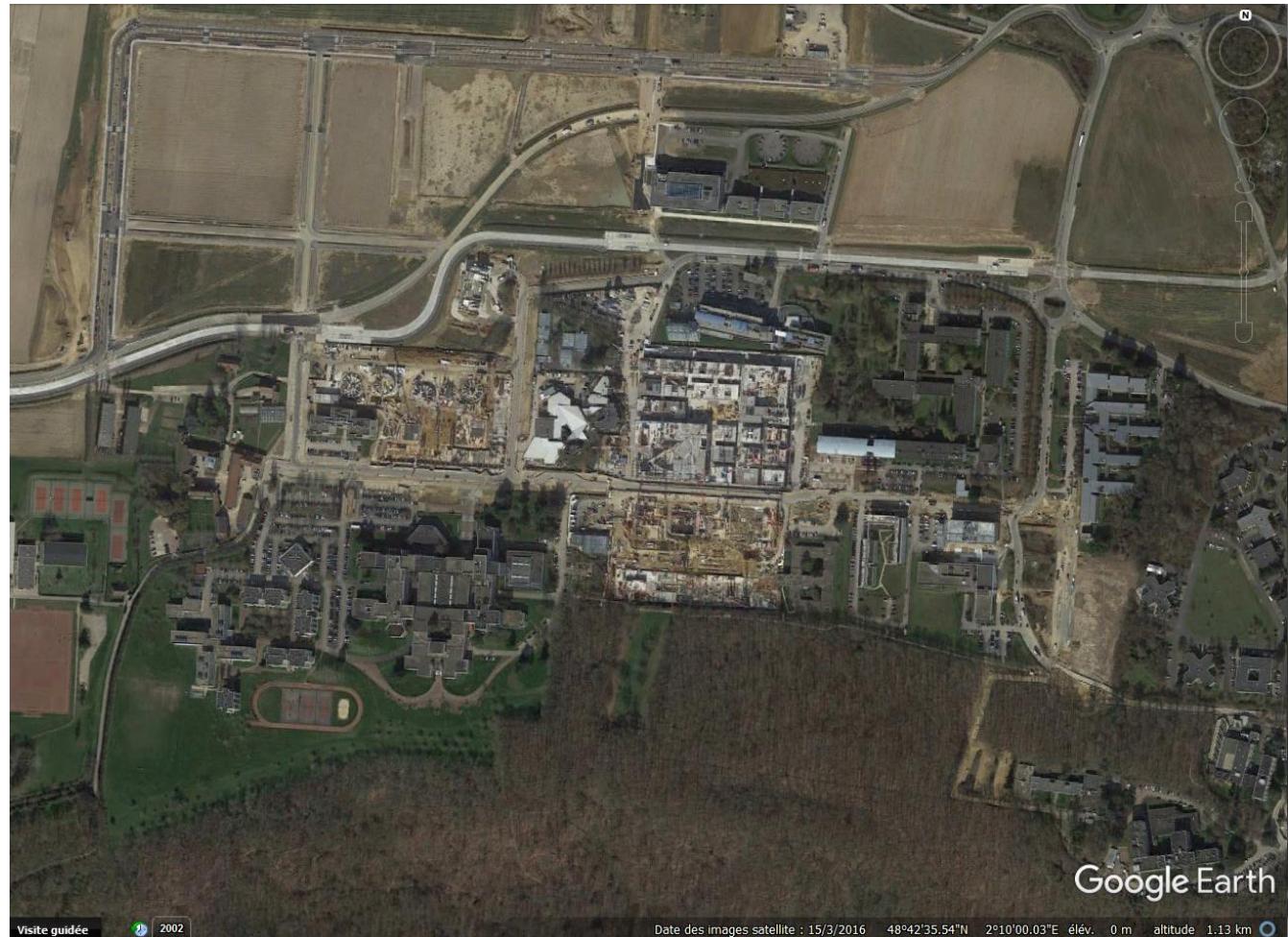
- Free for scientific programs
- Fully available and free for Copernicus program of ESA

■ To private industries:

- Paying data
 - CSK radar (1m) : 100 km² pour 6000 Euros
 - DigitalGlobe 50 cm : ~50 Euros par km²
 - RapidEye : 1 Euros par km²
- Public access for some study areas

Google Earth (2005-....)

- Widely used
- Metric images
(from different sensors)
- Google earth Engine



Geoportail of IGN (2006-....)

Professionnal and public software

Images + maps





Overview of the course

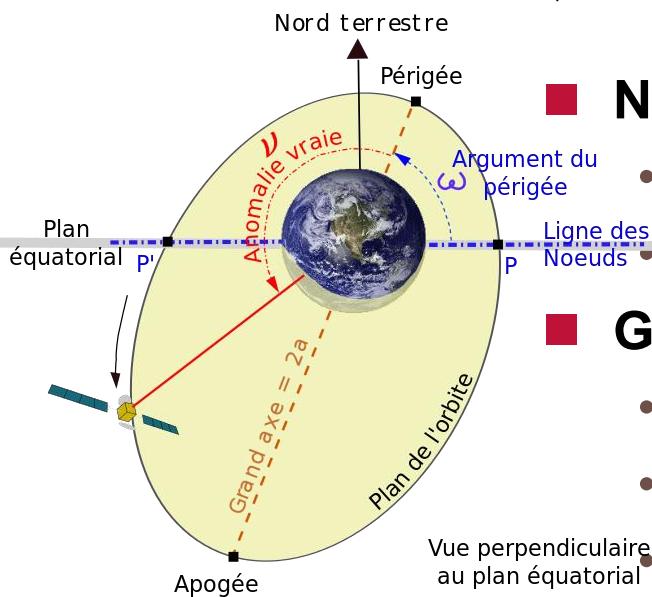
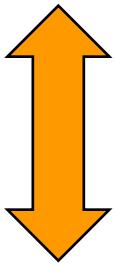
- Short history of remote sensing
- Satellites and orbits
- Imaging systems
- Applications



Basics of Kepler mechanics

■ Kepler :

- Orbits of planets are ellipses (with the sun as one of the two foci)
- A line segment joining a planet and the Sun sweeps out equal areas during equal intervals



■ Newton :

- Potential
- Force in $1/r^2$

■ Gravitational constant:

- $G=6,672 \times 10^{-11}$
 - $M_T = 5,597 \times 10^{24} \text{ kg}$
- $$\mu = GM_T = 3,986 \times 10^{14}$$

$$U = -\frac{\mu m}{r}$$

$$\vec{F} = -\frac{\mu m}{r^2} \frac{\vec{r}}{r}$$

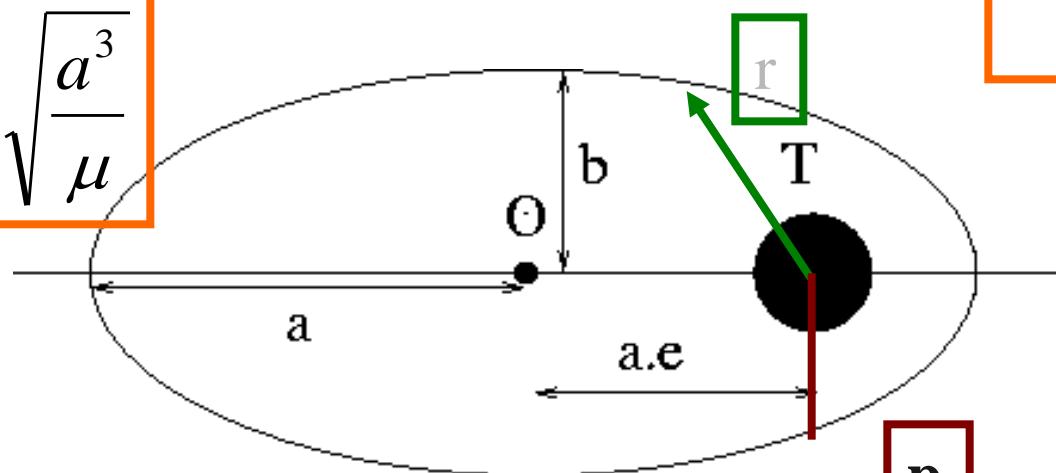
@wikipedia

Punctual and homogeneous earth :

$$U = -\frac{\mu m}{r}$$

- Elliptic trajectories for satellites
- Earth is in the orbital plane and one of the foci
- Ellipse parameters:

- Semimajor axis: a
- Semiminor axis: b
- Eccentricity: e



$$T = 2\pi \sqrt{\frac{a^3}{\mu}}$$

$$r = \frac{p}{1 + e \cos(\theta - \theta_0)}$$

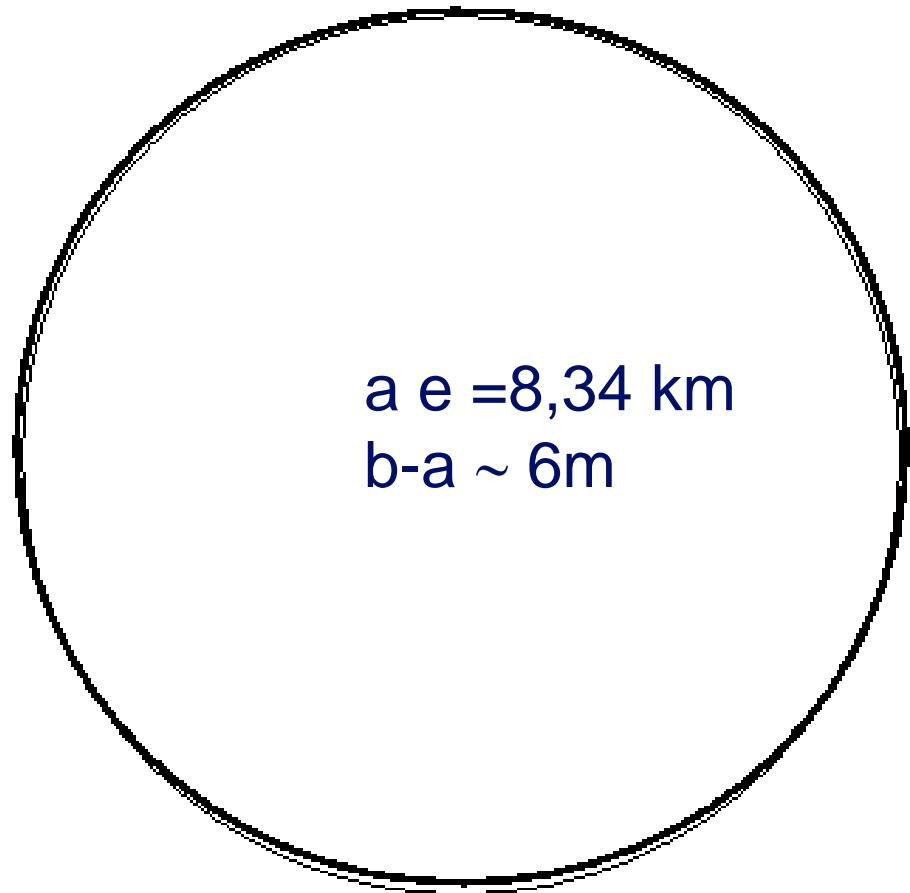
$$e^2 = 1 - \left(\frac{b}{a}\right)^2$$

p

$$p = a(1 - e^2)$$

Orbites of remote sensing satellites

- Almost circles
- Earth not exactly in the center:
 - Small eccentricity
 - Error of around 8 km
 - Shape of a circle
- Satellite speed varies along the trajectory:
 - Faster for low altitude
 - Slower for high altitude



Example of ERS : $e=0.001165$

Examples

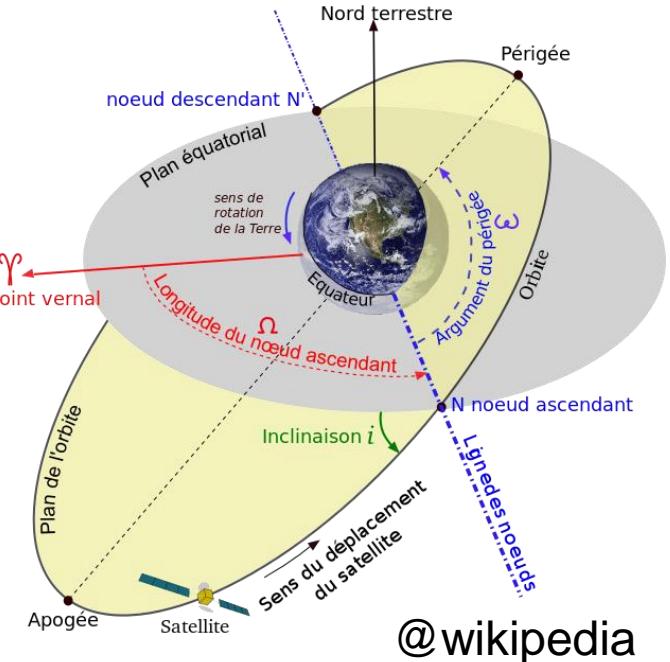
$$T = 2\pi \sqrt{\frac{a^3}{\mu}}$$

	Period	Altitude	Orbit/day
FORMOSAT	102,8'	891 km	14
SPOT	101,4'	832 km	14+5/26
RADARSAT	100,6'	798 km	14+7/24
ERS	100'	785 km	14+11/35
Landsat 7	98,5'	705 km	14+9/16
Ikonos	98'	681 km	
Terrasar-X	95'	515 km	15+2/11
Quickbird	93,5'	450 km	

Earth gravitational field Analysis of Sputnik 2 orbit

- Earth flattening $\approx 1/298$
- Coefficient J_2 in the terrestrial field

$$U = -\frac{\mu m}{r} \left(1 + J_2 \left(\frac{R_T}{r} \right)^2 P(\varphi) \right)$$

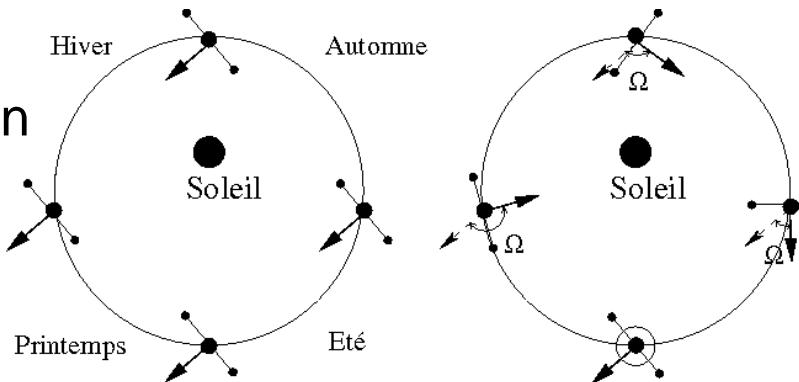


@wikipedia

■ Sun-synchronous trajectories :

- Choice of an inclination i such that the rotation of the orbit plane is 360° in one year
(one altitude \rightarrow one inclination)

For altitudes in [400,800]km,
inclinations in [97°,99°]



Sun-synchronous orbits

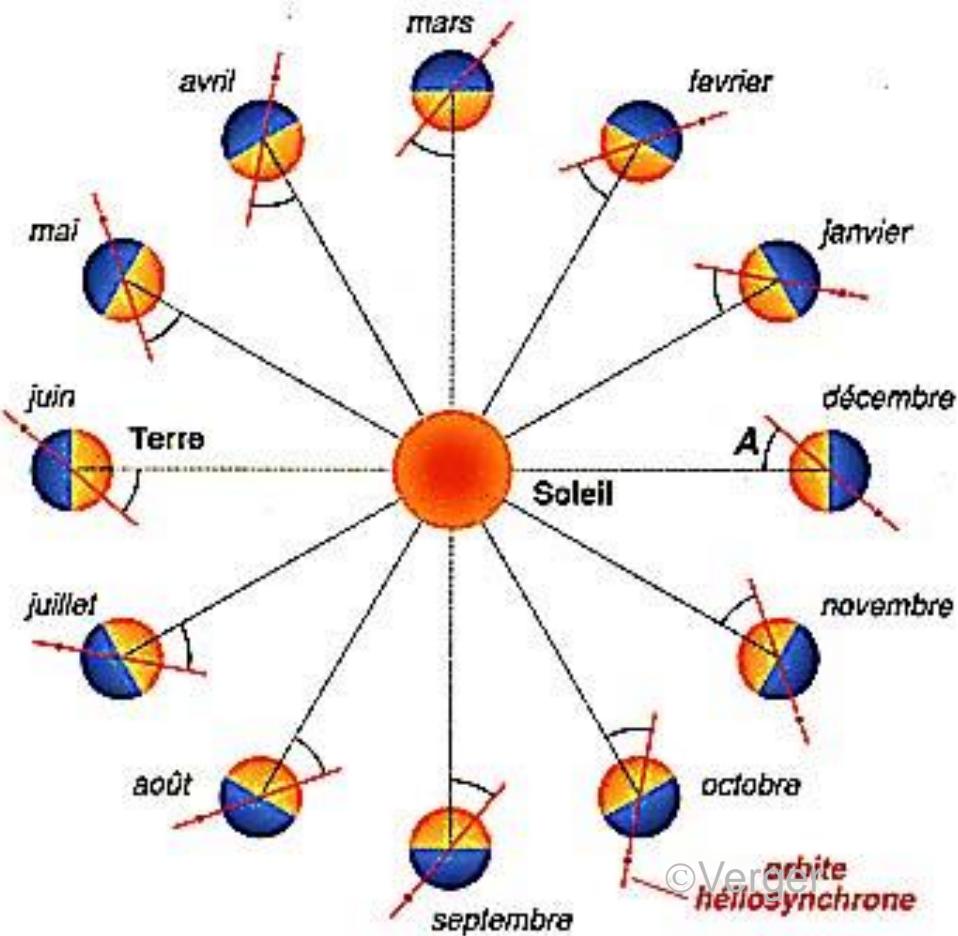
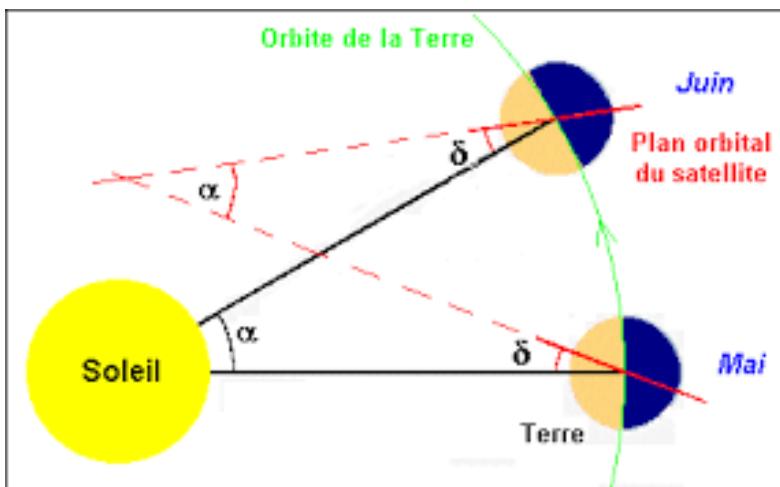
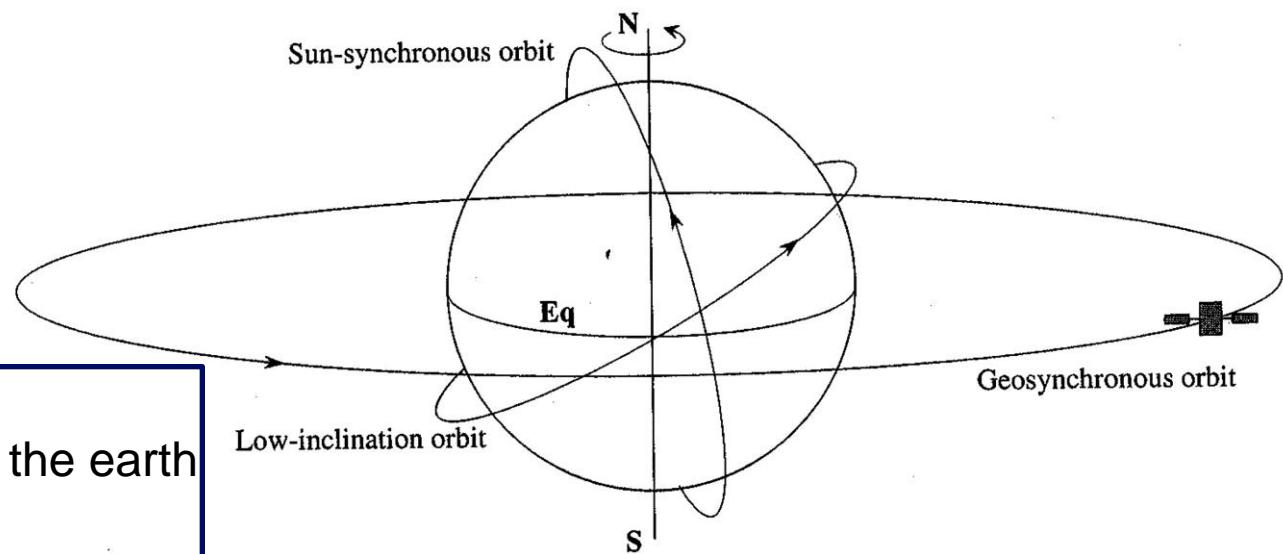
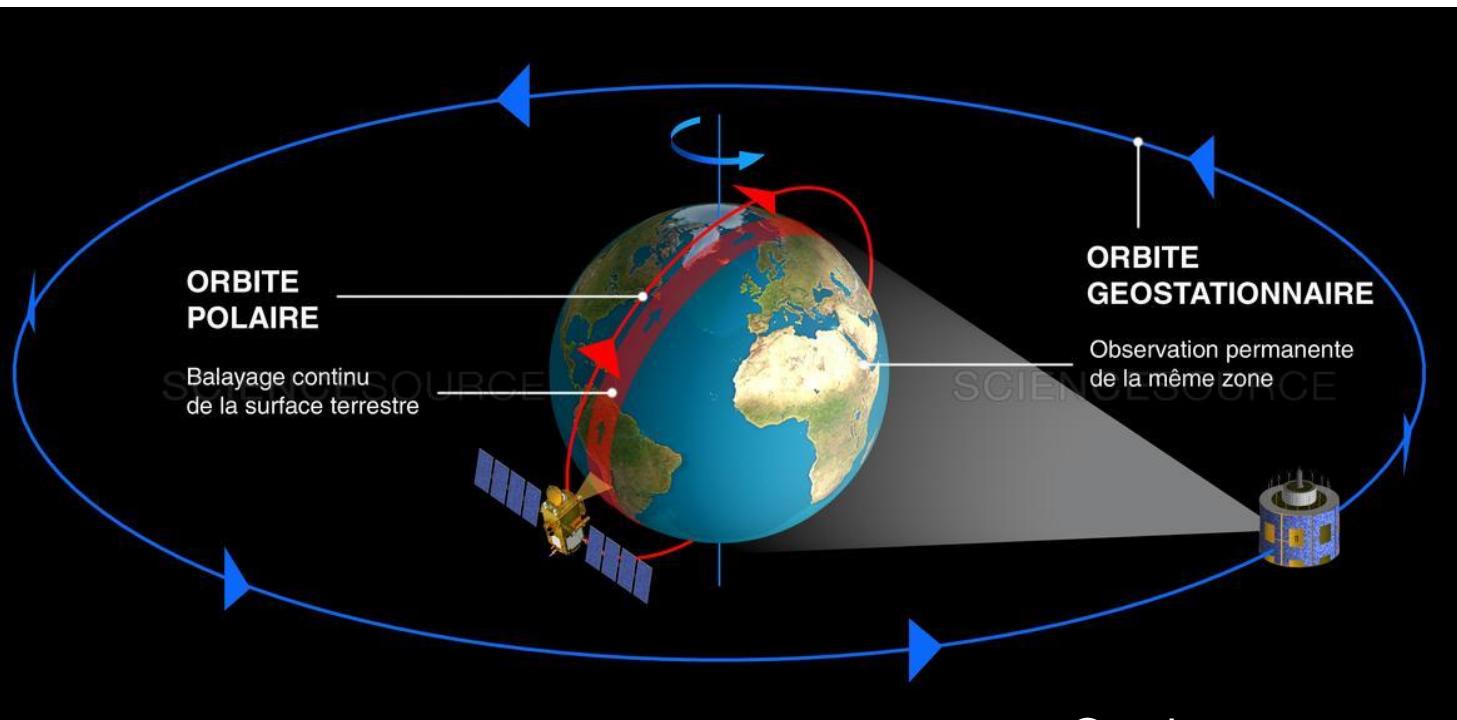


Fig. 28 - Principe de l'héliosynchronisme. L'angle A formé par le plan de l'orbite et la direction Terre - Soleil demeure constant au cours de l'année.



Sun-synchronous orbit:
Illumination of a point on the earth
at the same local time

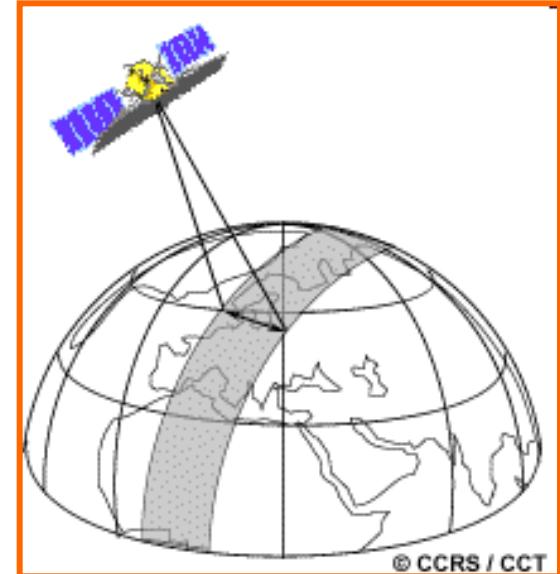


© science source

Choice of orbits for satellites

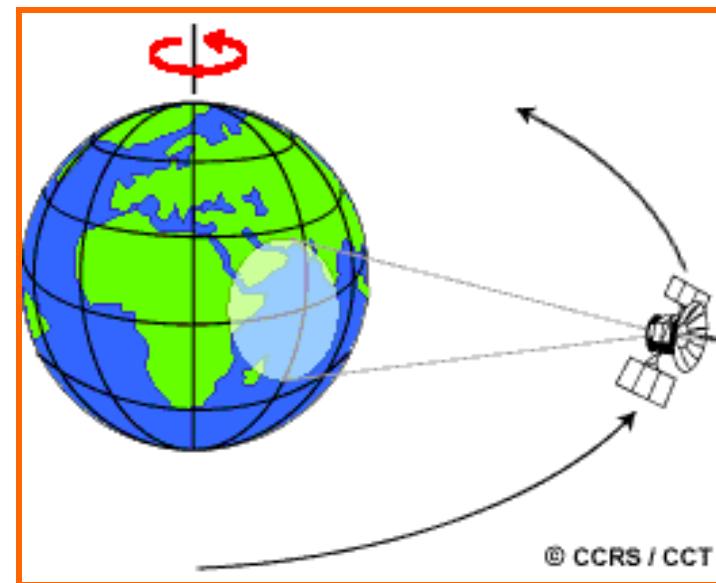
■ Low orbits (500 km – 1000 km)

- LEO (Low Earth orbit)
- Sun synchronous (near polar orbit - for stability of acquisition conditions)
- Altitude chosen for a given cycle (period depends on altitude, cycle depends on period)
- For altitude < 400 km, fast destruction due to rubbings



■ Geostationary orbits

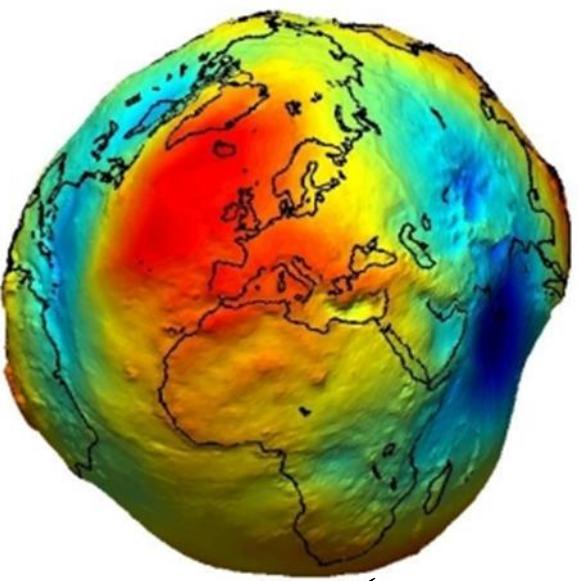
- High geostationary orbit (altitude 35 683km)
- Orbital plane in equatorial plane: motionless satellite from earth
- Visibility of a fixed area of the earth (42%)



Improving earth shape: DORIS experiments (1990)

- Emission on earth of known signals (2036.25 MHz et 401.25 MHz)
- Doppler shift analysis on board
 - Determination of the satellite speed (0,06 mm/s)
 - Knowledge of TCA (Time of Closest Approach)
- Recomputation of orbital trajectories:
 - Accuracy of the satellite position:
 - 10 cm after 3 heures
 - 4 cm after 3 jours
 - 2,5 cm after 30 jours
 - Aim: < 1 cm





Improving earth shape 2017...

$$U = -\frac{\mu}{r} \left[1 + \sum_{n=2}^{\infty} \left(\frac{R_T}{r} \right)^n J_n P_n(\cos \phi) + \sum_{n=2}^{\infty} \sum_{q=1}^{\infty} \left(\frac{R_T}{r} \right)^n J_{n,q} P_{n,q}(\cos \phi) \cos(q(\lambda - \lambda_0)) \right]$$

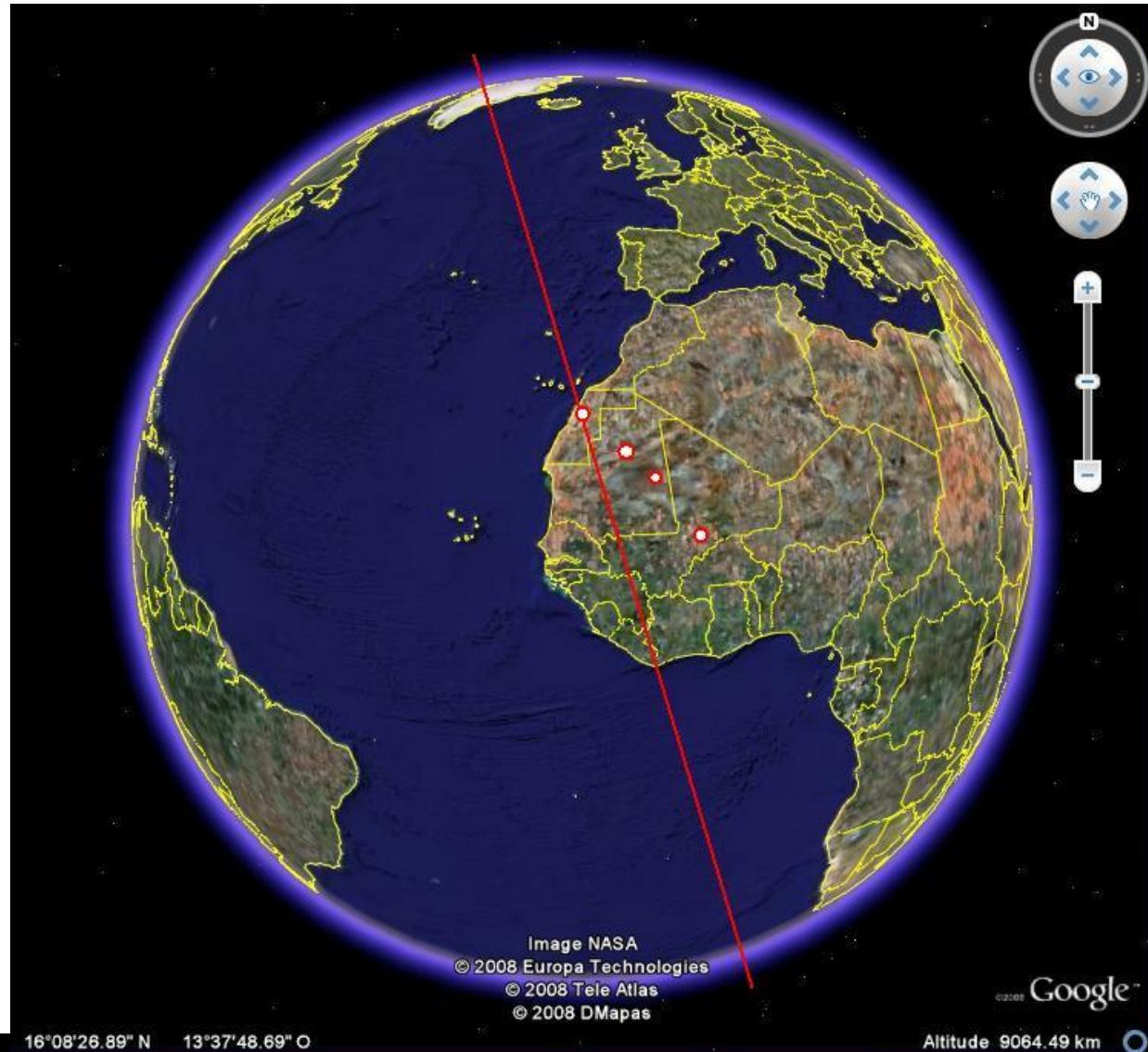
- 2017 : 5×10^6 coefficients (available on the WEB)
- Excellent positionnement des satellites (GPS+centrales inertielles)

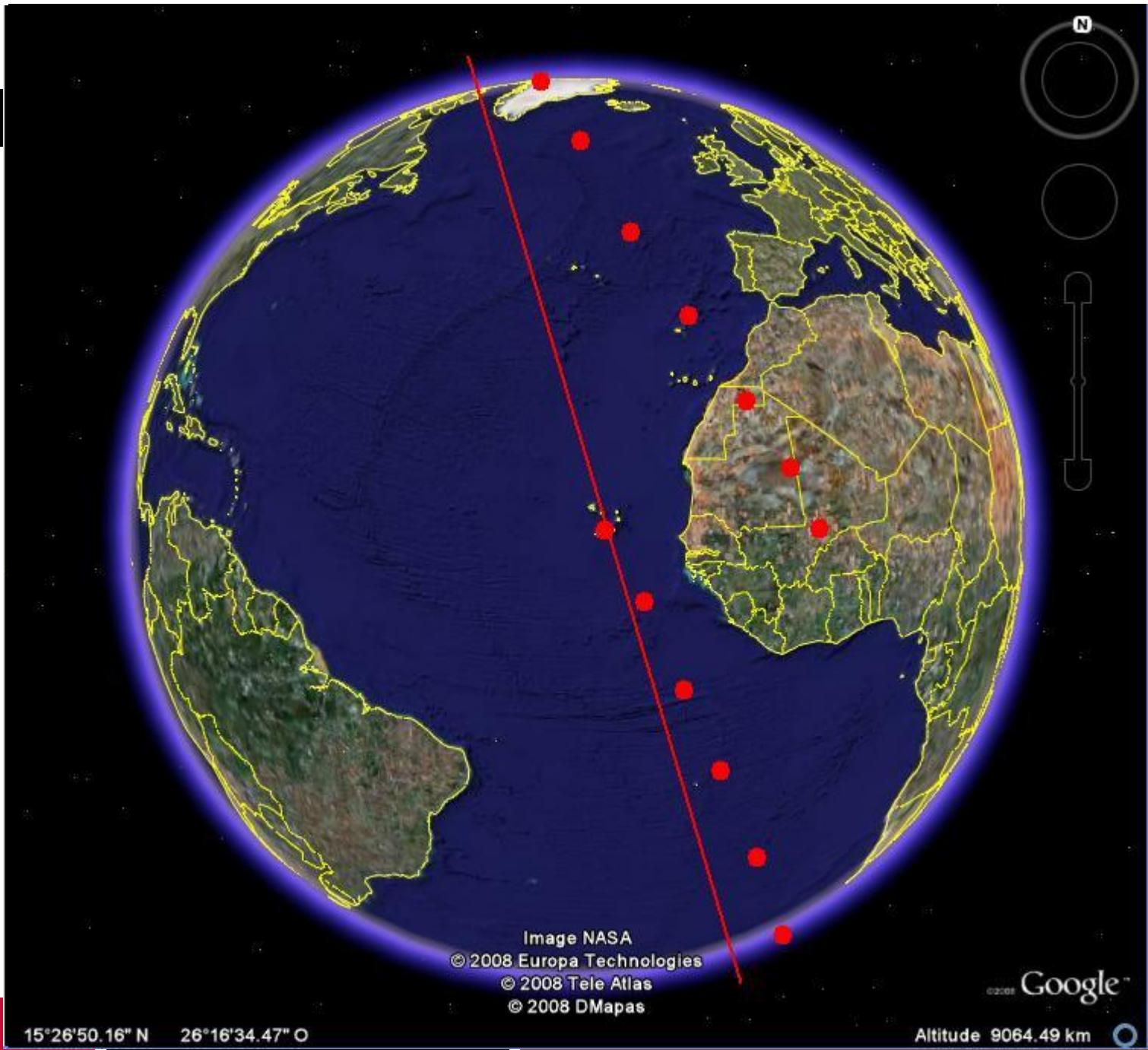
Orbit plane, earth without rotation



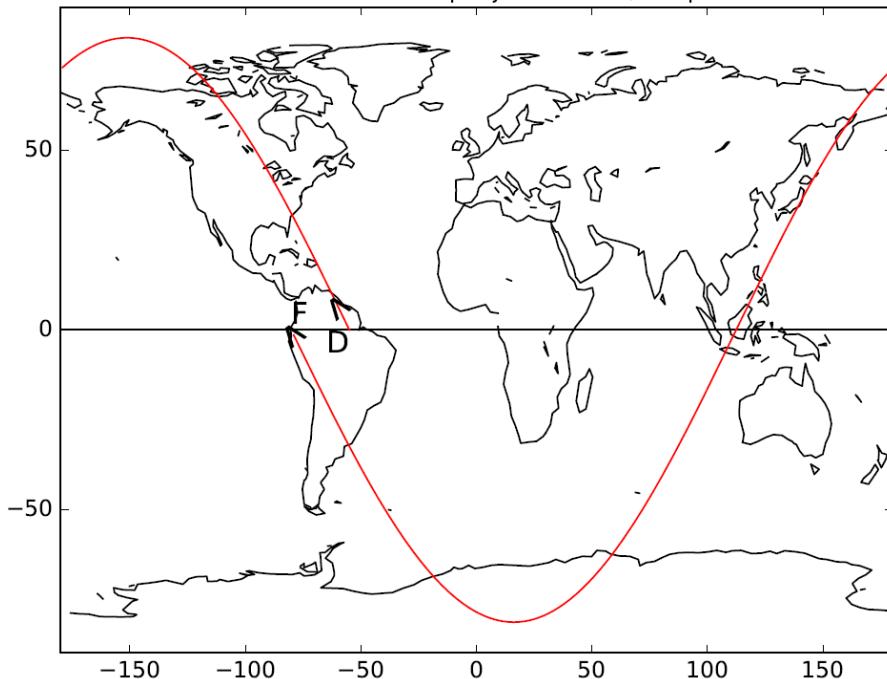
15°47'16.72" N 6°48'27.87" O

A satellite and a rotating earth



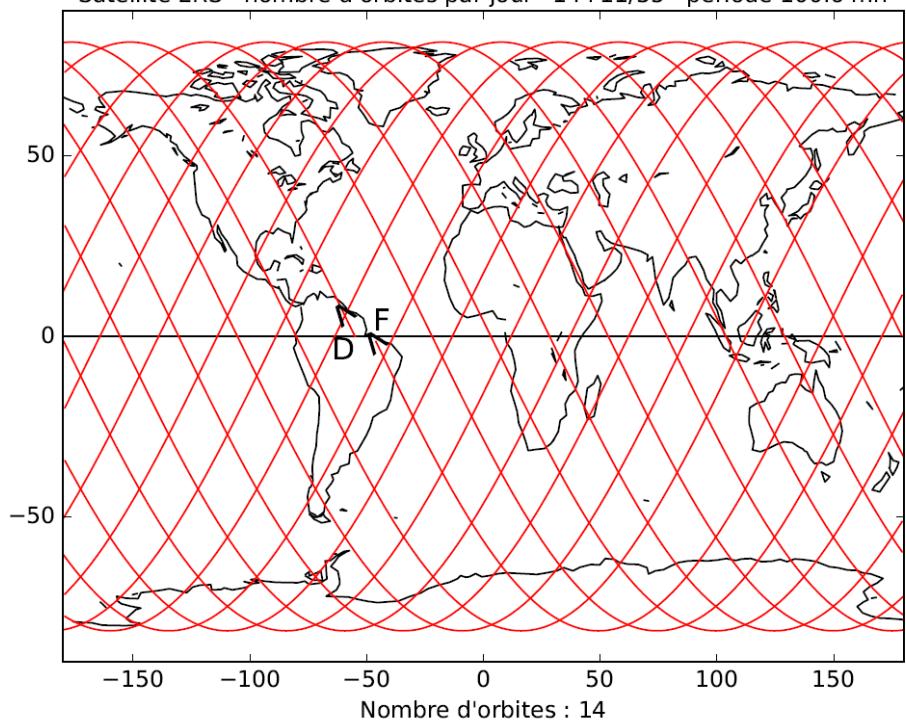


Satellite ERS nombre d'orbites par jour=14+11/35 période 101 mn

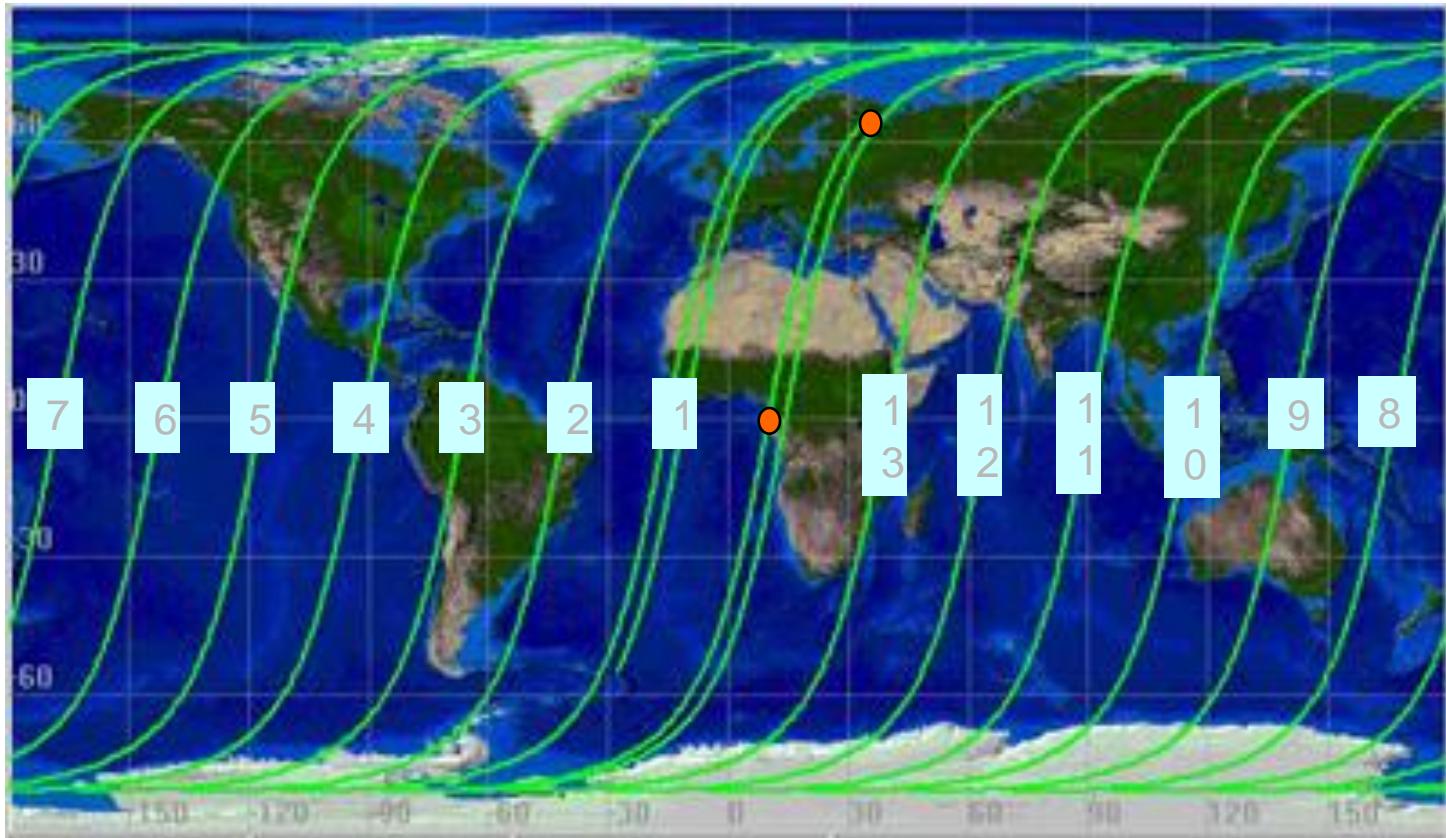


One orbit
One day of orbits

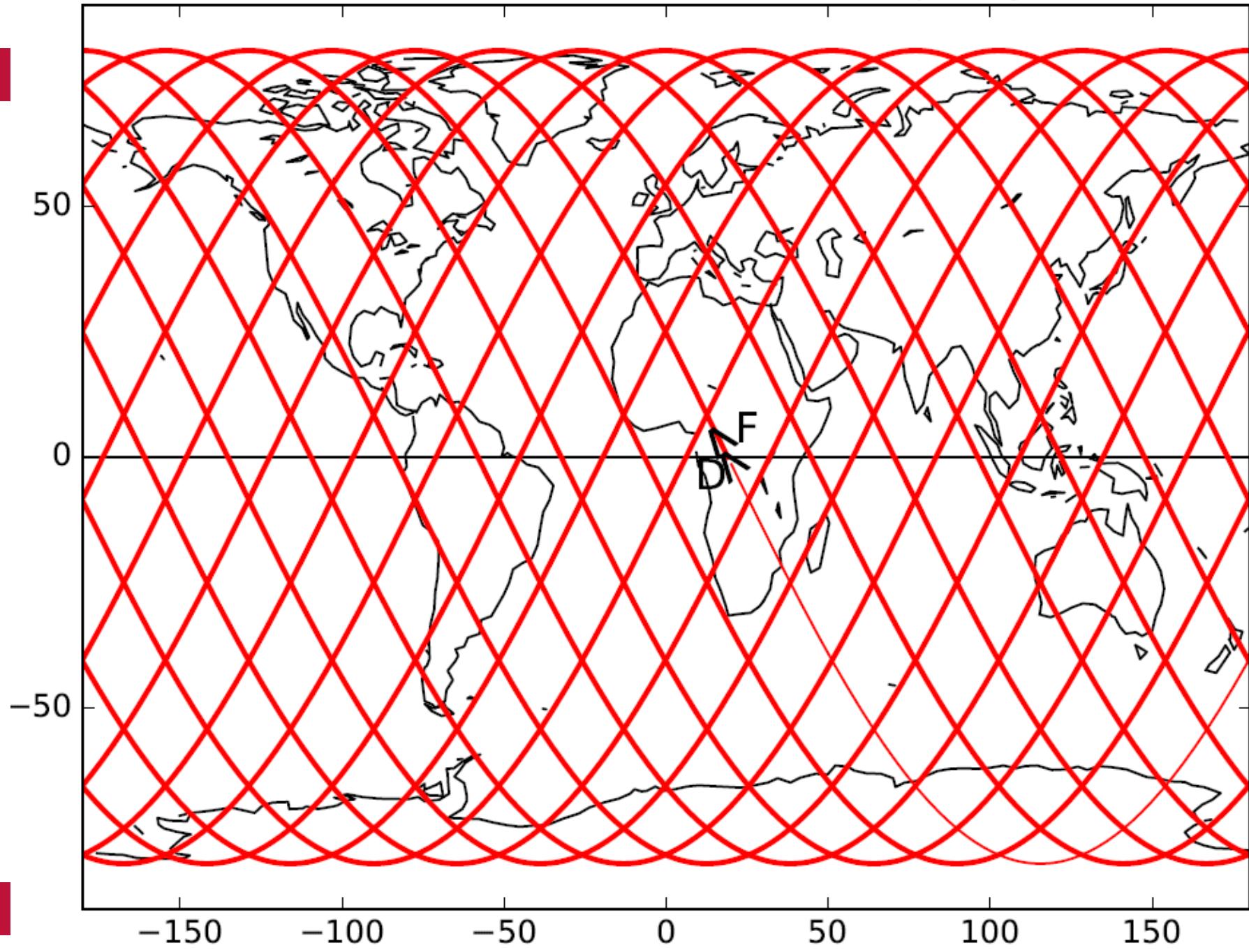
Satellite ERS nombre d'orbites par jour=14+11/35 période 100.6 mn



ERS : descending tracks

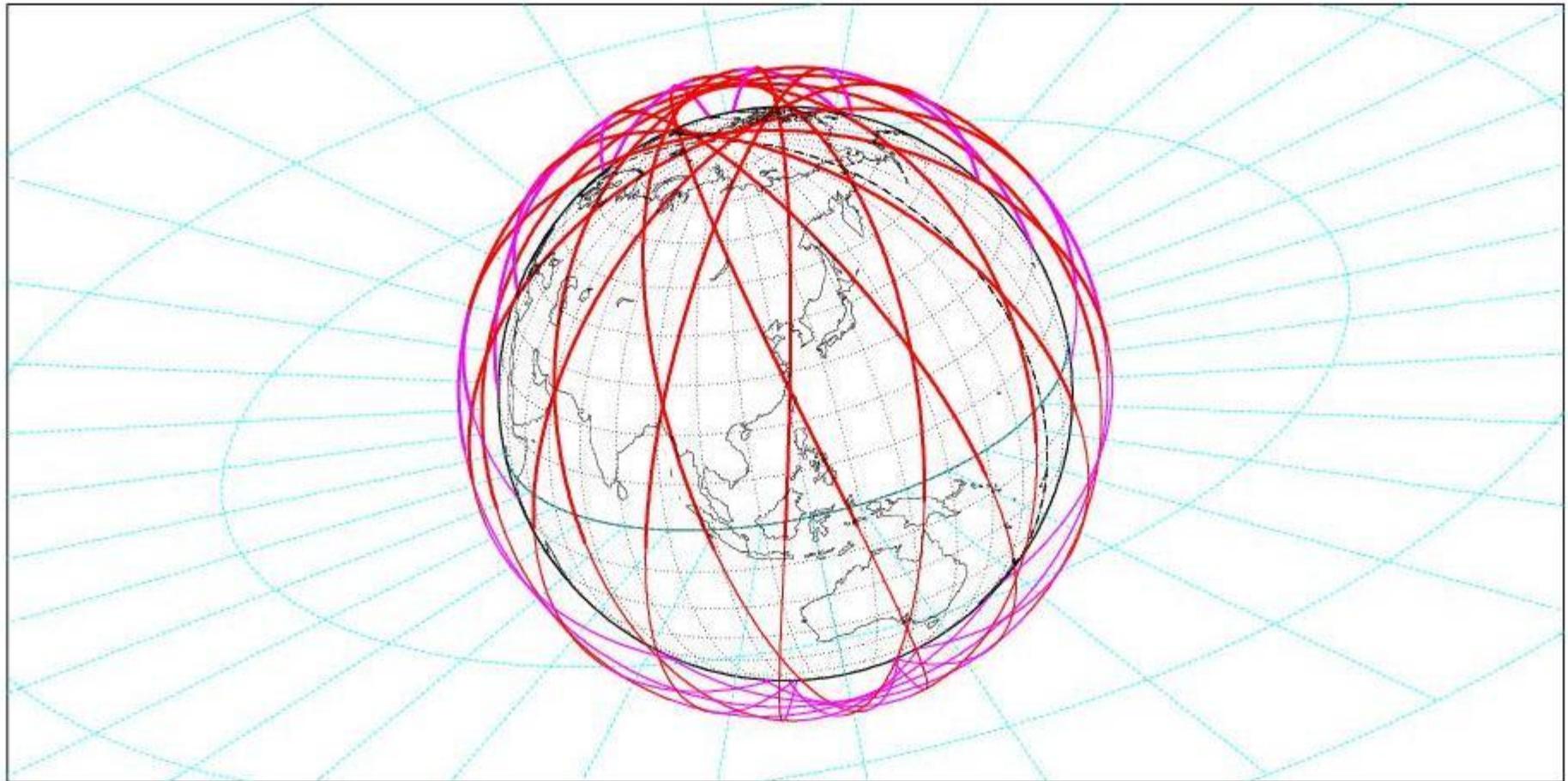


Satellite FORMOSAT nombre d'orbites par cycle=14





1 day with Formosat : 14 orbits per day



Examples of cycles

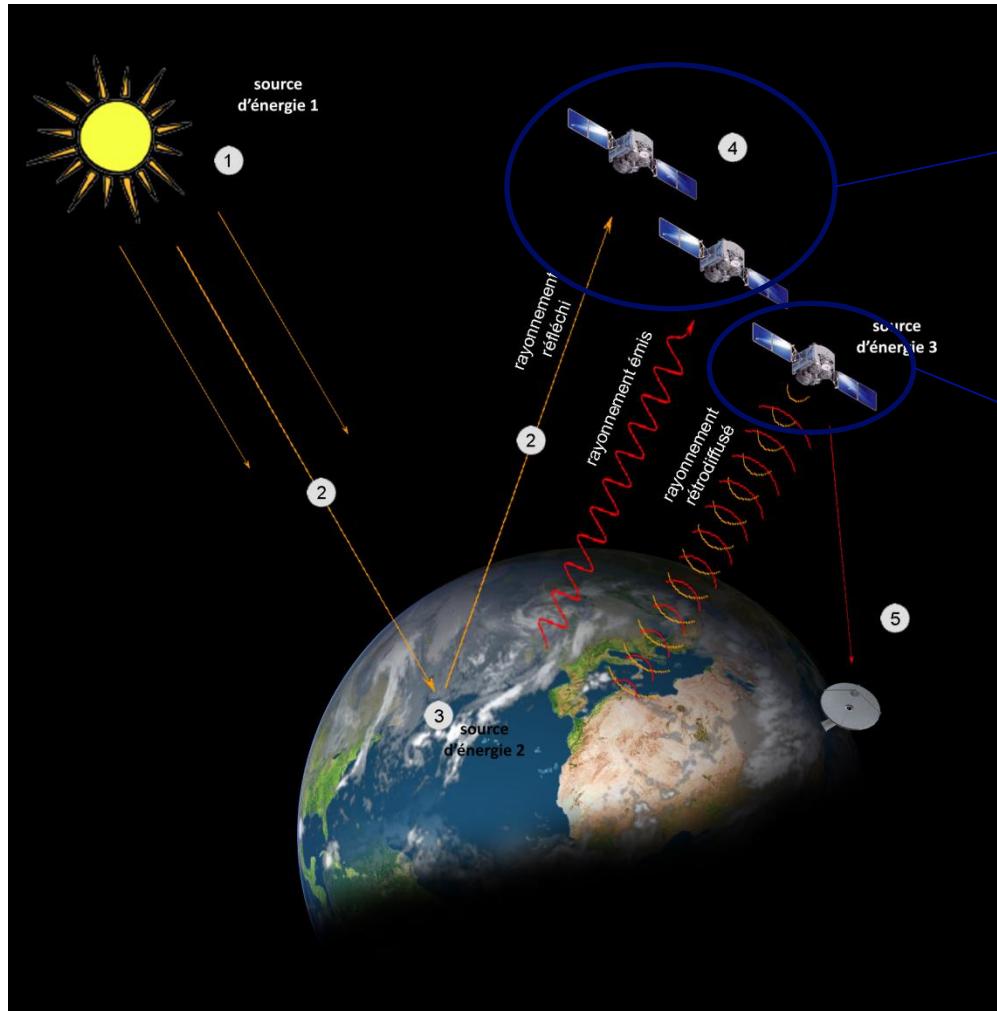
1 day	FORMOSAT	14
10 days	Sentinel-2	14+3/10
11 days	Terrasar-X	15+2/11
16 days	LANDSAT 7, Terra	14+9/16
24 days	RADARSAT	14+7/24
26 days	SPOT	14+5/26
35 days	ERS	14+11/35
46 days	ALOS	

Overview of the course

- Short history of remote sensing
- Satellites and orbits
- Imaging systems
- Applications



Physics of electromagnetic radiations



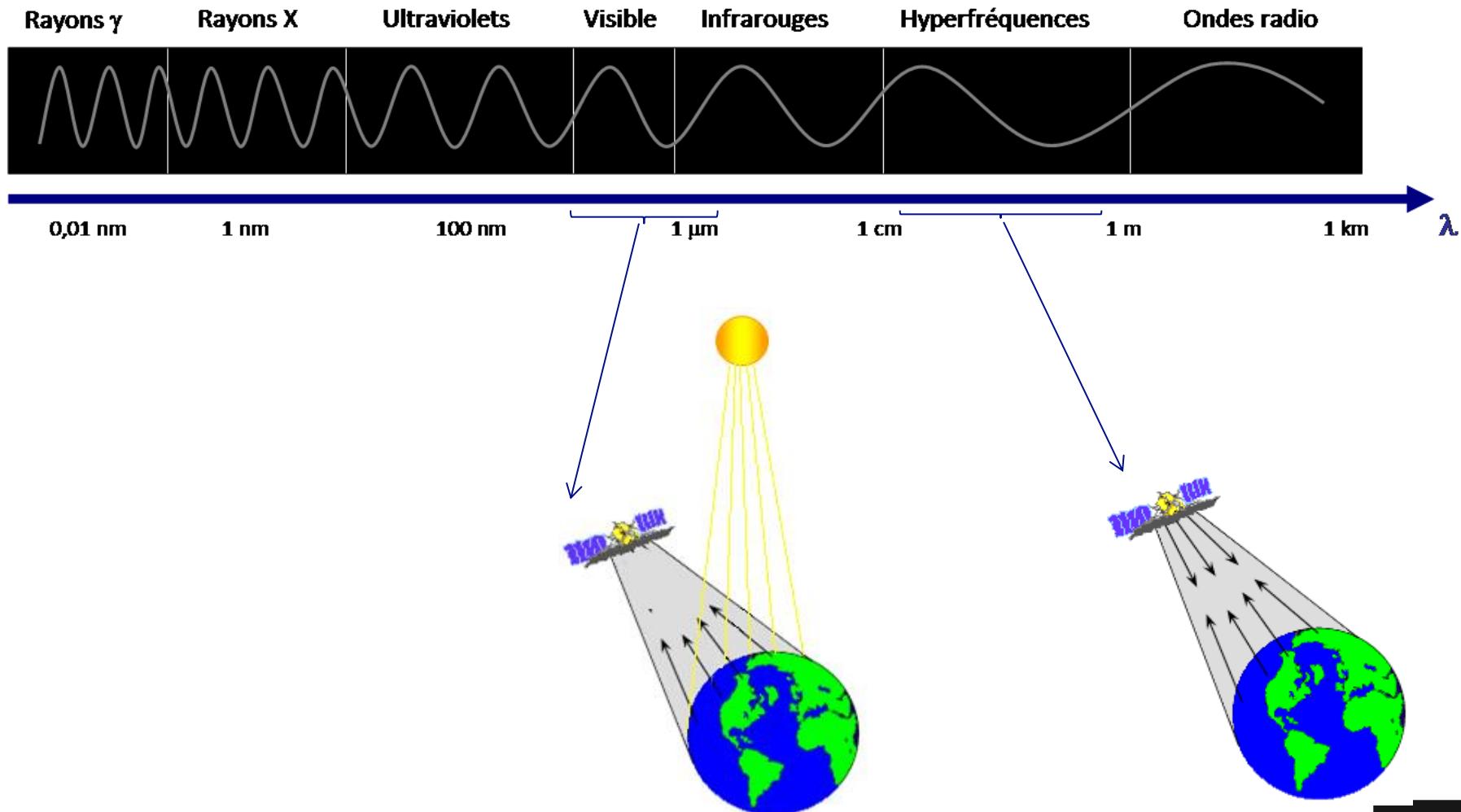
Passive sensors

- Optic domain
- Infra red

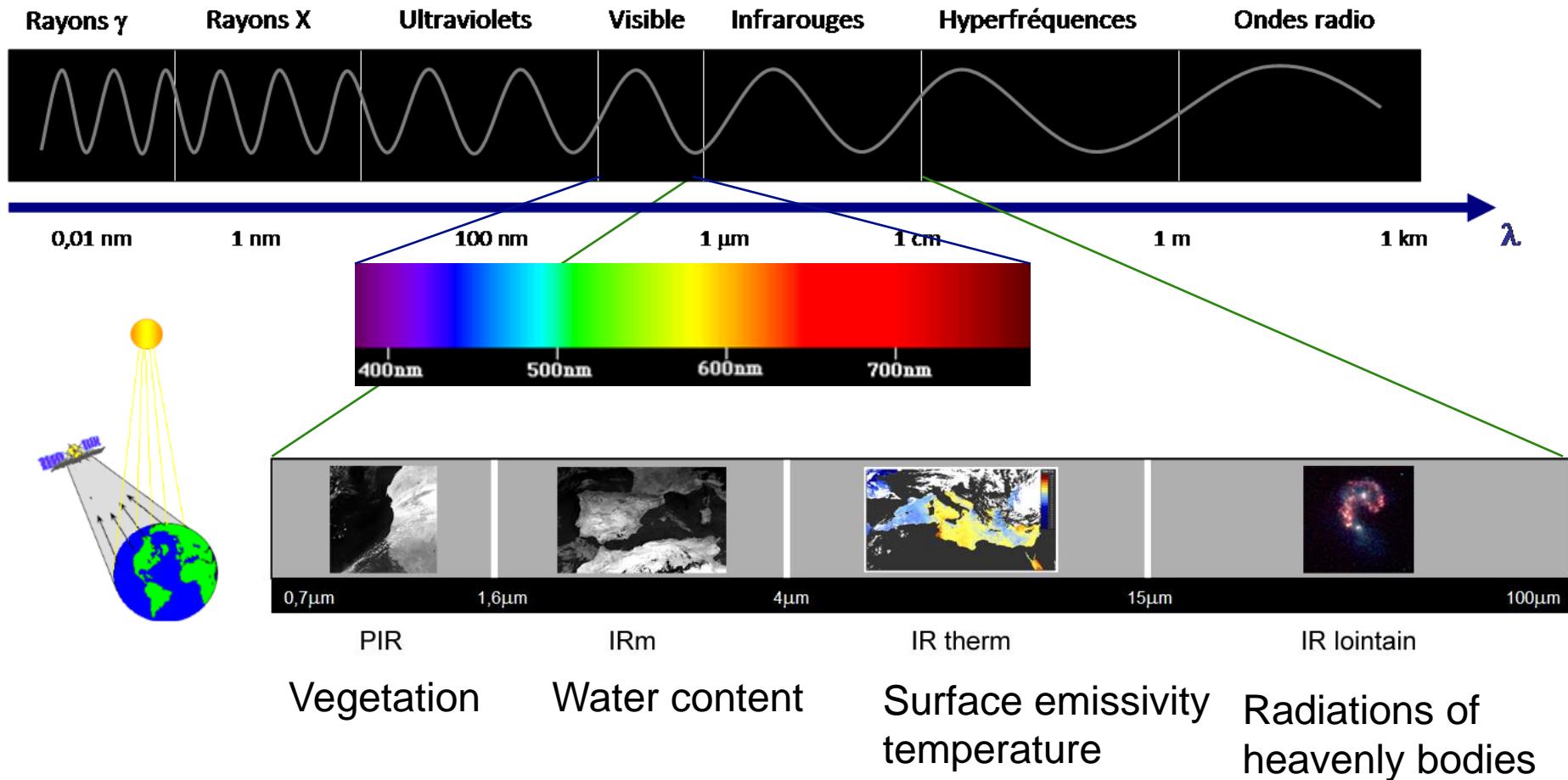
Active sensors

- radar
- lidar

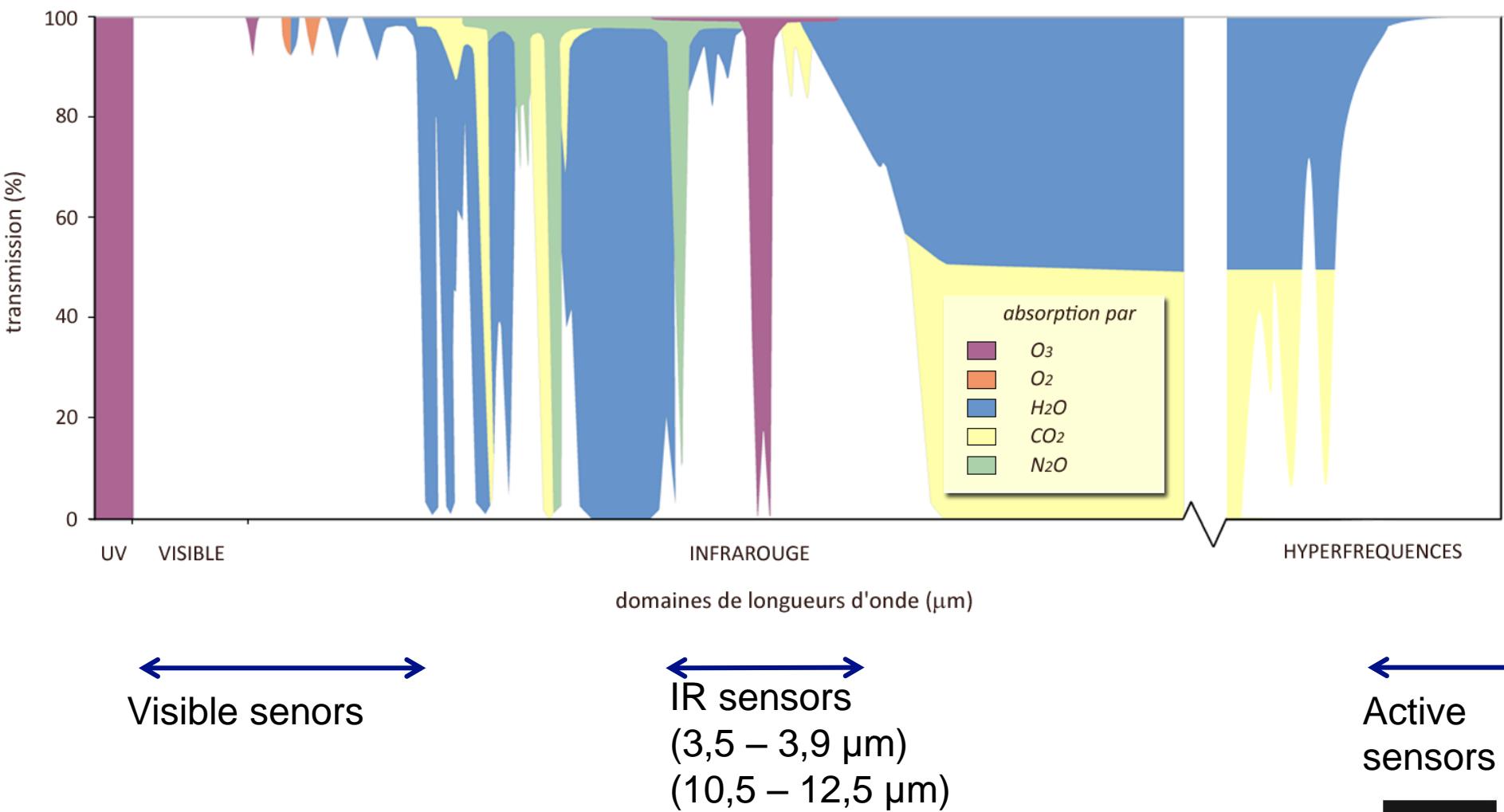
Physics of electromagnetic radiations



Physics of electromagnetic radiations



Atmospheric windows

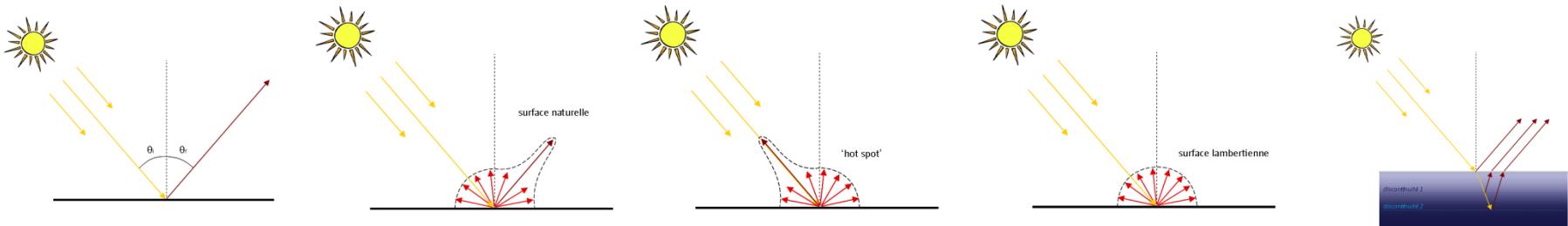


Electro-magnetic radiations and matter

■ Interaction

- Absorption / reflexion / transmission

■ Reflexion



■ Absorption

- Atmosphere, natural surfaces

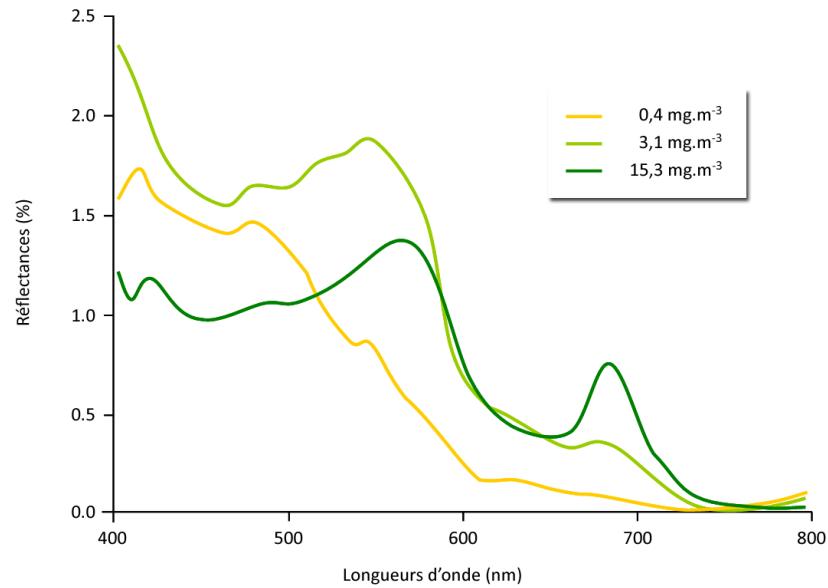
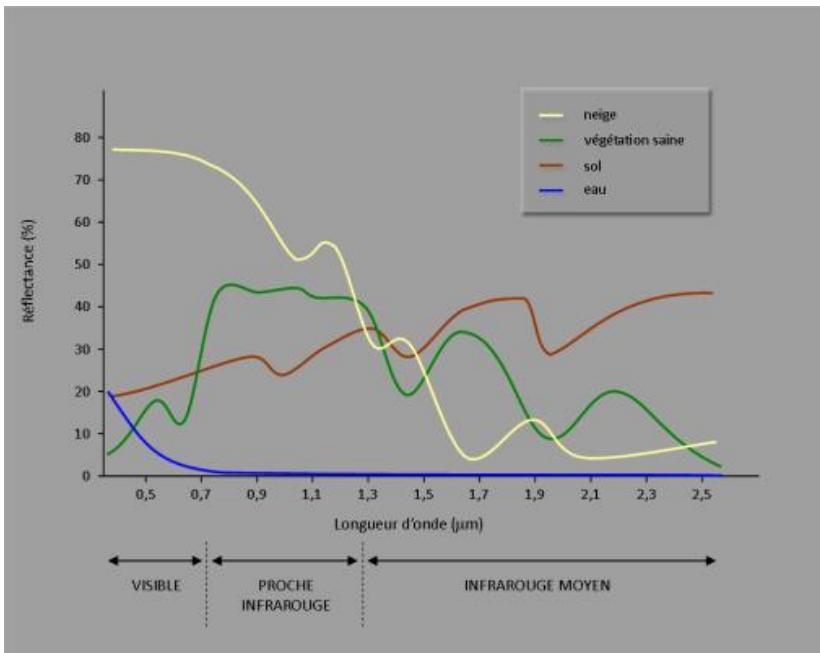
■ Transmission

- Transparent media for some wavelengths

■ Measurements: luminance, radiance

- Radiometric calibration: sensor measurement to physical quantity (from DN to radiance)

Spectral signatures of media

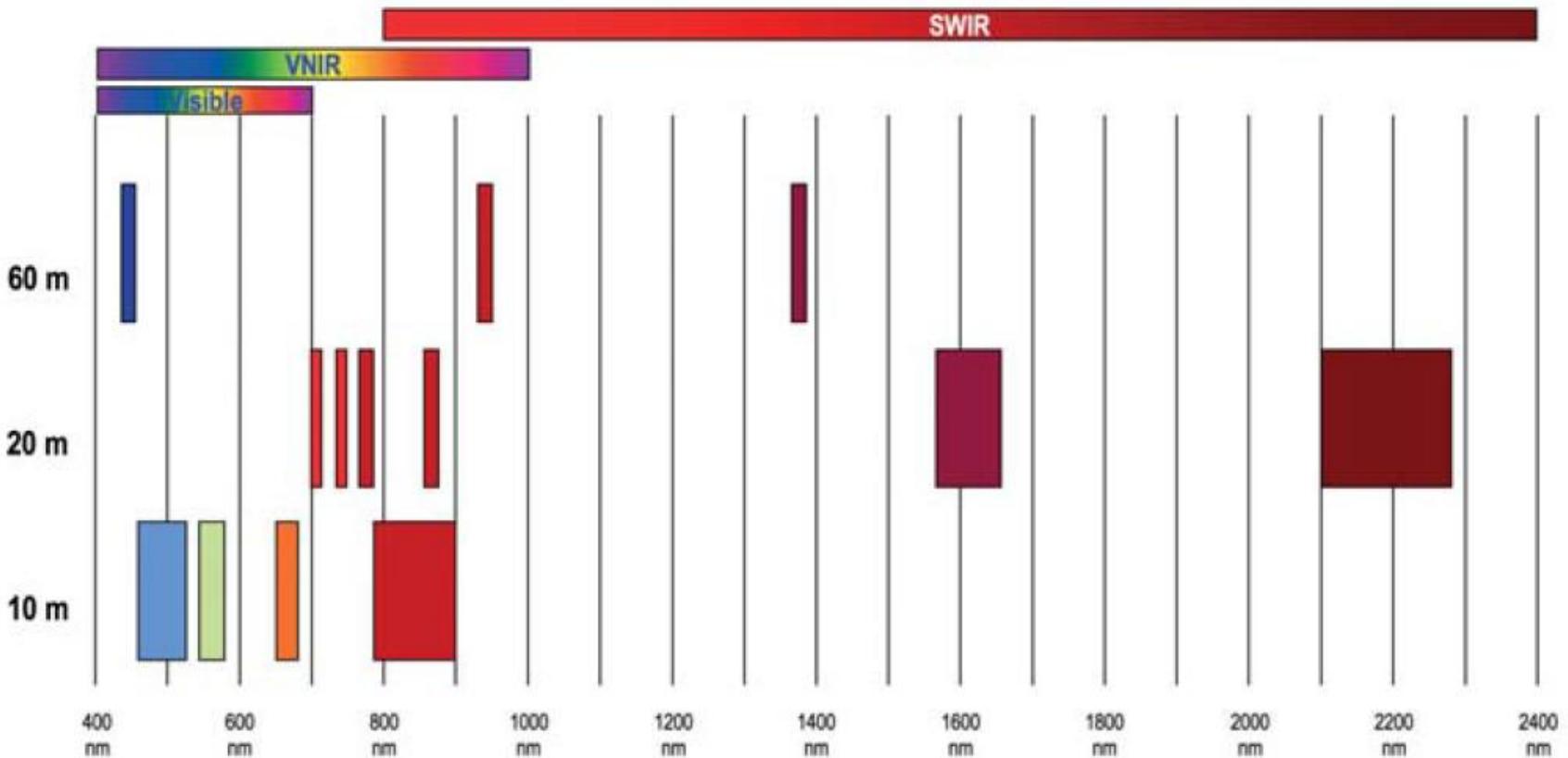


Spectral signatures of natural surfaces
Identification with multi/hyper spectral imagery

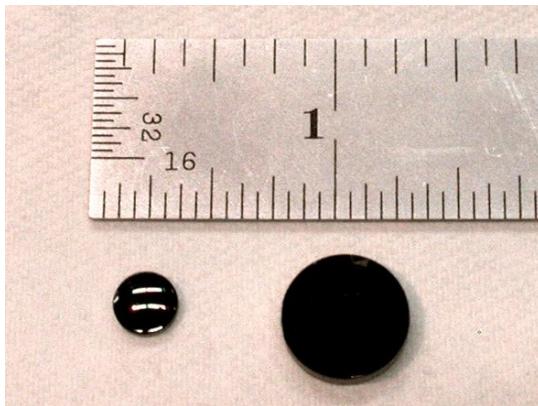
Spectral signature of water depending on its chlorophyle content
It depends also on its turbidity (content of sedimentary materials)

Multimodal : visible, NIR, SWIR

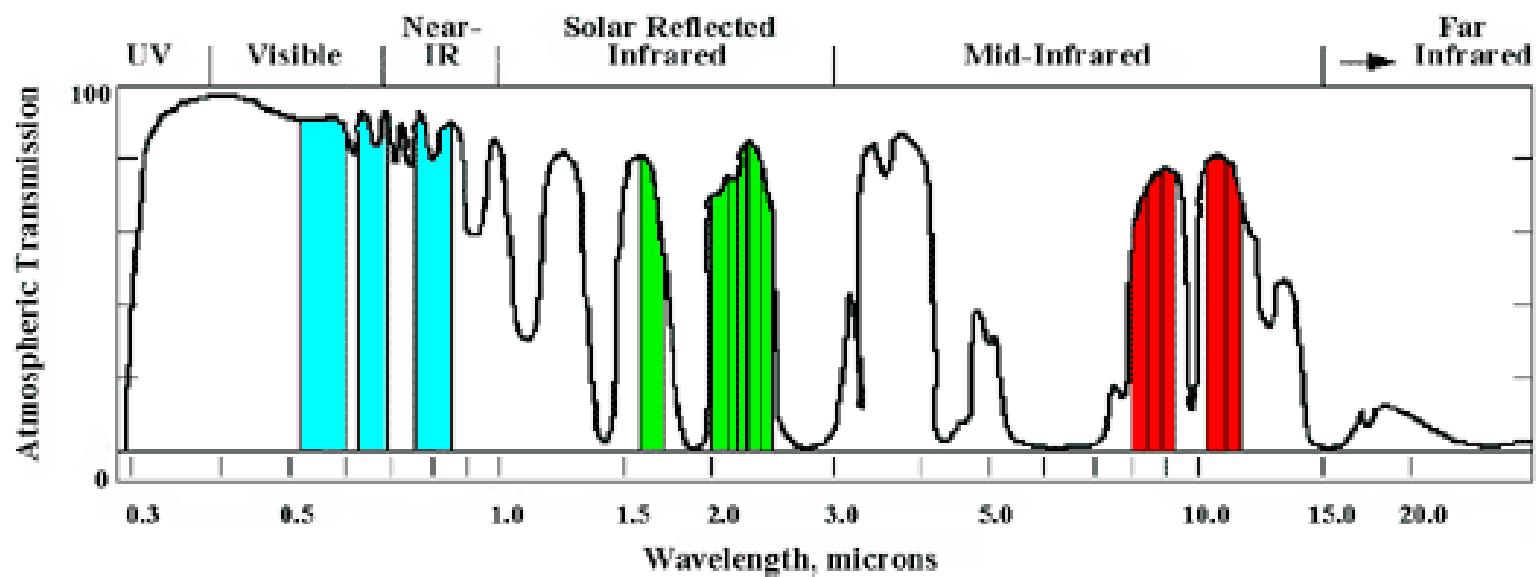
Sentinel-2 sensor



TIR (Thermic Infra Red) senors



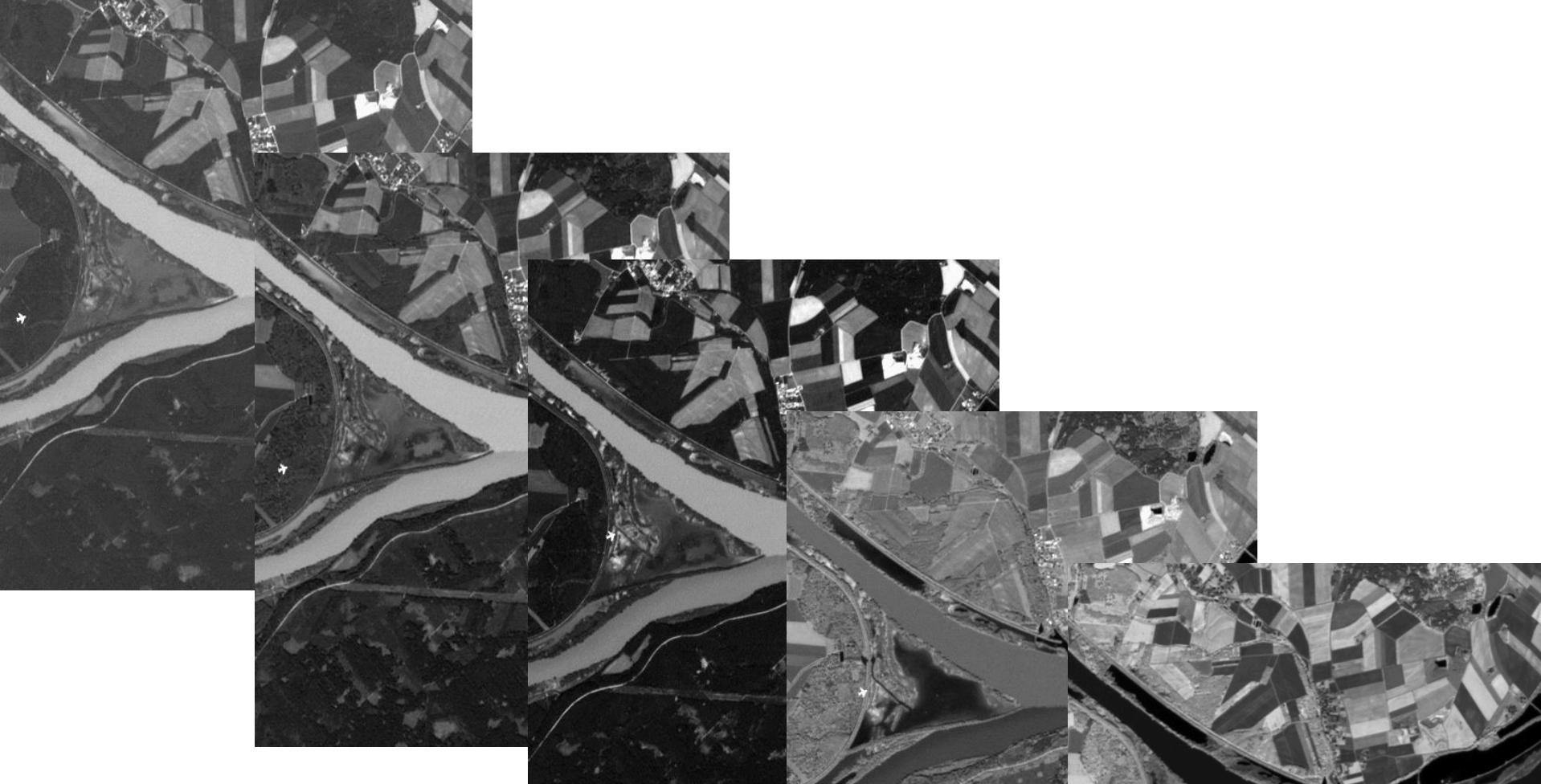
ASTER Spectral Bands



VNIR
15 m

SWIR
30 m

TIR
90 m



440-510

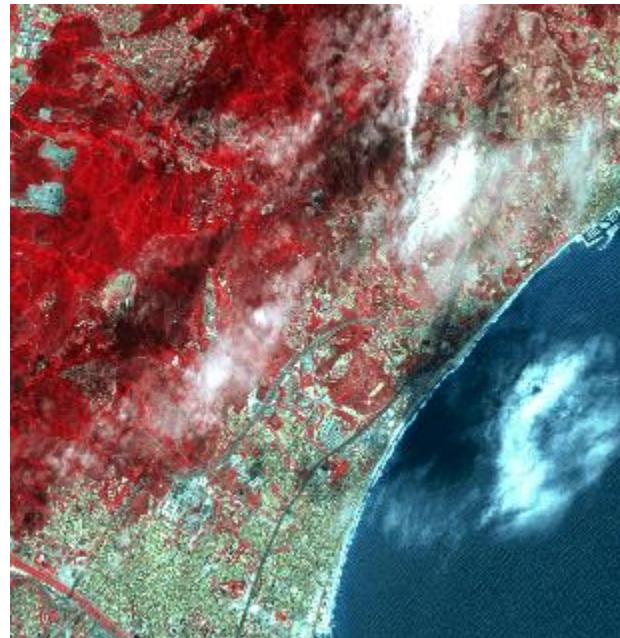
520-590

630-685

690-730

760-850

False color images



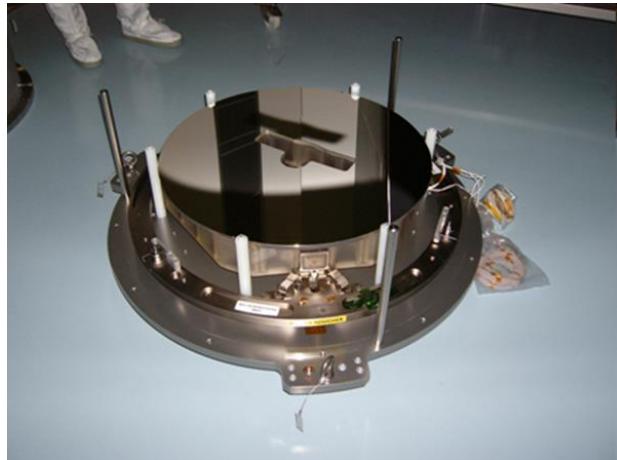
- Left: B+G+R channels (1, 2 and 3)
- Right: B+G+MIR channels (2, 3 and 4)

Optical systems

Aperture and resolution

μ+φ

- Resolution / pixel spacing
- For optical systems, resolution depends on distance D, aperture L and wavelength λ



$$\delta y = \frac{\lambda D}{L}$$



LECOM
ParisTech

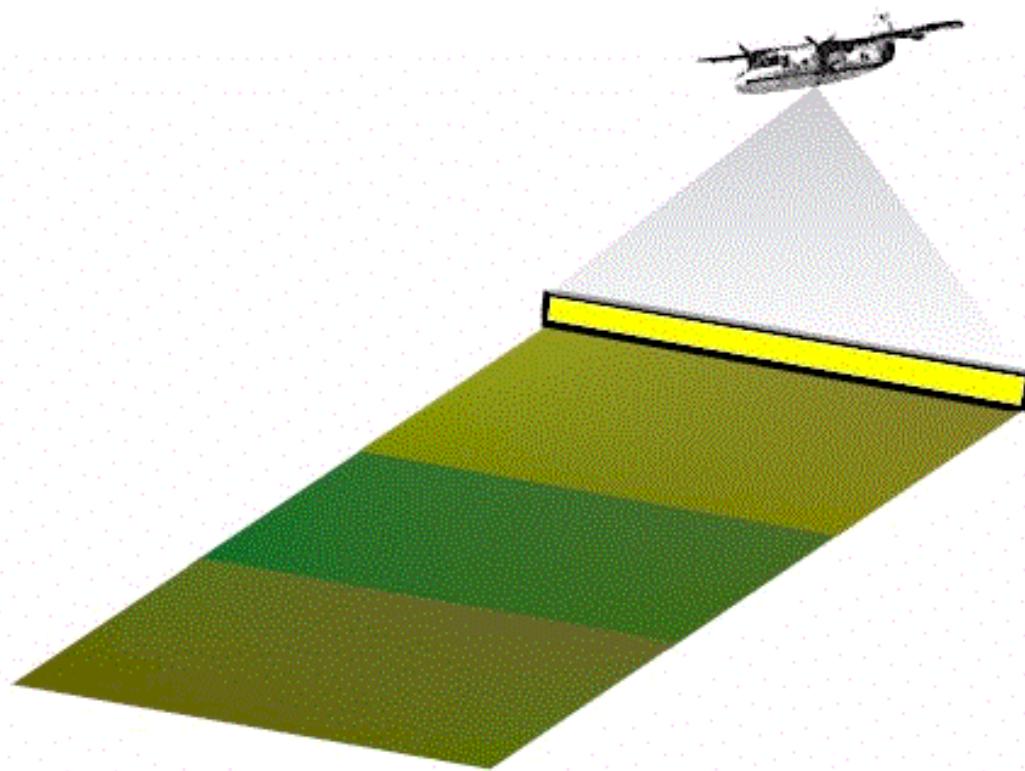


Scanning of the earth

- 1-D sensor (CCD line)
- Building of the image by scanning

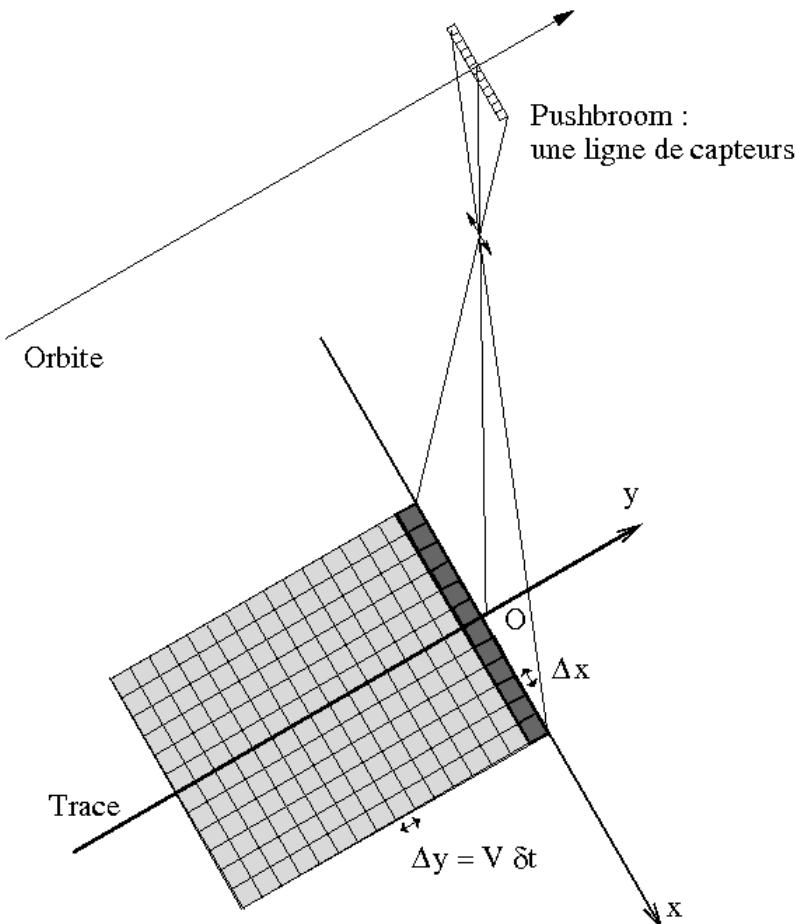


Pushbroom: 1 line + sensor movement



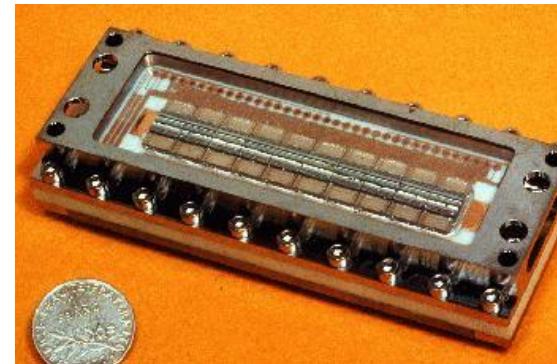
©Georgiatech University, Pr Scott Tyo

Pushbroom



- Line by line acquisition
- 6000 pixels to 24000 pixels
- Resolution in flight direction:

$$\Delta y = V_s \delta t$$



- VHR → limited integration time
 - 1 line of CCD → TDI



Skysat

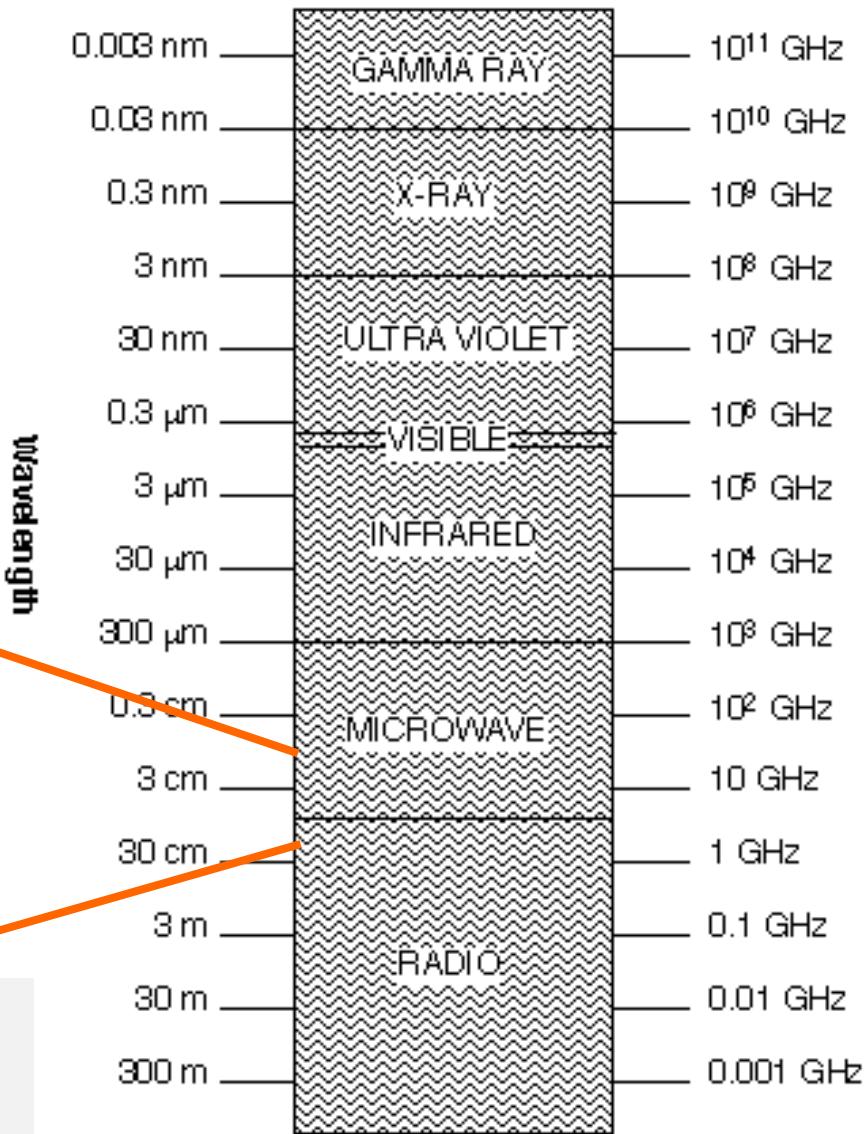
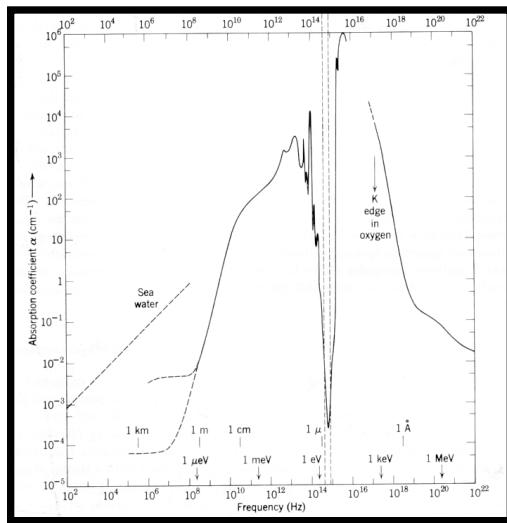
■ 2D CCD

- ~ 2000 x 1000
- Image swath: 2 km x 1 km
- 30 images/s



(SkyBox Imaging, then
Terra Bella (Google)
bought by Planet

SAR sensors - Electro-magnetic waves

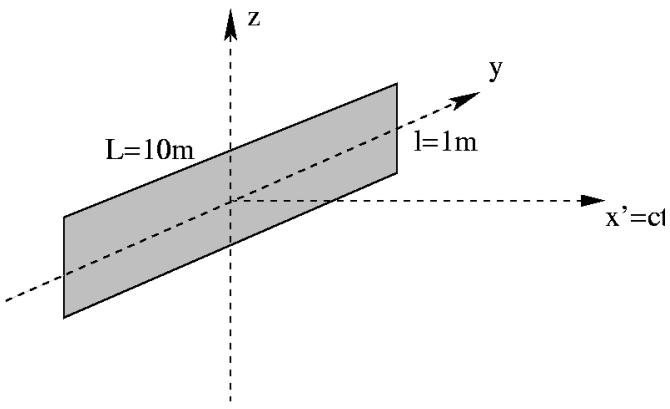


Radar bands:

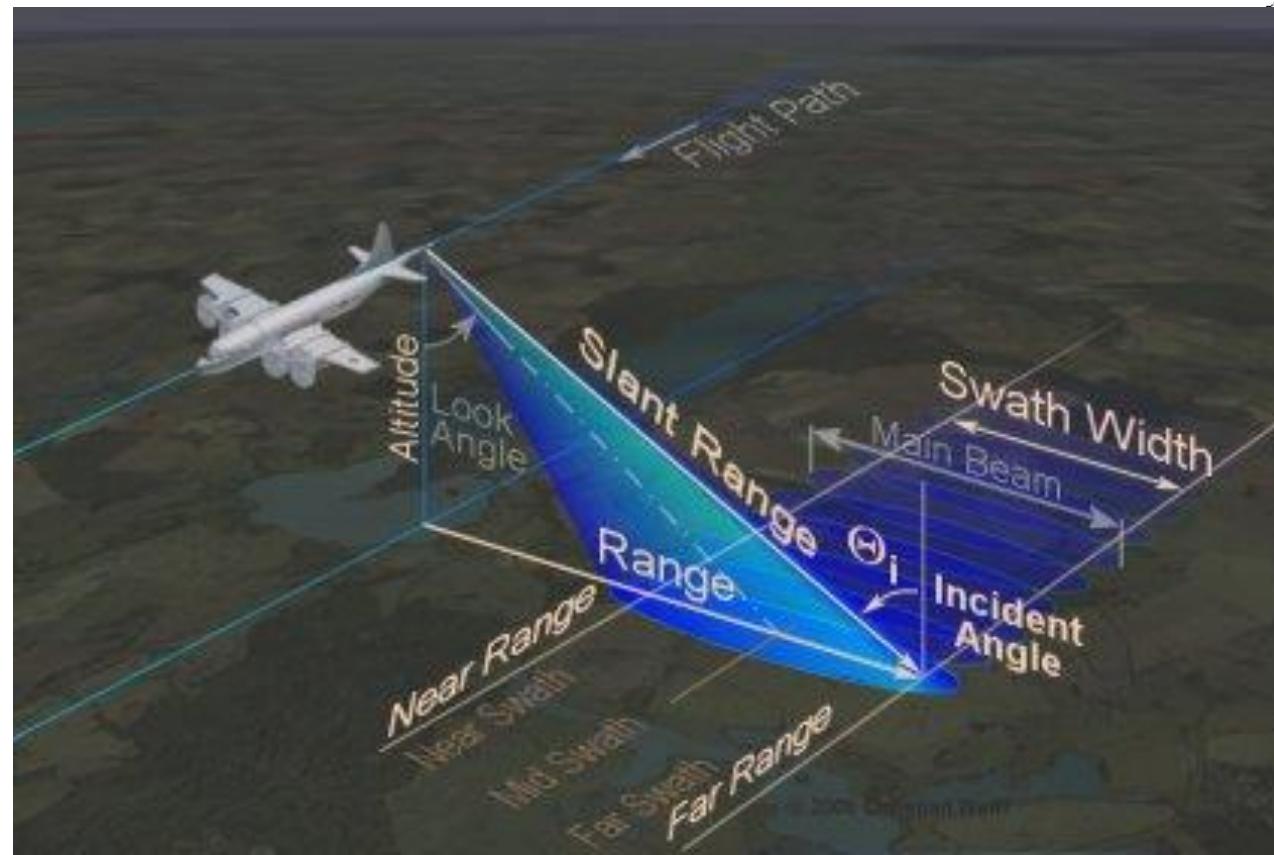
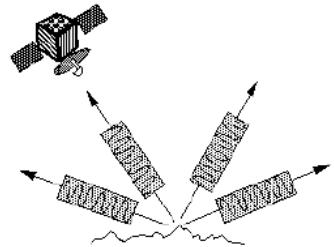
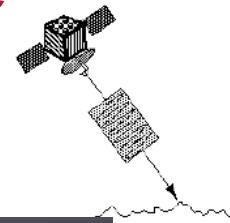
- X ~ 2 cm (~ 9 GHz)
- C ~ 5 cm (~ 5 GHz)
- L ~ 20 cm (~ 1 GHz)

- X: top of the canopy
- L: vegetation penetration

Radar antenna



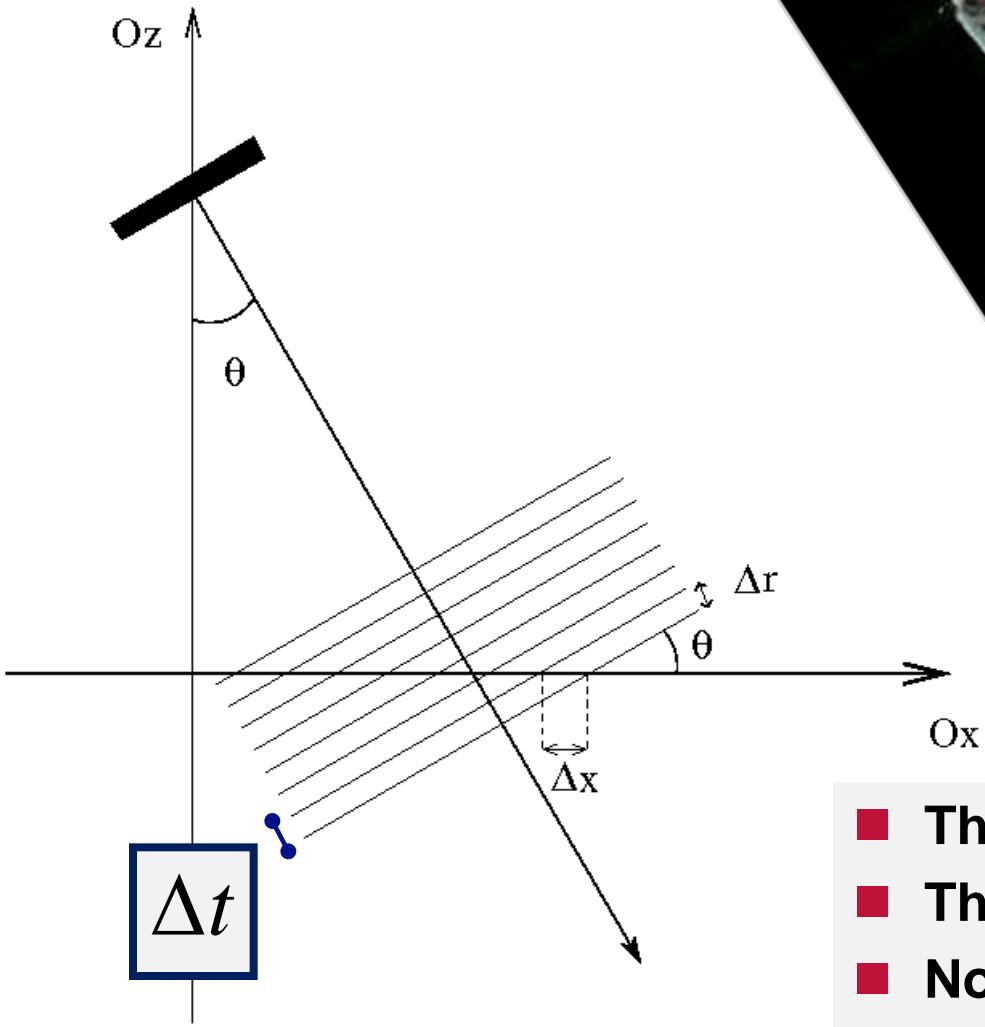
Radar antenna: main lobe



$$\delta y = \frac{\lambda R}{D}$$

©<http://www.radartutorial.eu/>

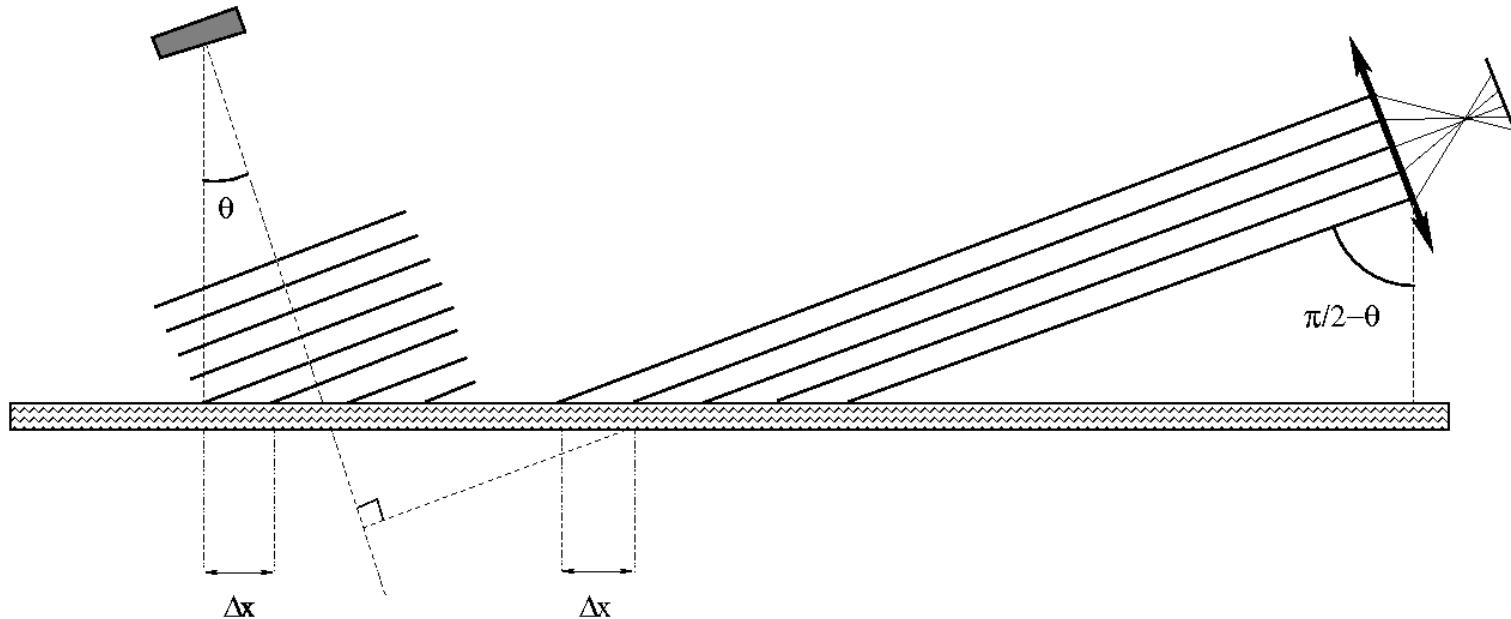
Lateral viewing



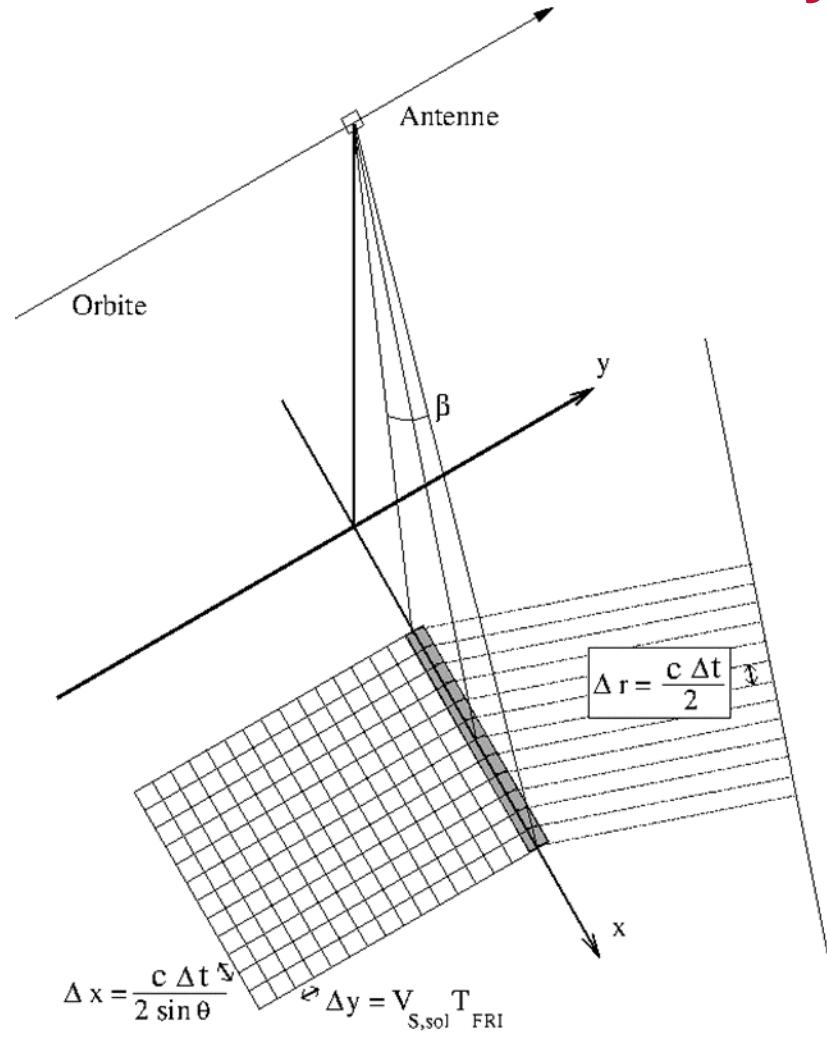
$$\Delta x = \frac{\Delta r}{\sin \theta}$$

- The range cell (Δr) is constant
- The ground cell depends on θ
- No dependency on R !!

Equivalence optic / SAR



« radarbroom » : Movement of the « synthetic » antenna (>5 km)



■ SAR: azimuth direction

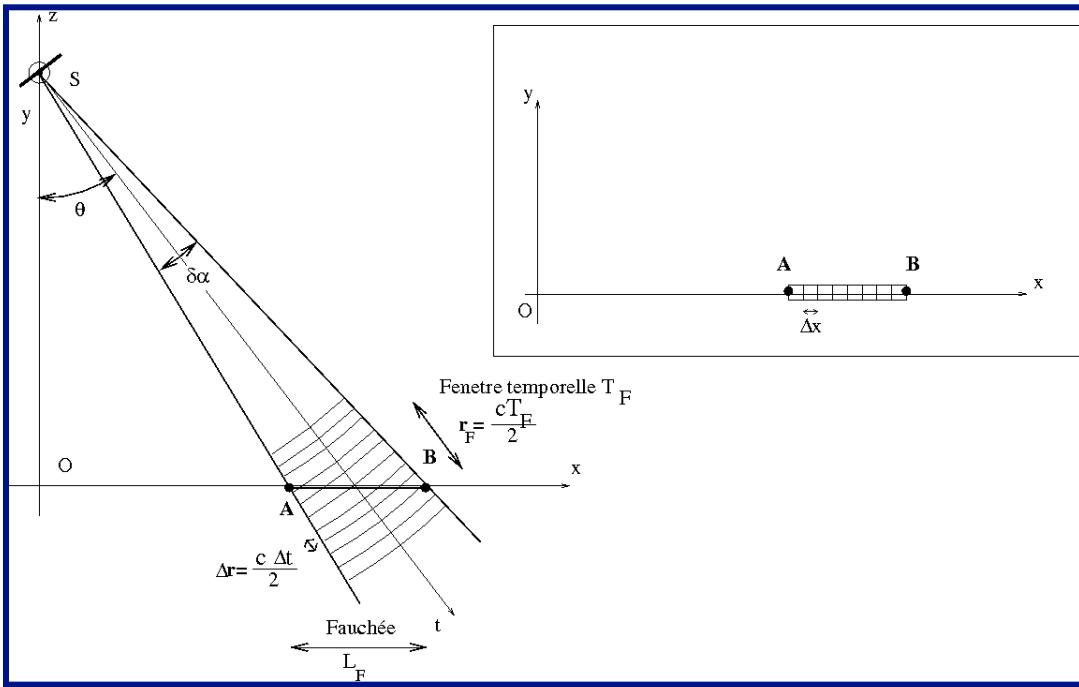
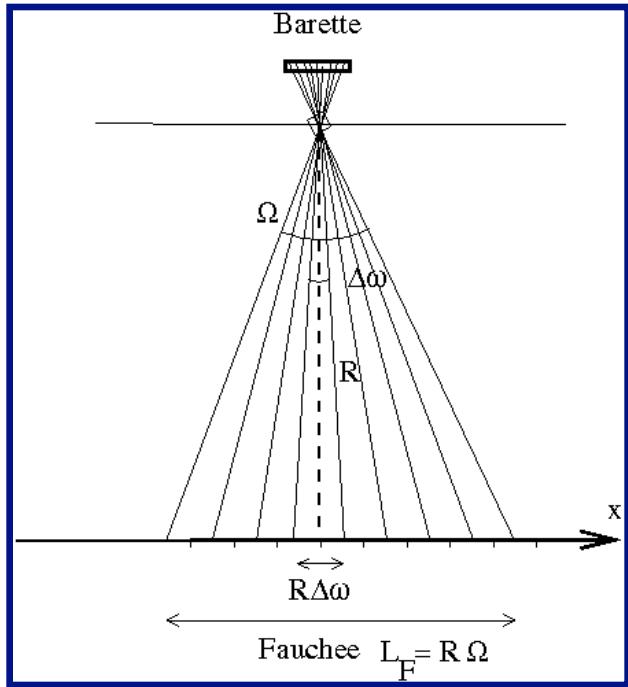
- Real antenna : a few meters
- Principle of Synthetic Aperture Radar

■ SAR: range direction

- Signal duration too long
- Chirp

**Both directions:
matched filters !**

Optic and radar swath



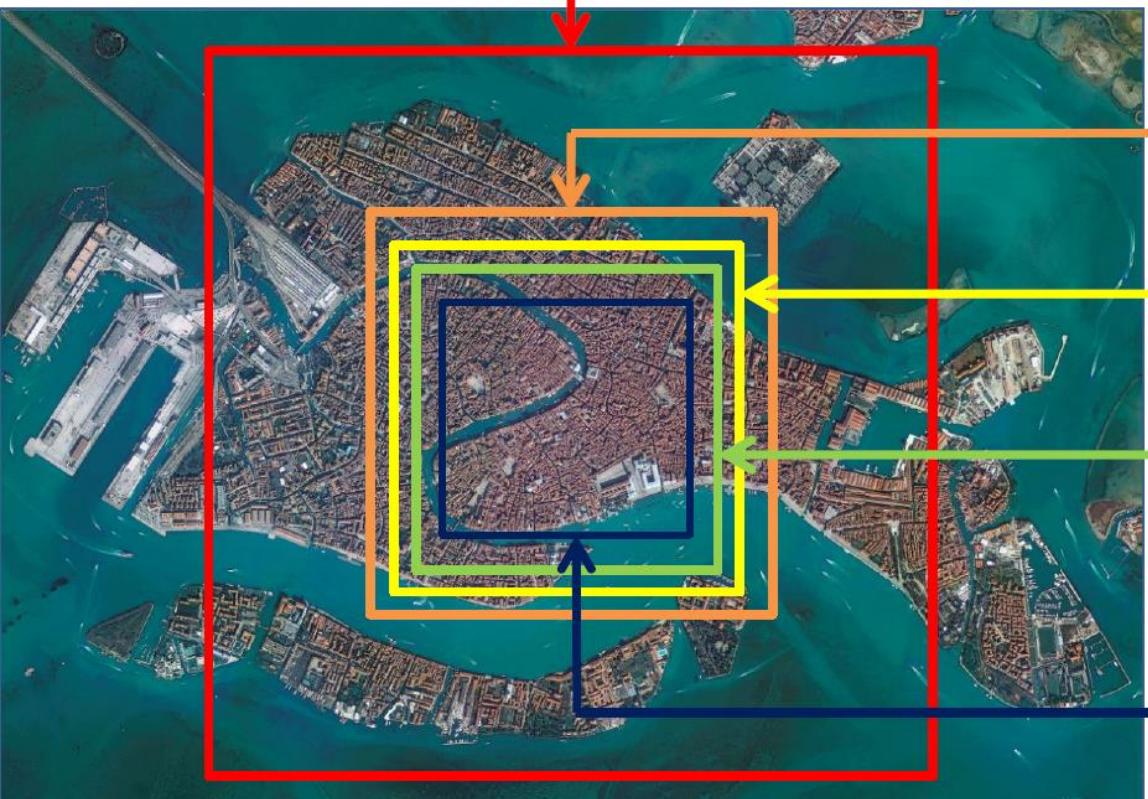
■ HR and VHR sensors:

- Swath of 10km to 100 km
- Ground cell size: 24 cm to 10 m

■ « Large swath » sensors:

- Swath of 100km to 2000 km
- Ground cell size : 100 m to 2 km

VHR sensors



Resurs-P (Russia)
38,6 x 38,6 km
R=0,7-1 m

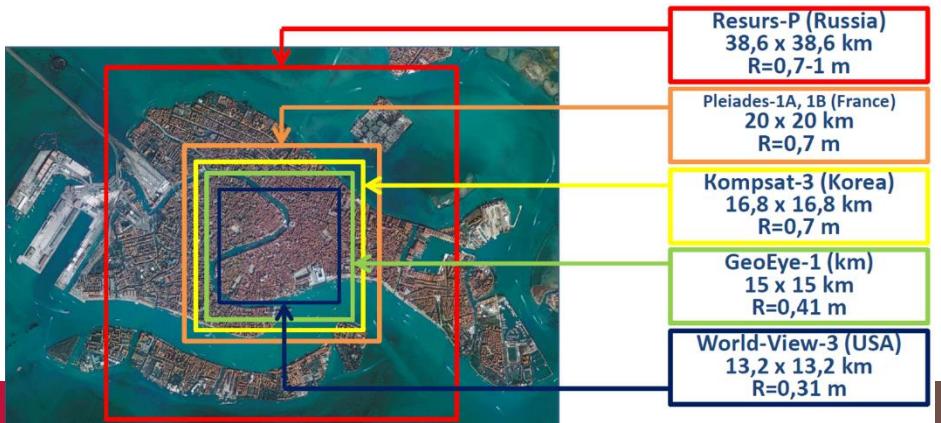
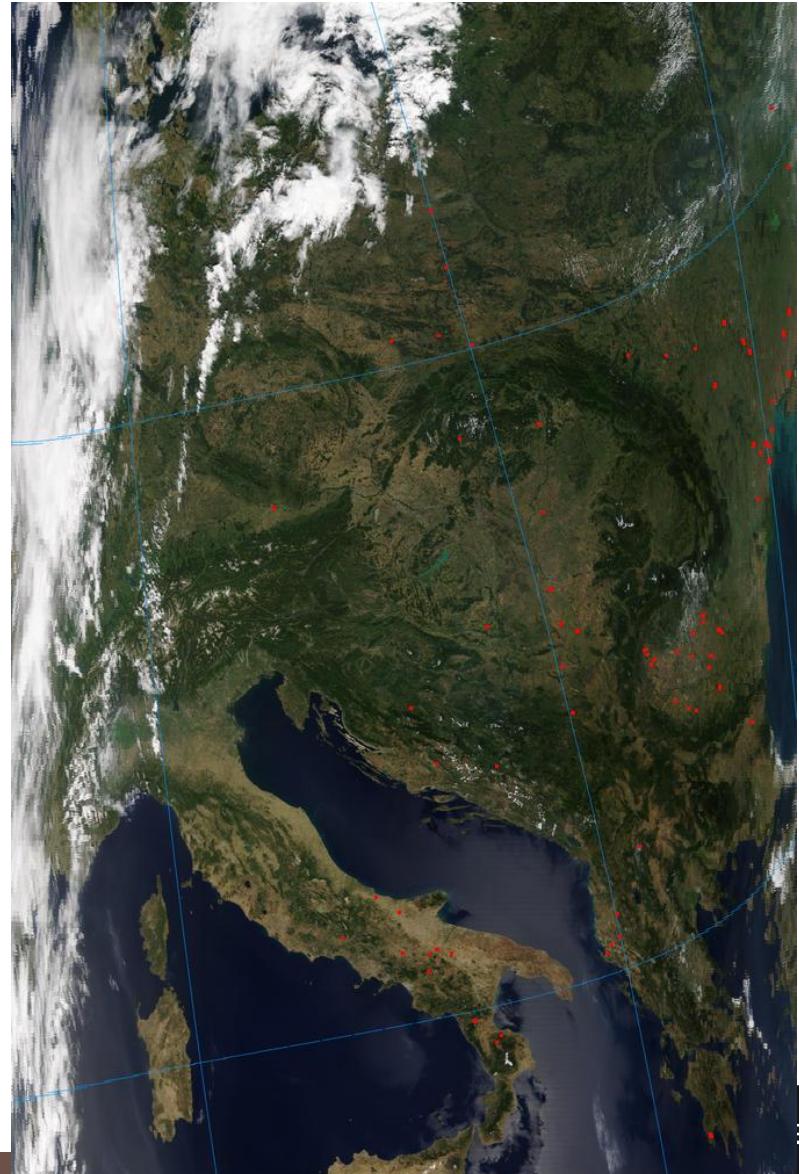
Pleiades-1A, 1B (France)
20 x 20 km
R=0,7 m

Kompsat-3 (Korea)
16,8 x 16,8 km
R=0,7 m

GeoEye-1 (km)
15 x 15 km
R=0,41 m

World-View-3 (USA)
13,2 x 13,2 km
R=0,31 m

Large / small swath



IDS/IMAGES



Sensor and satellite

■ Satellite:

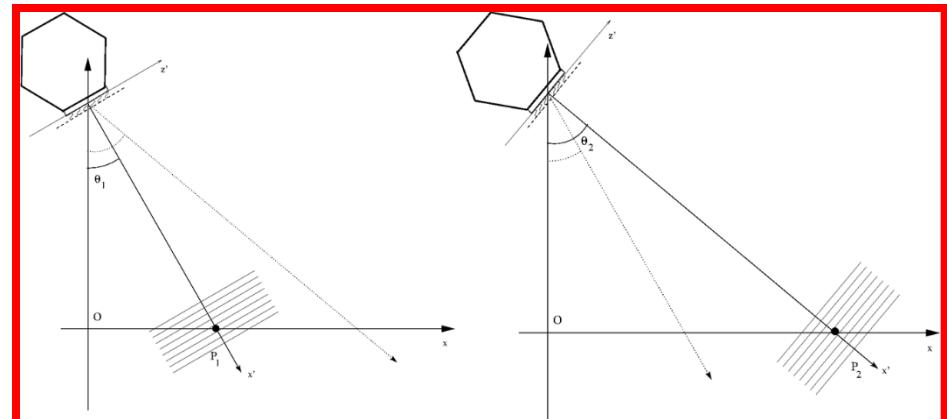
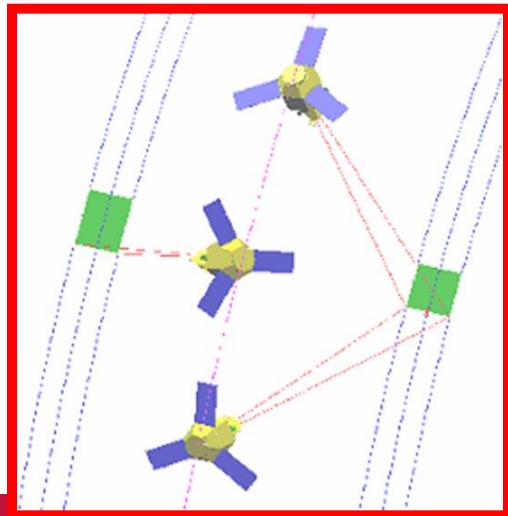
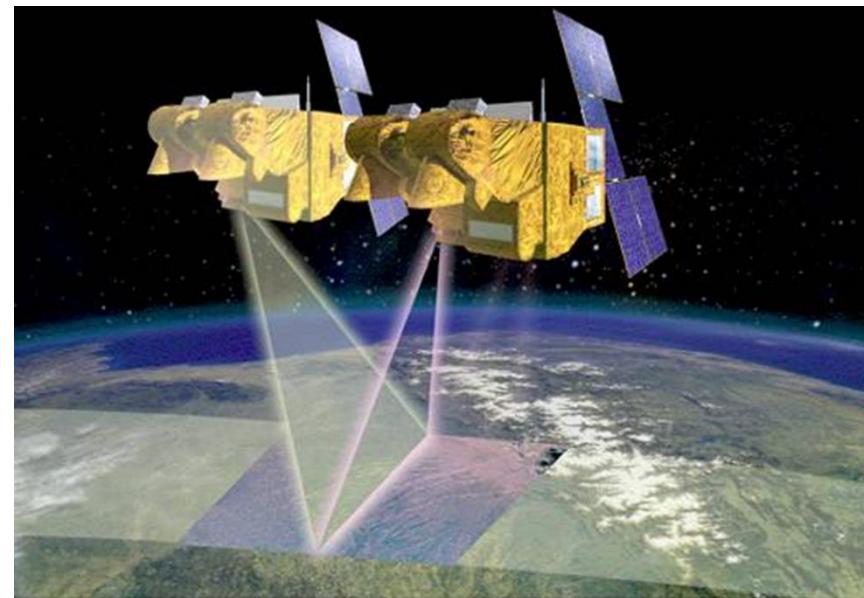
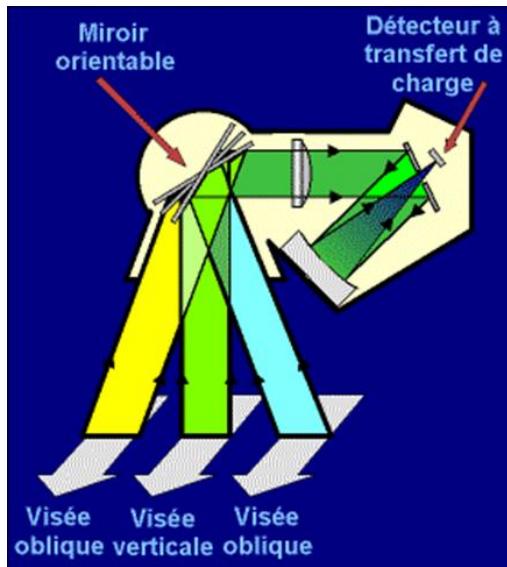
- → Orbital cycle: **time of the cycle**
- Identical geometry viewing for each cycle

■ Satellite + sensor agility:

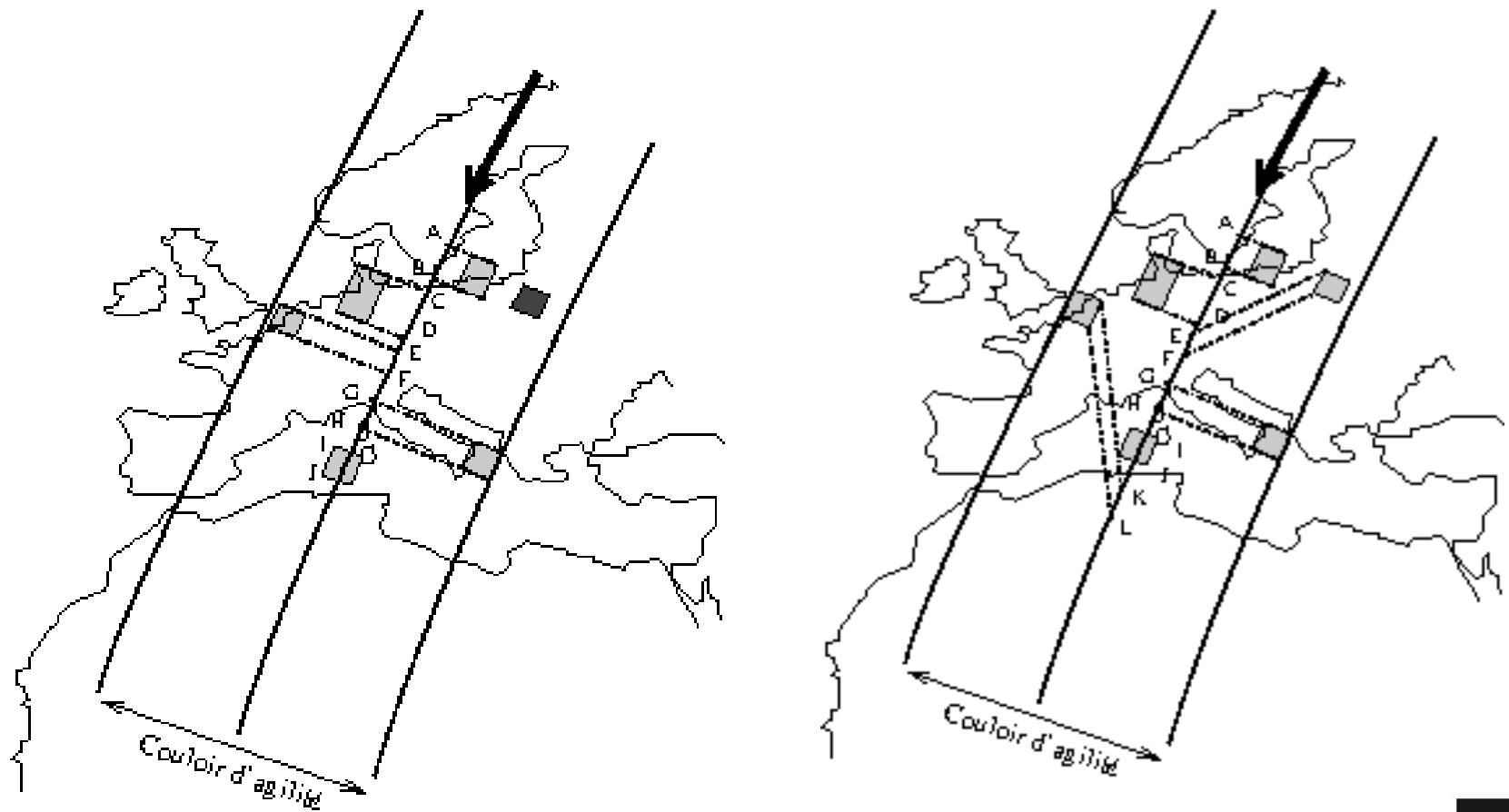
- → **Revisit time**
- Sensor geometry different for each acquisition

■ Satellite constellations

Sensor agility



Left / right and forward / backward agility



Pléiades



© CNES

Revisit time: Pleiades



©CNES

- Sensor agility
- Angular variations

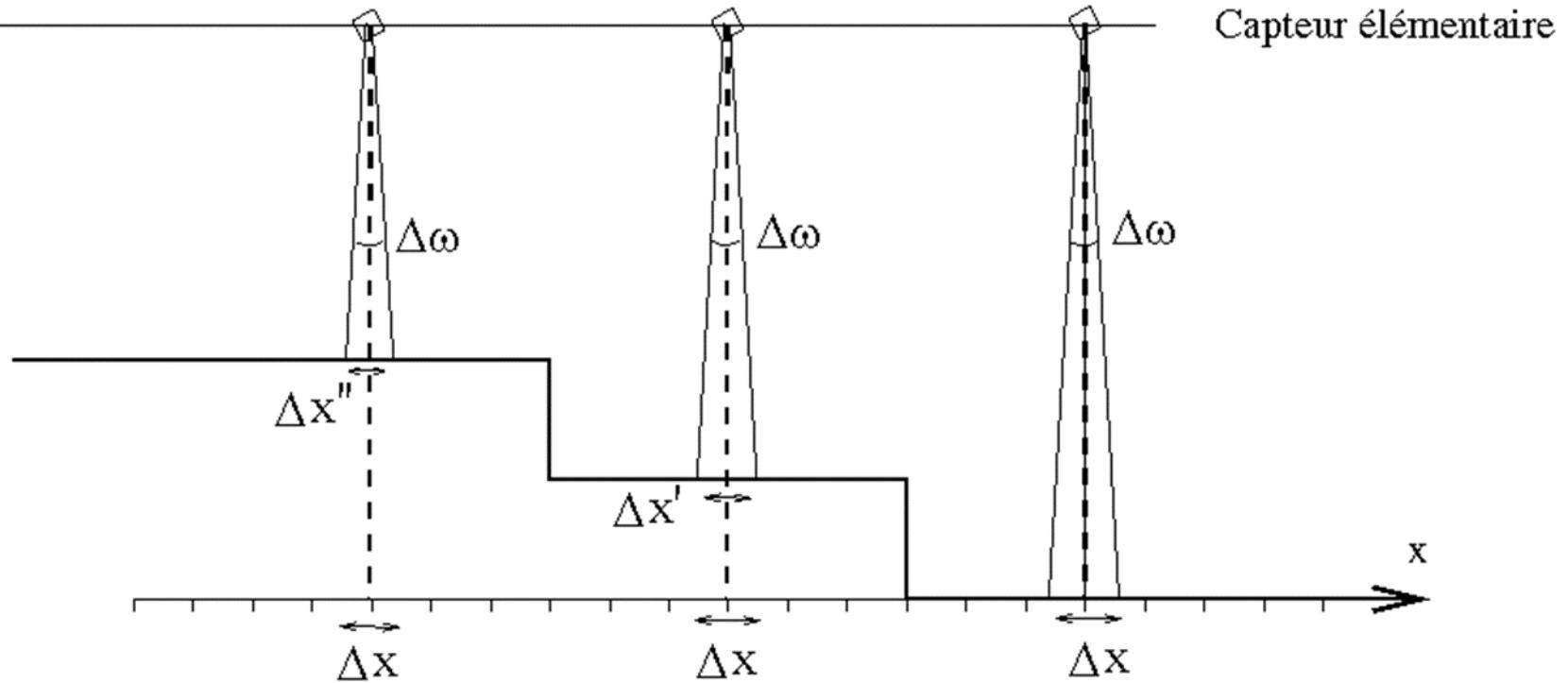
Authorized angular variation	1 satellite	2 satellites
5°	25 days	13 days
20°	7 days	5 days
30°	5 days	4 days
45°	2 days	1 day
47°	1 day	1 day



Pleiades

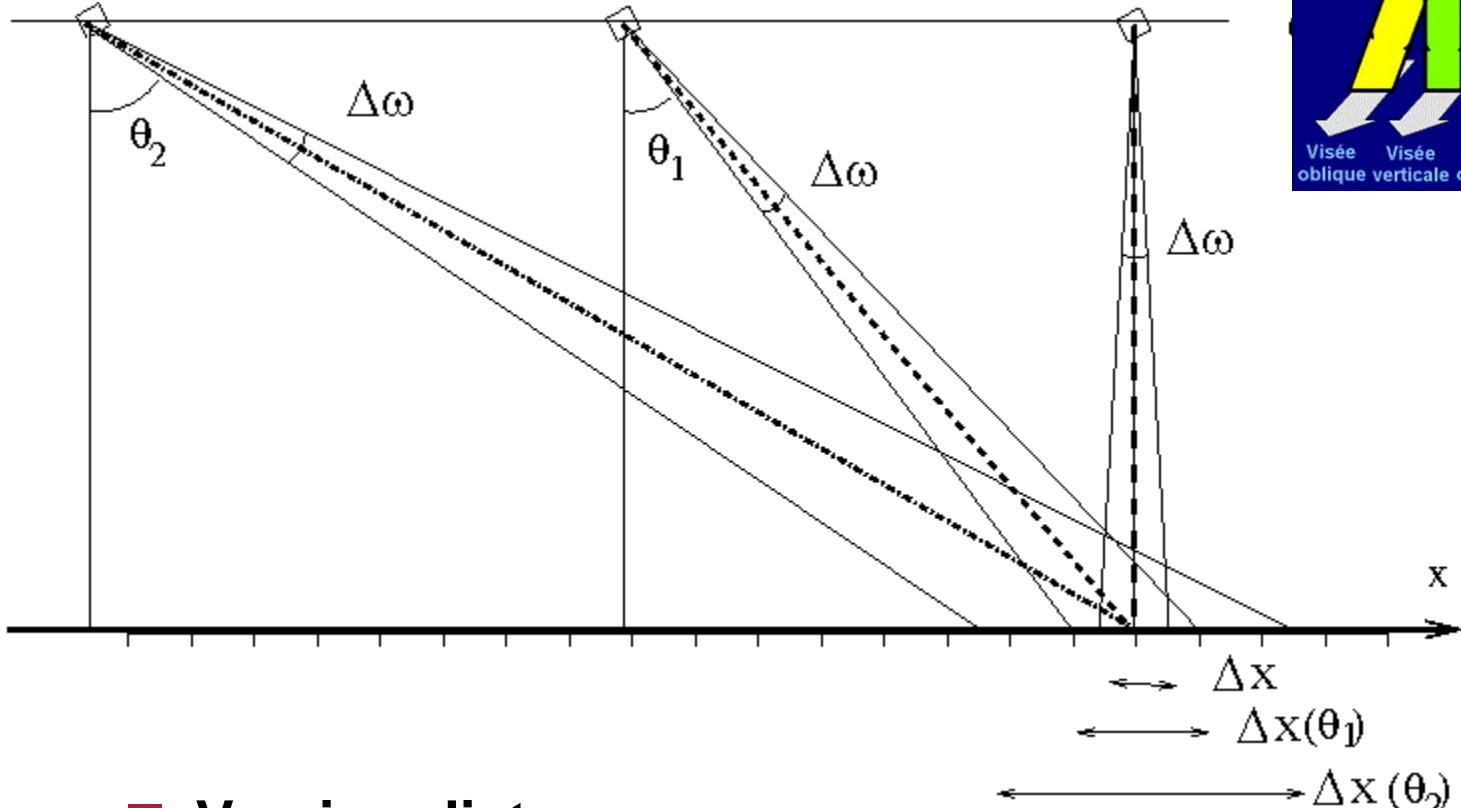
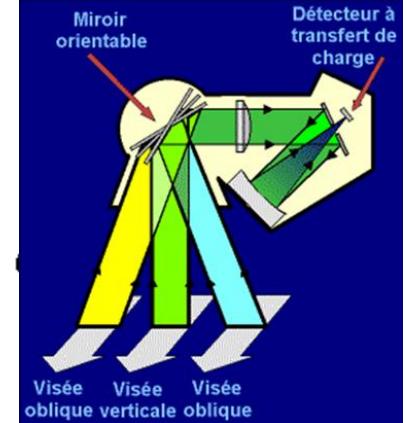


Optic – vertical viewing



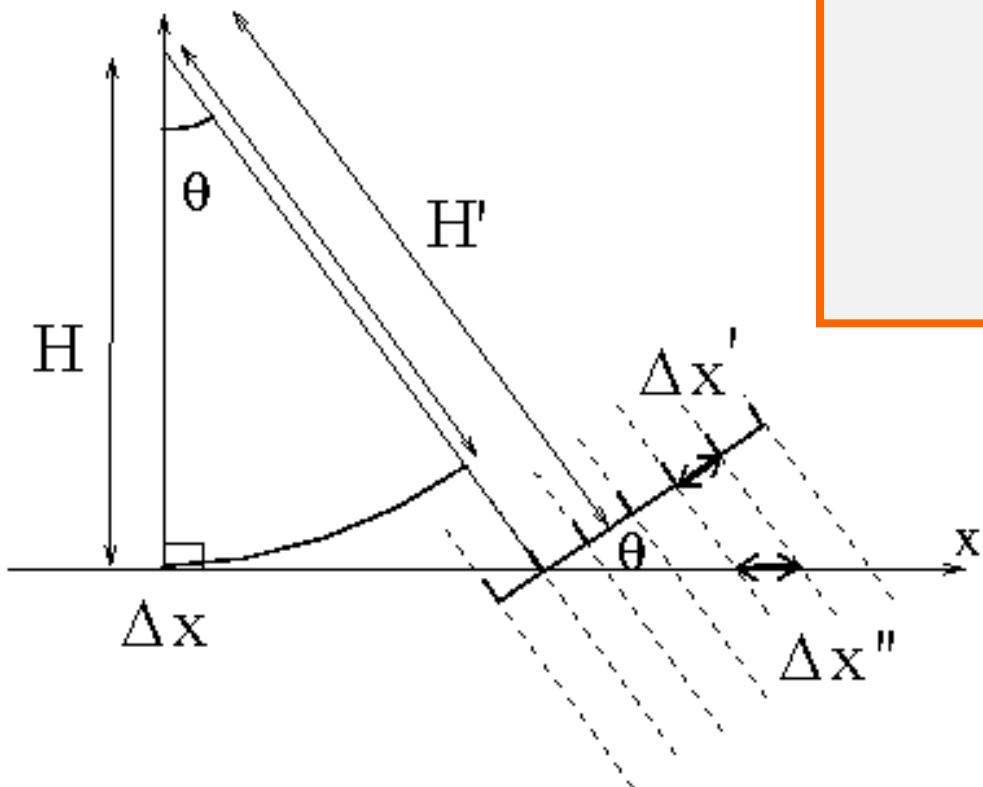
$$\Delta x(H') = \frac{H'}{H} \Delta x(H)$$

Lateral viewing Angular step $\Delta\omega$



- Varying distance
- Varying local incidence

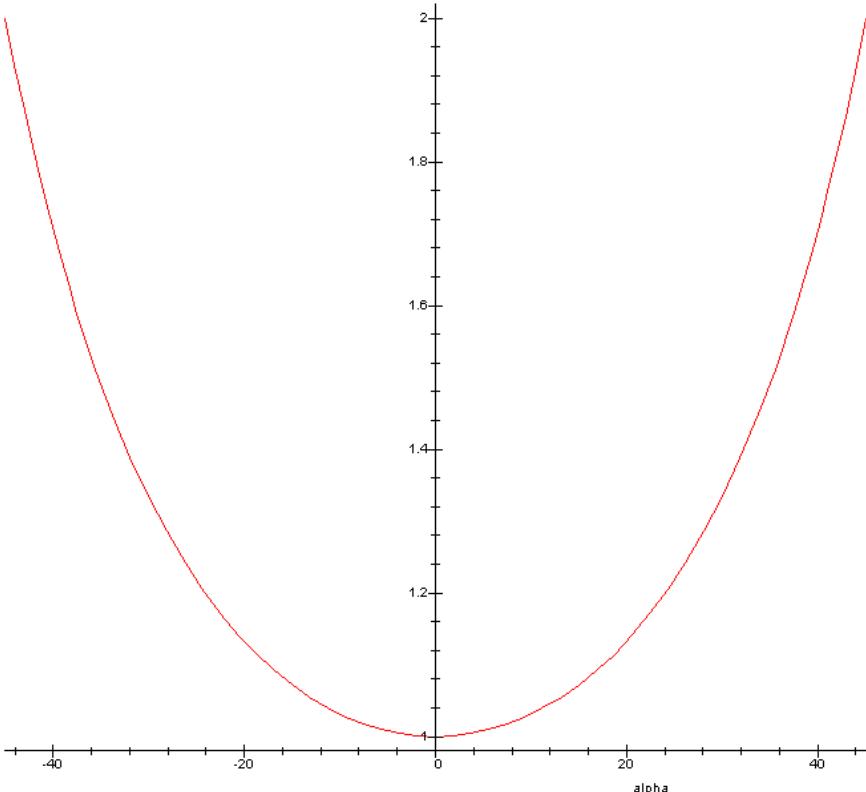
Optic – lateral viewing, flat earth



$$\begin{aligned}\Delta x(H', \theta) &= \frac{\Delta x(H', \theta' = 0^\circ)}{\cos(\theta)} \\ &= \Delta x(H, \theta' = 0^\circ) \frac{H'}{H} \frac{1}{\cos(\theta)} \\ &= \Delta x(H, \theta' = 0^\circ) \left(\frac{1}{\cos(\theta)} \right)^2\end{aligned}$$

Ikonos : GSI from -45° to 45°

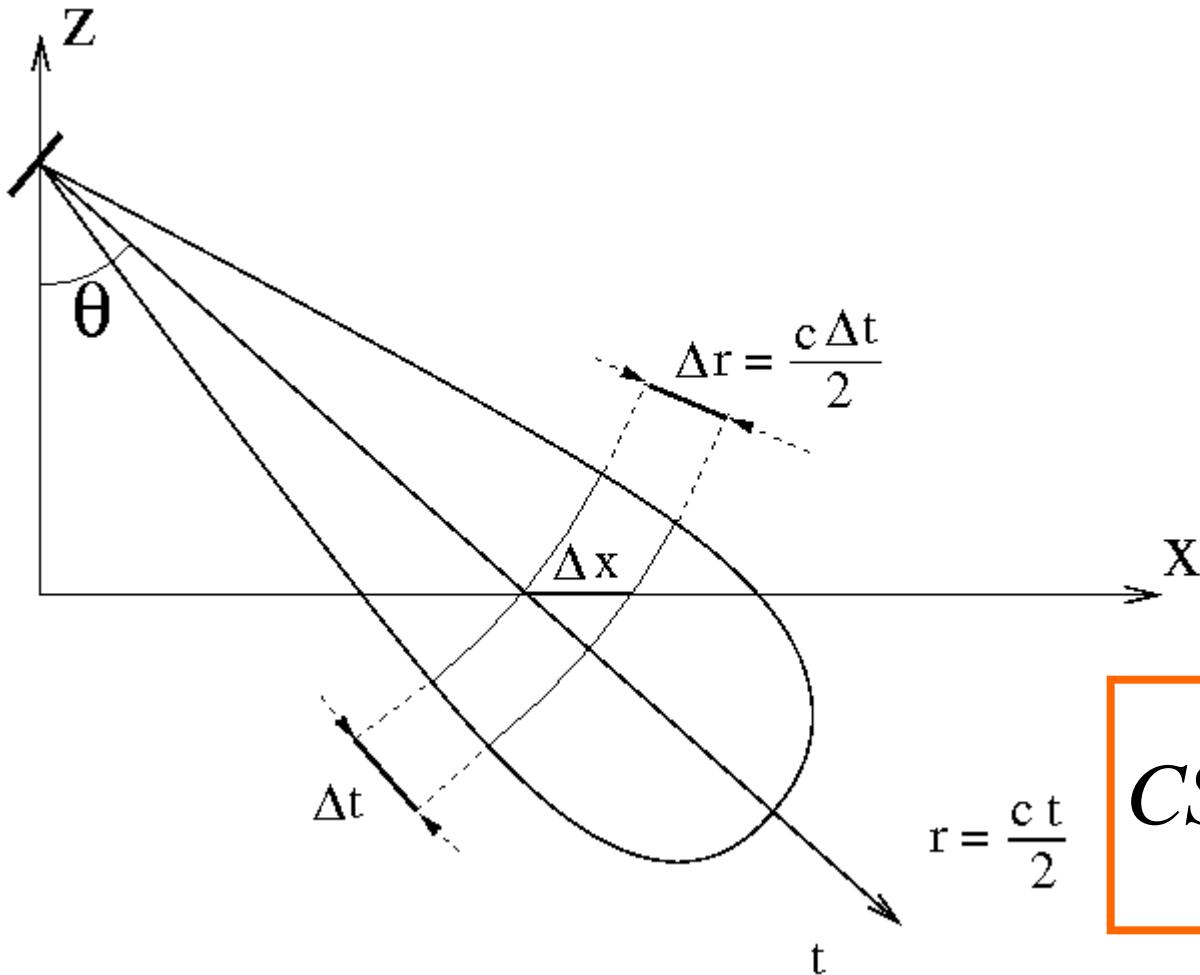
$$GSI(\theta) = GSI(0) \left(\frac{1}{\cos(\theta)} \right)^2$$



1m to 2m

WARNING : flat earth hypothesis

Radar: lateral viewing



$$CS = \Delta x = \frac{\Delta r}{\sin(\theta)}$$

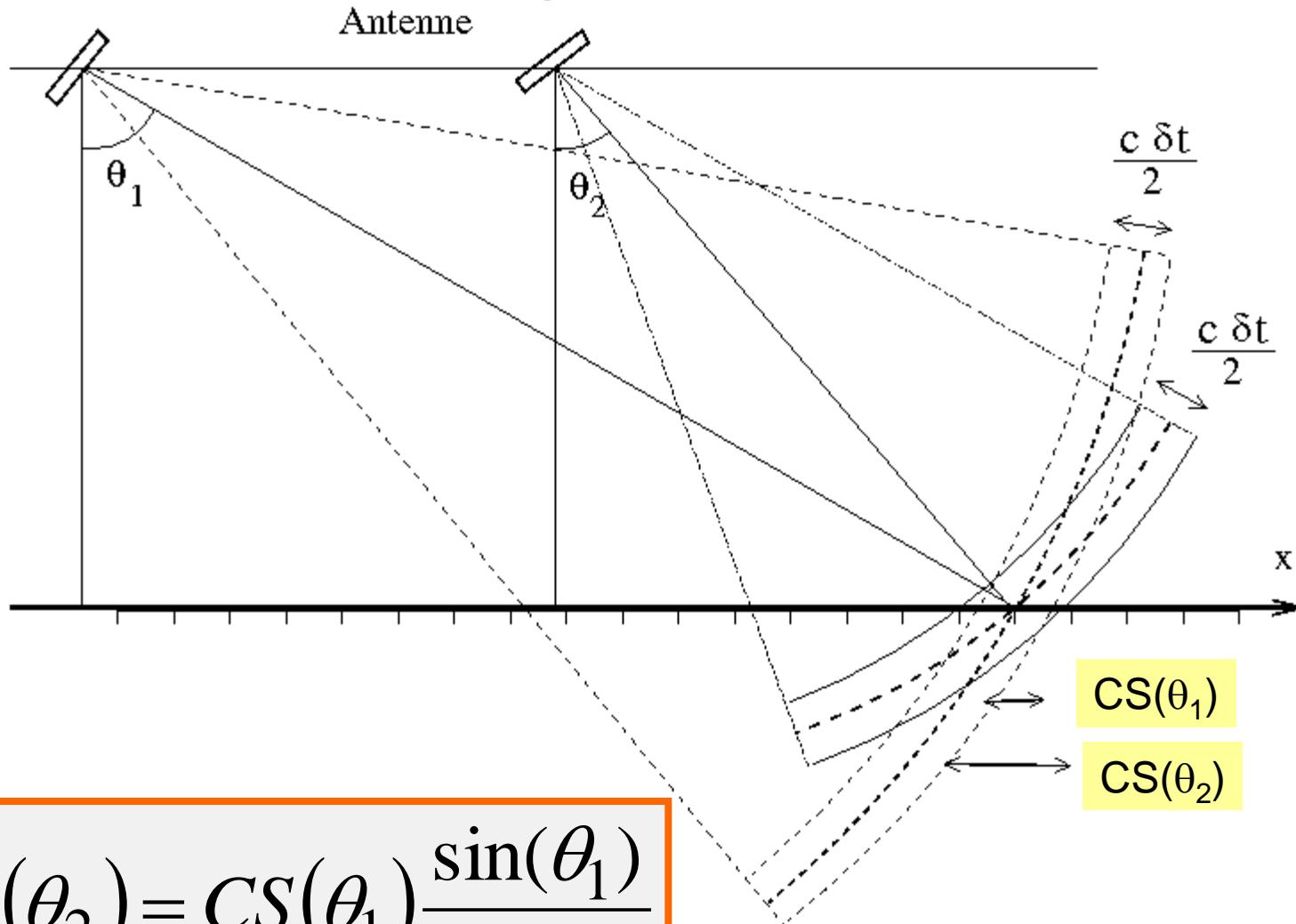


$\theta=6^\circ$, dx

$\theta=60^\circ$, dx/10



Variation of the ground cell with the local incidence angle



$$CS(\theta_2) = CS(\theta_1) \frac{\sin(\theta_1)}{\sin(\theta_2)}$$

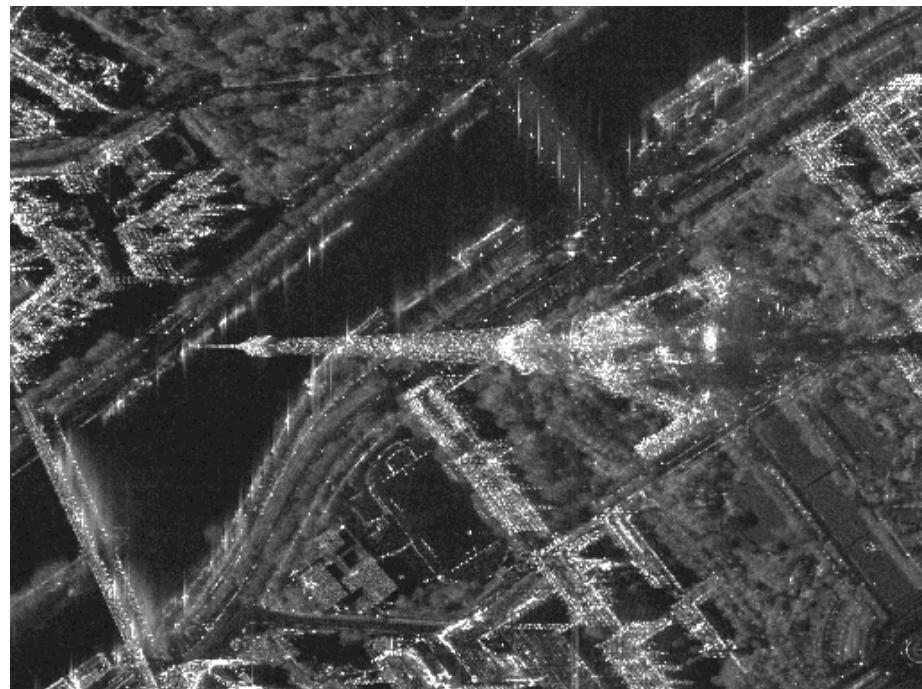
Eiffel Tower – effect of lateral viewing





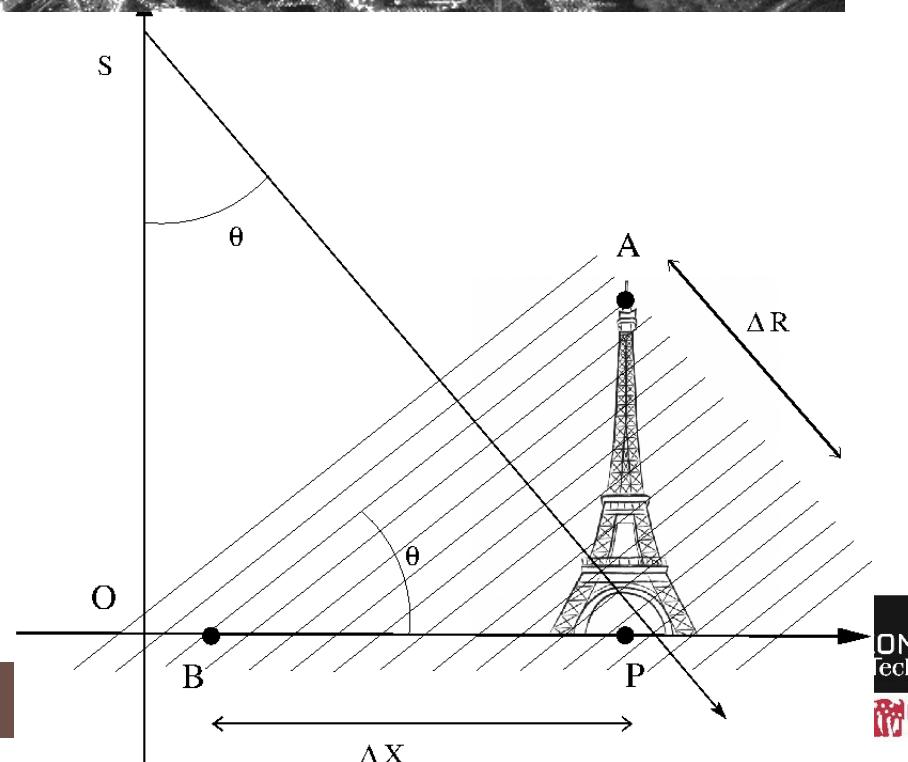
Visée latérale

■ Terrasar-X, $\theta \sim 34^\circ$

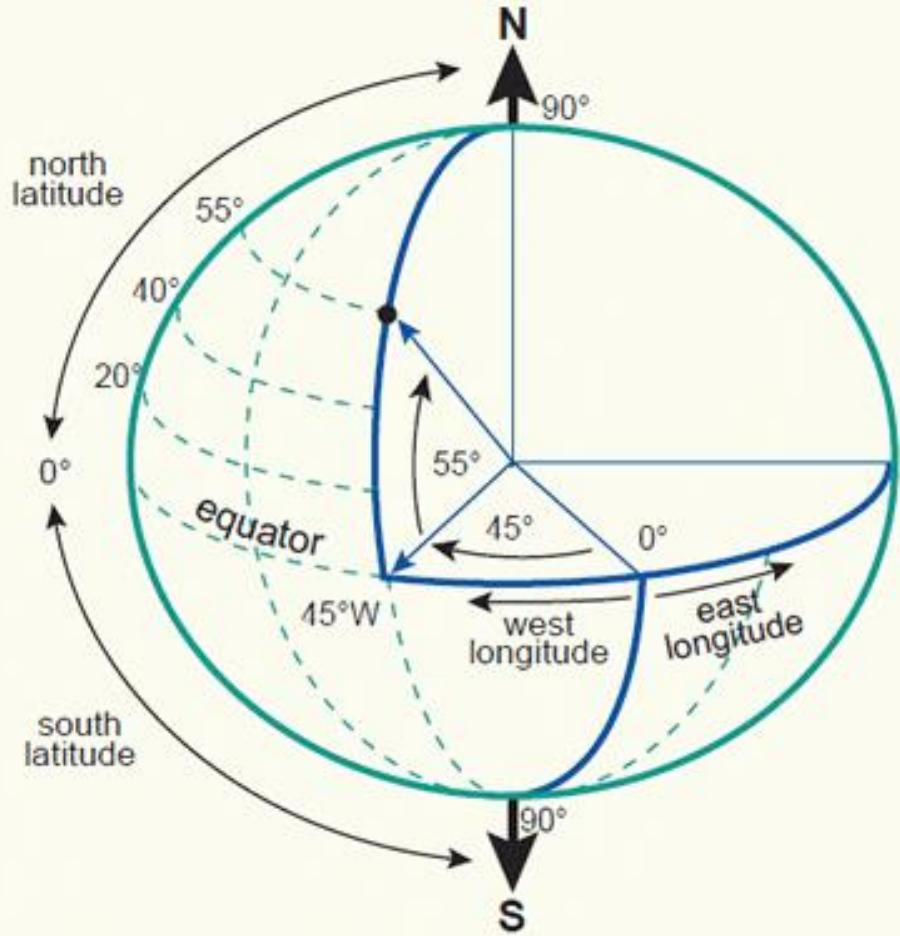


$$H = \frac{\Delta X}{\tan \theta}$$

$$H = \frac{\Delta R}{\cos \theta}$$

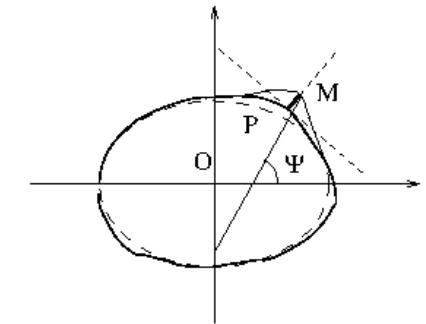
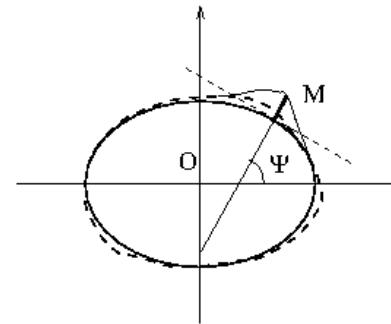
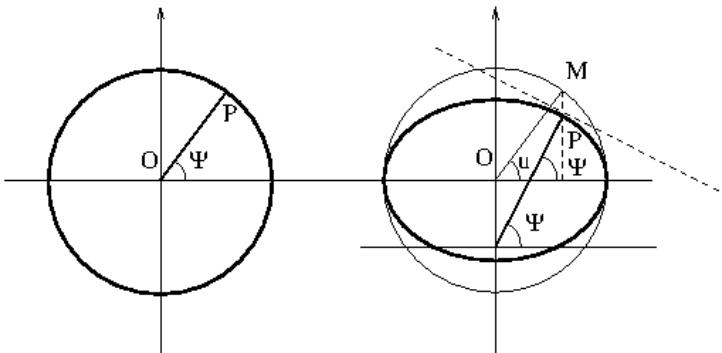


Geographic coordinate system



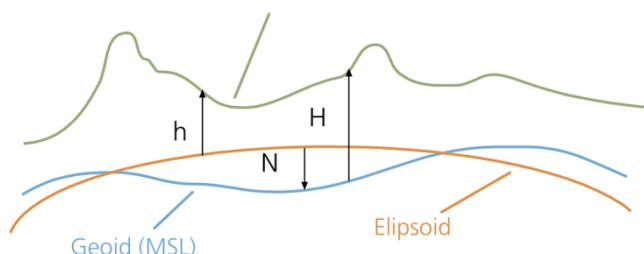
- Choice of an ellipsoid
- A point is defined by
 - Longitude
 - Latitude
- Altitude: h ?

Coordinate of a point on earth (X,Y,Z) : Longitude, latitude, altitude



$$h = H + N$$

Topo surface (earth surface or GPS antenna)



h =ellipsoid height
 H =orthometric height
 N =geoid height

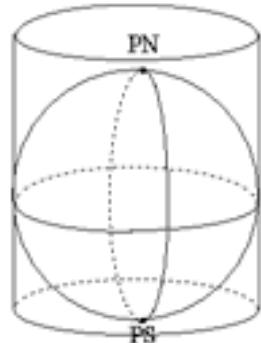
Ellipsoid / geoid Different altitude definitions :

- orthometric height (H) = the height above an imaginary surface called the geoid, which is determined by the earth's gravity and approximated by MSL (Mean Sea Level)
- GPS = height (h) above the reference ellipsoid that approximates the earth's surface.

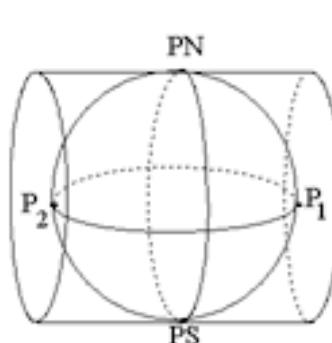
From earth to map

■ « modeling of the earth surface »

Représentation cylindrique :

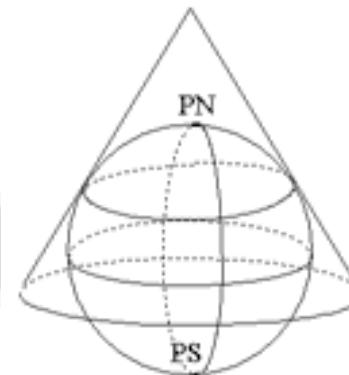


directe

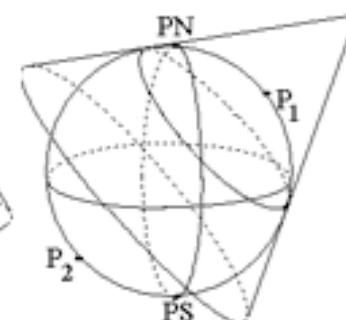


transverse

Représentation conique :



directe



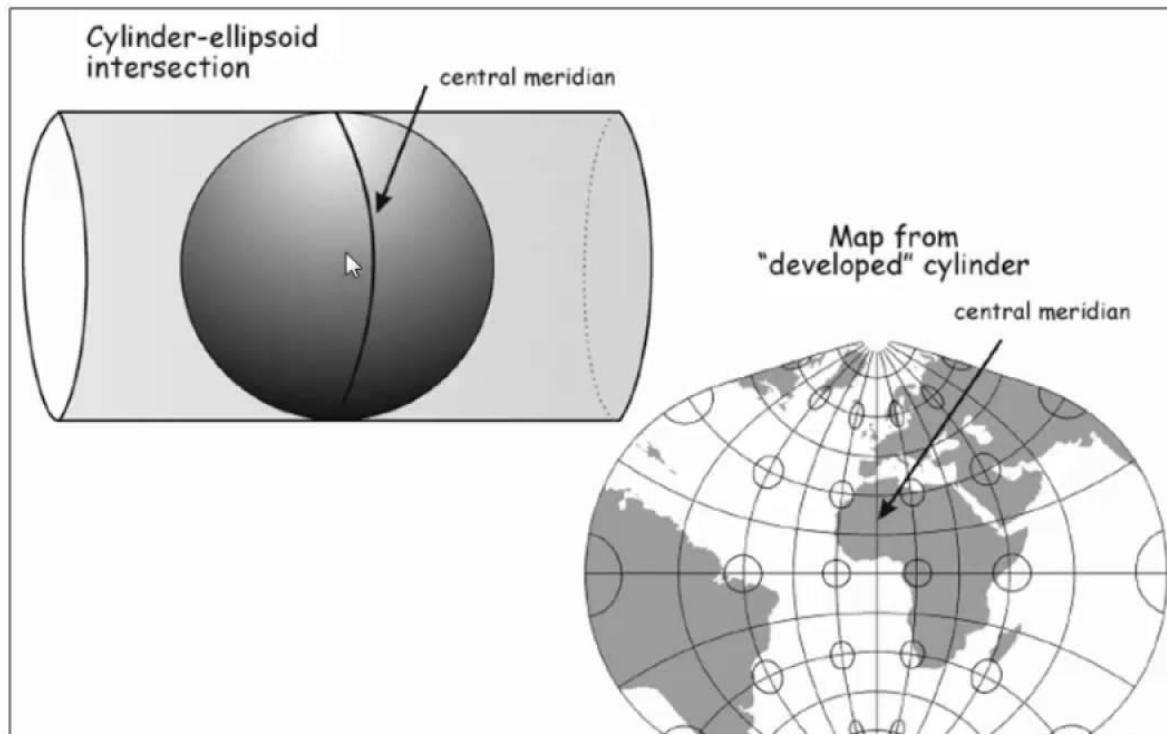
oblique

■ Two main projection families:

- UTM : Universal Traverse Mercator Projection
- Lambert : Conformal Conic Projection

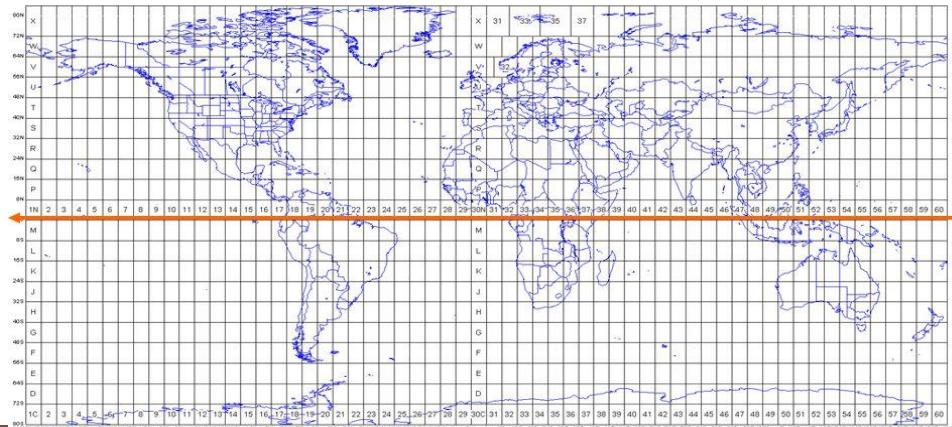
©IGN

-Unroll cylinder to make flat map



uses a “flat earth,” model and is own below.

The X axis is the Equator, and there is a different Y axis for each zone.





Converting image positions to cartographic coordinates

■ Product levels

- Level 1 or 2 (depend on the data provider) for georeferenced data

■ Softwares for data conversion

- GDAL, NEST (ESA)
- May need a Digital Terrain Model
- Chosen geoid is often IAG GRS 80 with terrestrial reference system WGS84

Overview of the course

- Short history of remote sensing
- Satellites and orbits
- Imaging systems
- Applications



Remote sensing applications

ATMOSPHERE



Clouds and movements,
temperature, water content,
composition
Meteo, climate change, pollution

OCEAN

Temperature, color, tides, sea levels,
ice sheets and movements
Ocean survey, climate change, pollution

LAND

Urban and land use, topography
Emergency response, land or urban mapping and monitoring



LAND applications

■ Environmental applications

- Vegetation and hydrology survey
- Agriculture monitoring
- Urban monitoring
- Snow / glacier monitoring
- DTM / DSM

■ Security applications

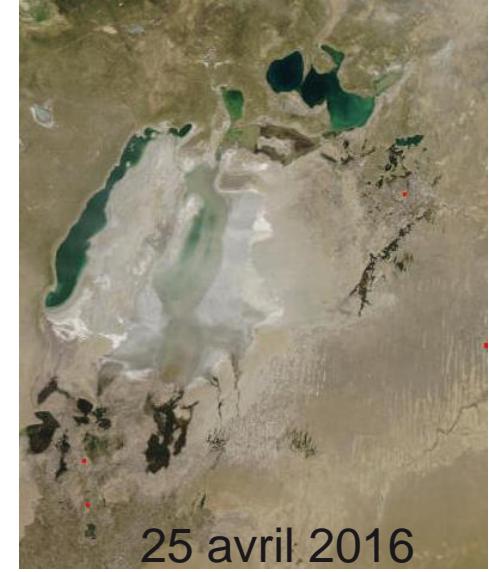
- Ground movement monitoring
- Disaster management

■ Defense applications

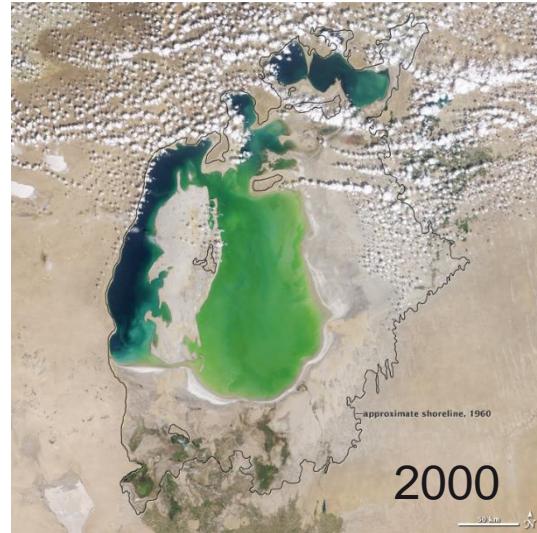
- Land survey
- Activity area detection



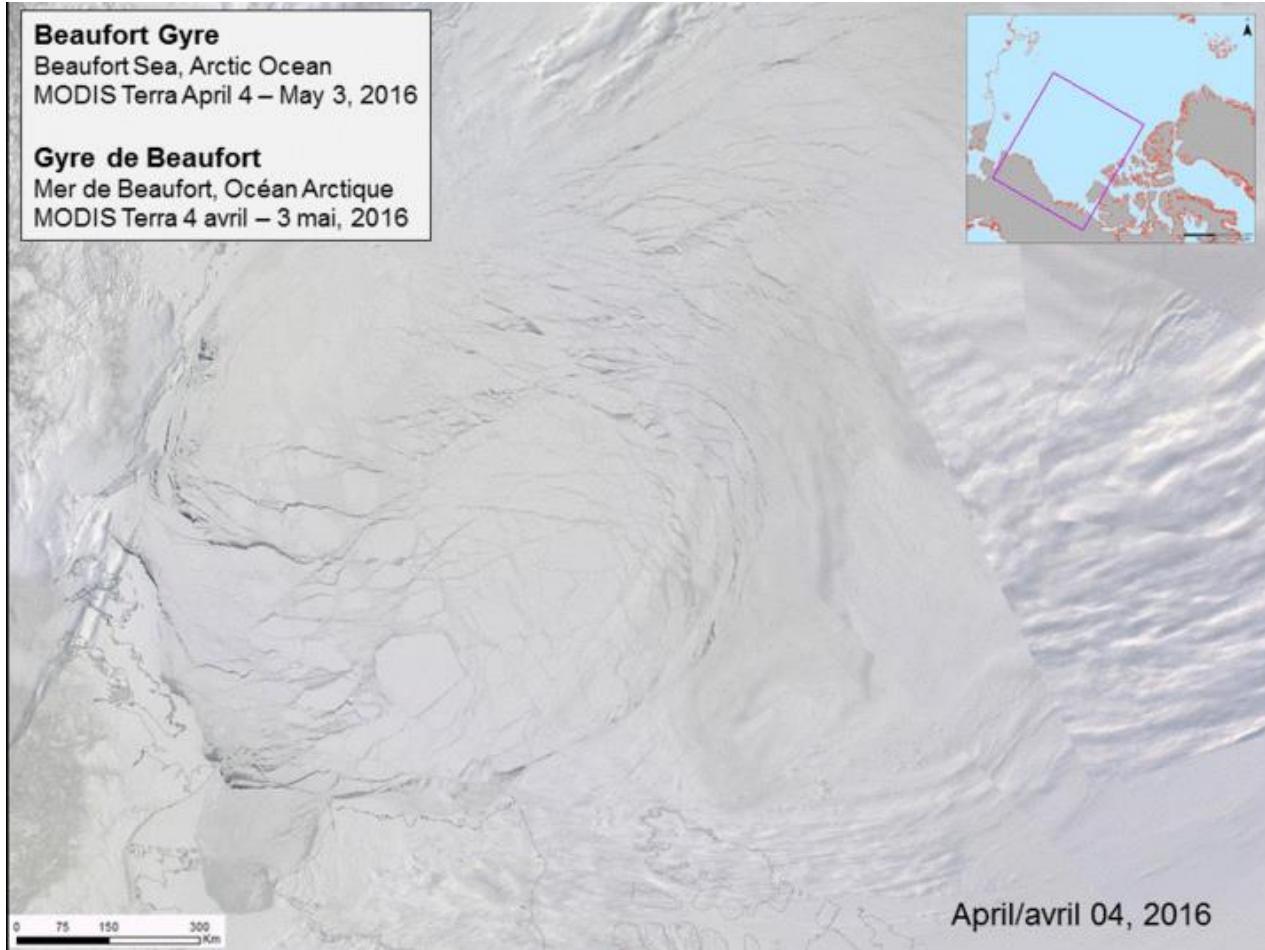
Environment monitoring



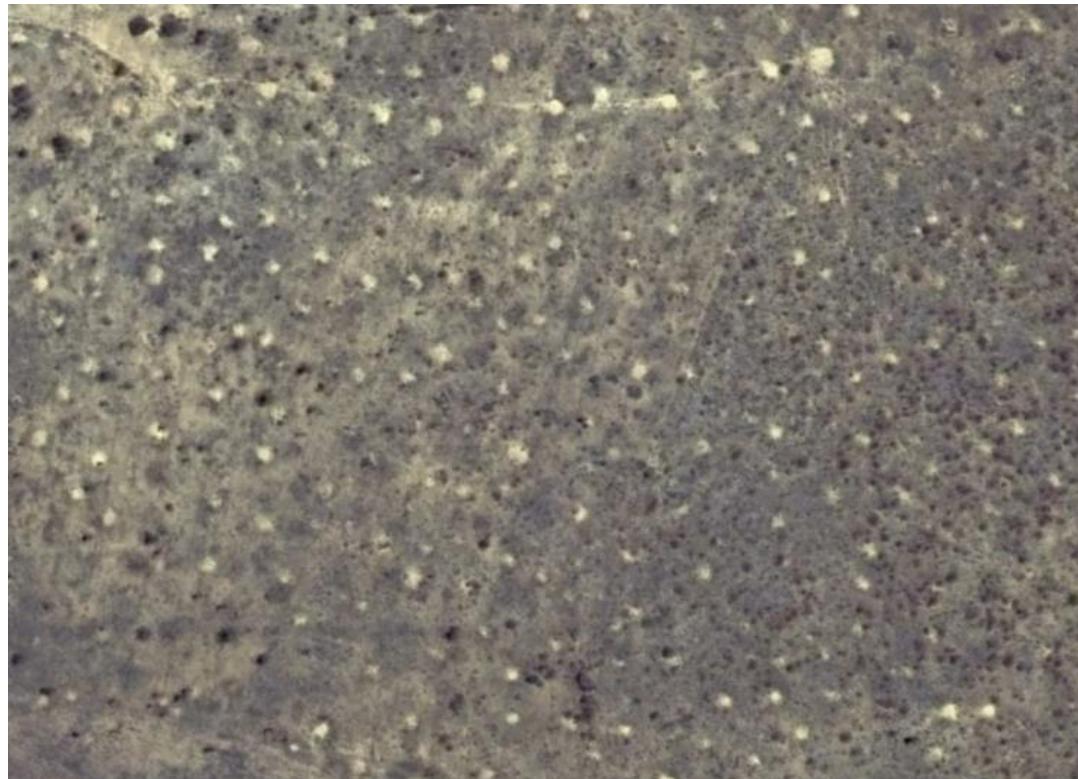
↔
50 km



Gyre of Beaufort, Terra satellite between 4/04/2016 and 3/05/2016



Regional analysis, metric optic images Termite's mount in Brazil

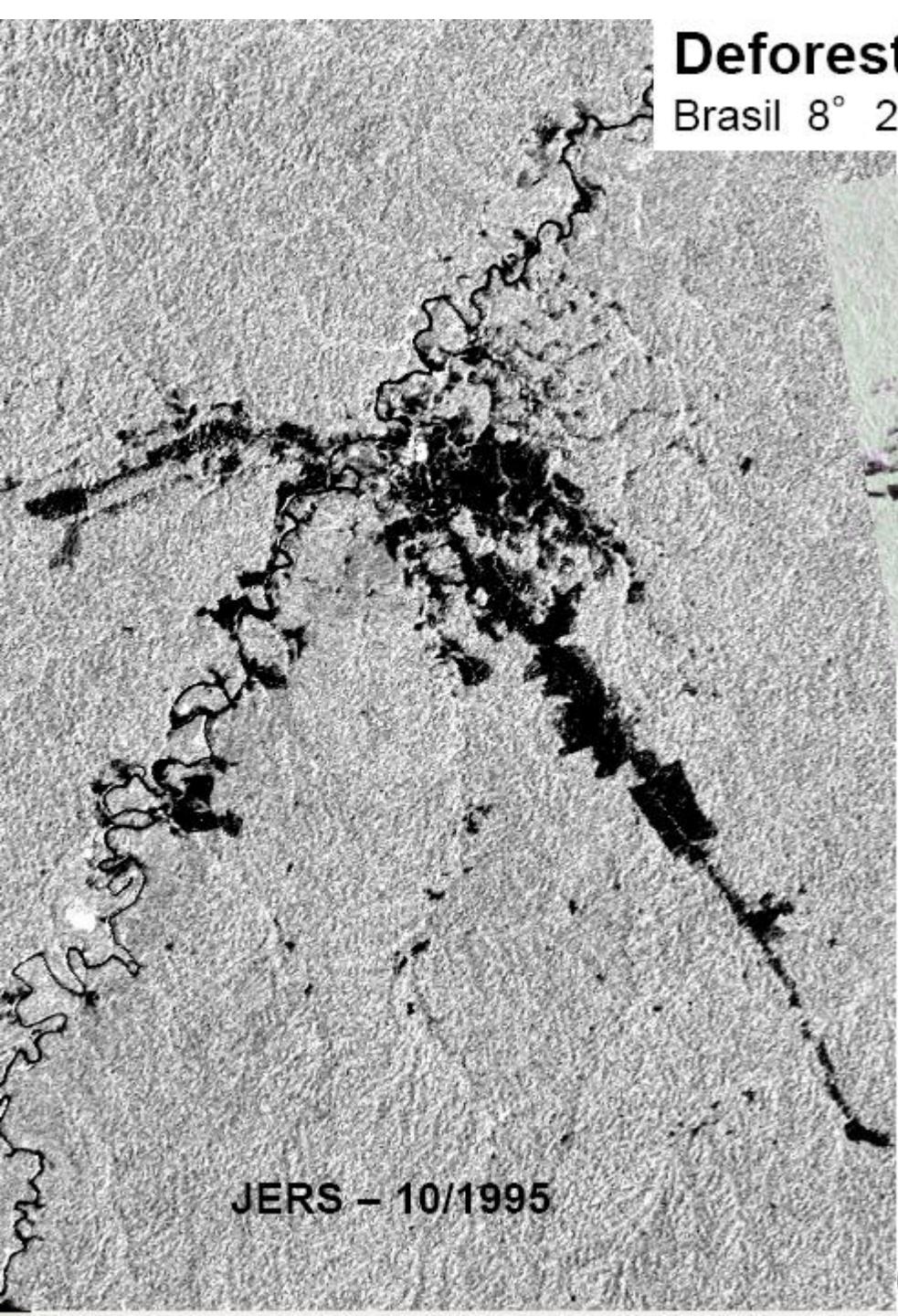


~1 km²

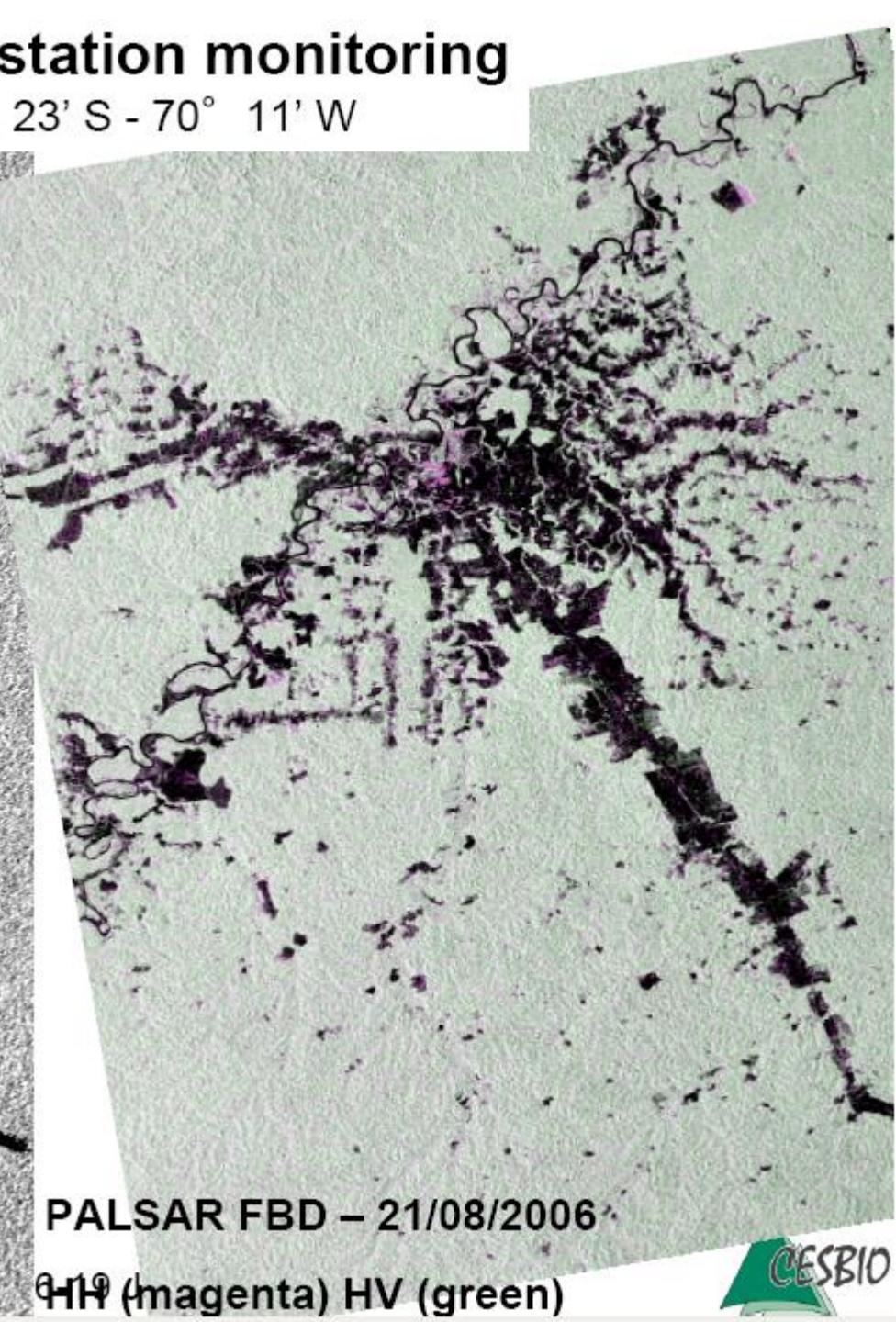
- Total area: 230 000 km² (~Great Britain)

Deforestation monitoring

Brasil 8° 23' S - 70° 11' W



JERS – 10/1995



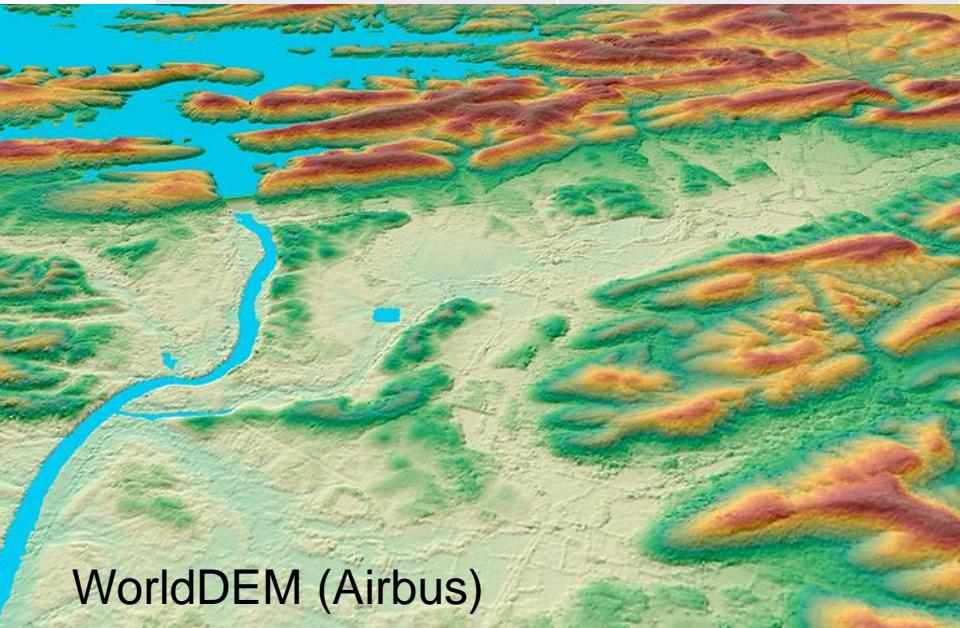
PALSAR FBD – 21/08/2006

HH (magenta) HV (green)

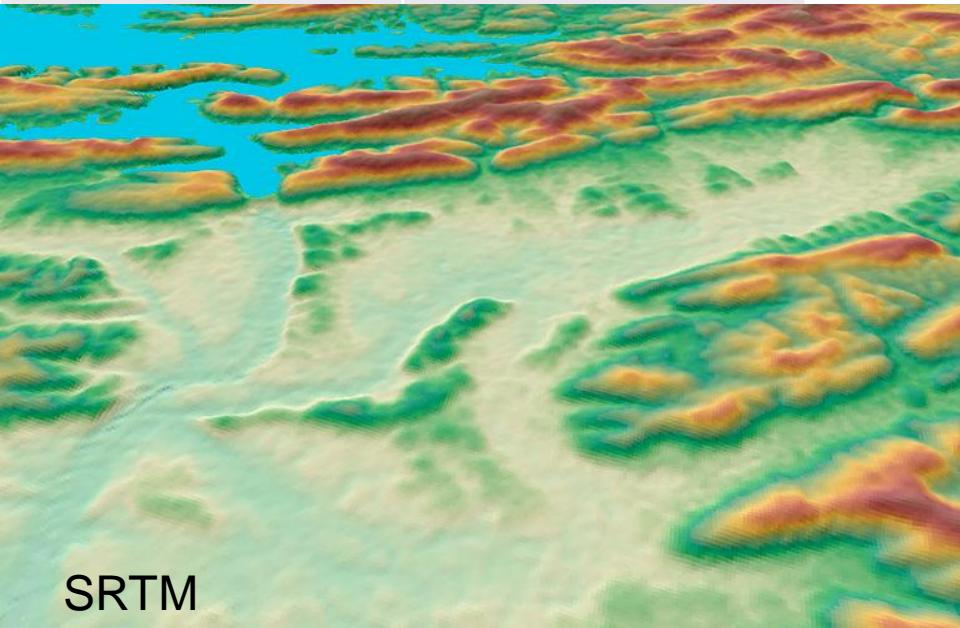


Reconstruction 3D - MNT

Mission	mode	Planimetric accuracy	Altimetric accuracy
SRTM (2000)	Bande X Single-pass interferometry	60m (30m)	16m abs. 10m rel.
TanDEM-X WorldDEM	Single-pass + mult-pass interferometry	12m	4m abs. 2m rel.



WorldDEM (Airbus)



SRTM

Subsidences by radar interferometry: ERS-1

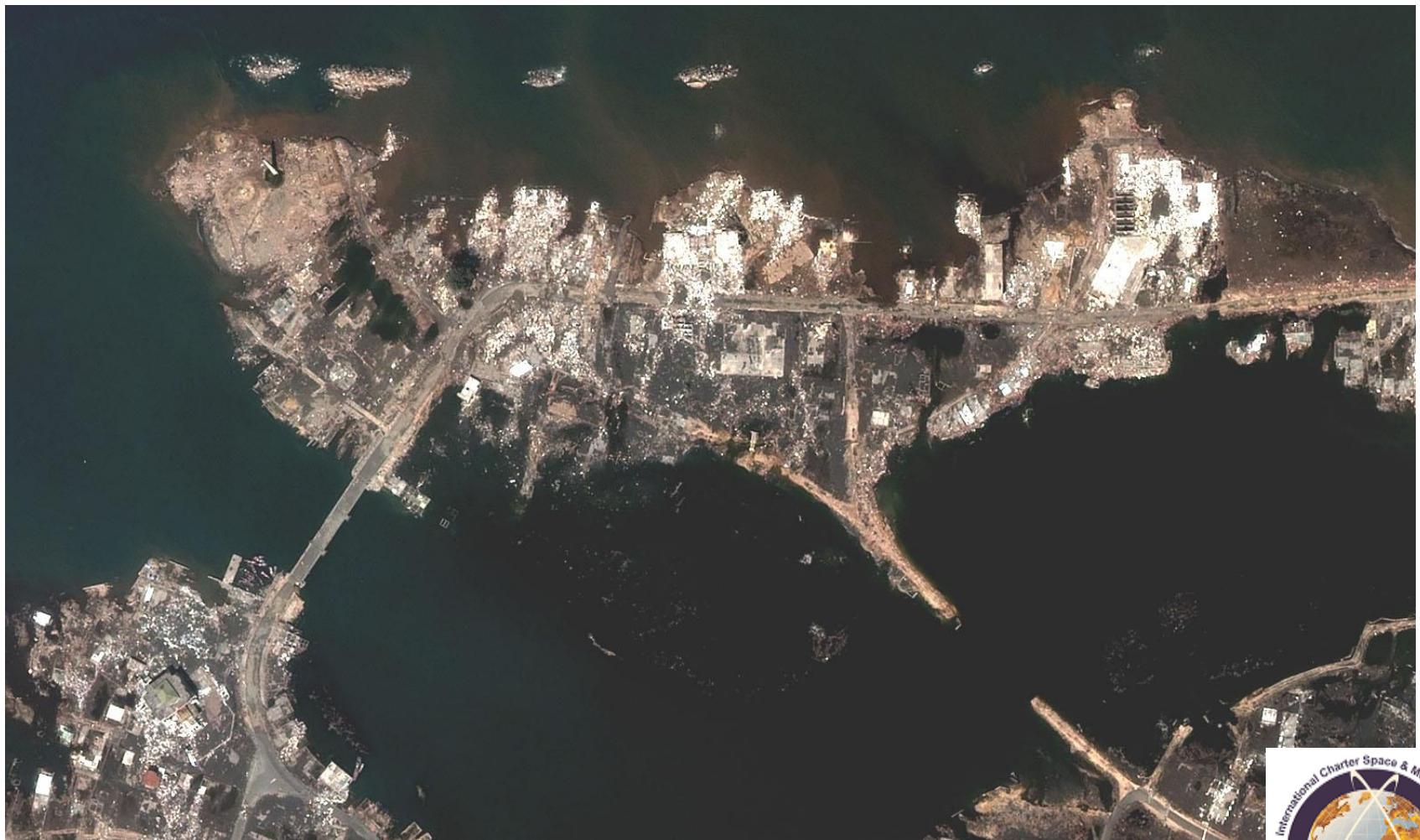


Pomona subsidence: animation of Politecnico di Milano

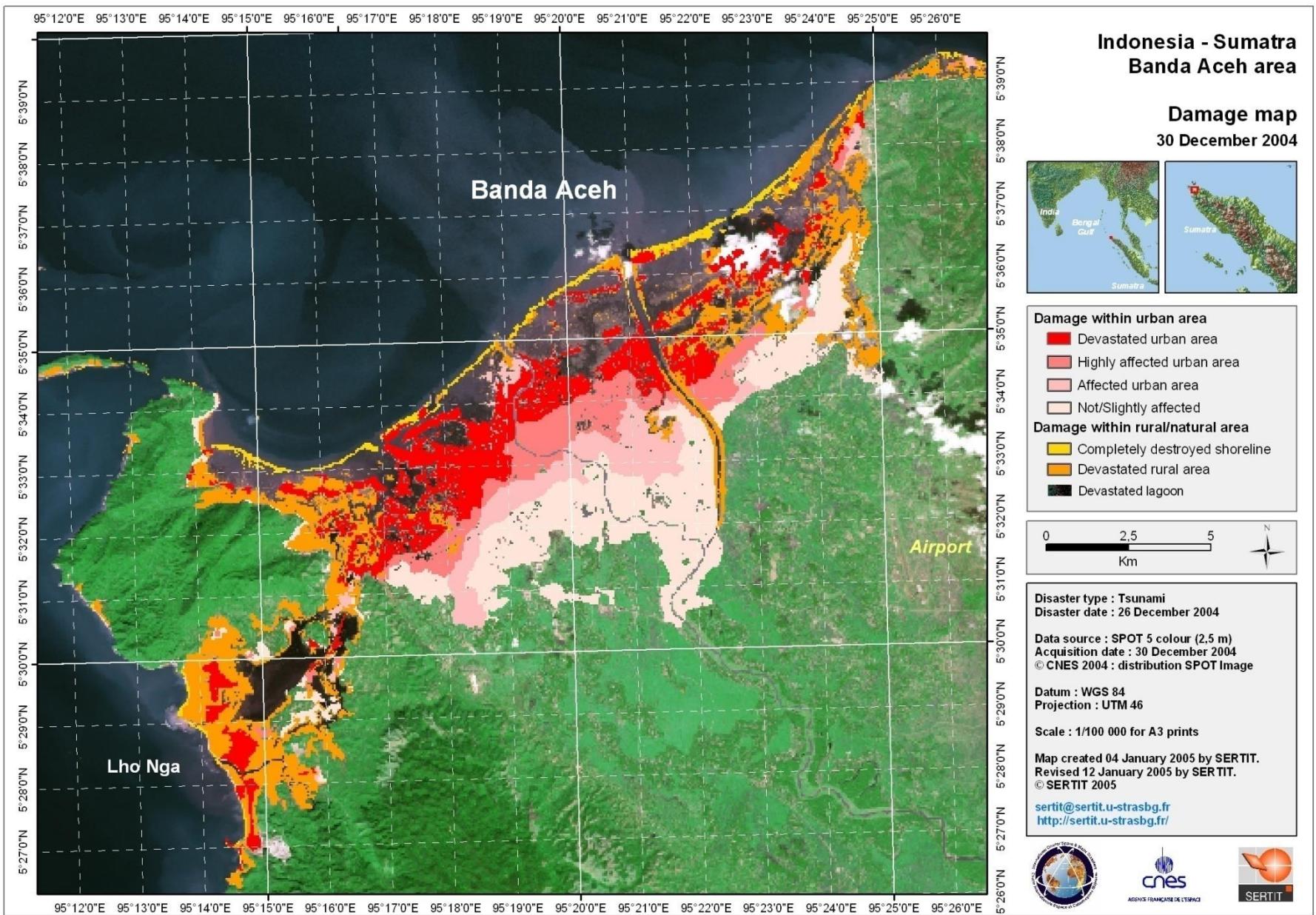
Banda Aceh, summer 2004



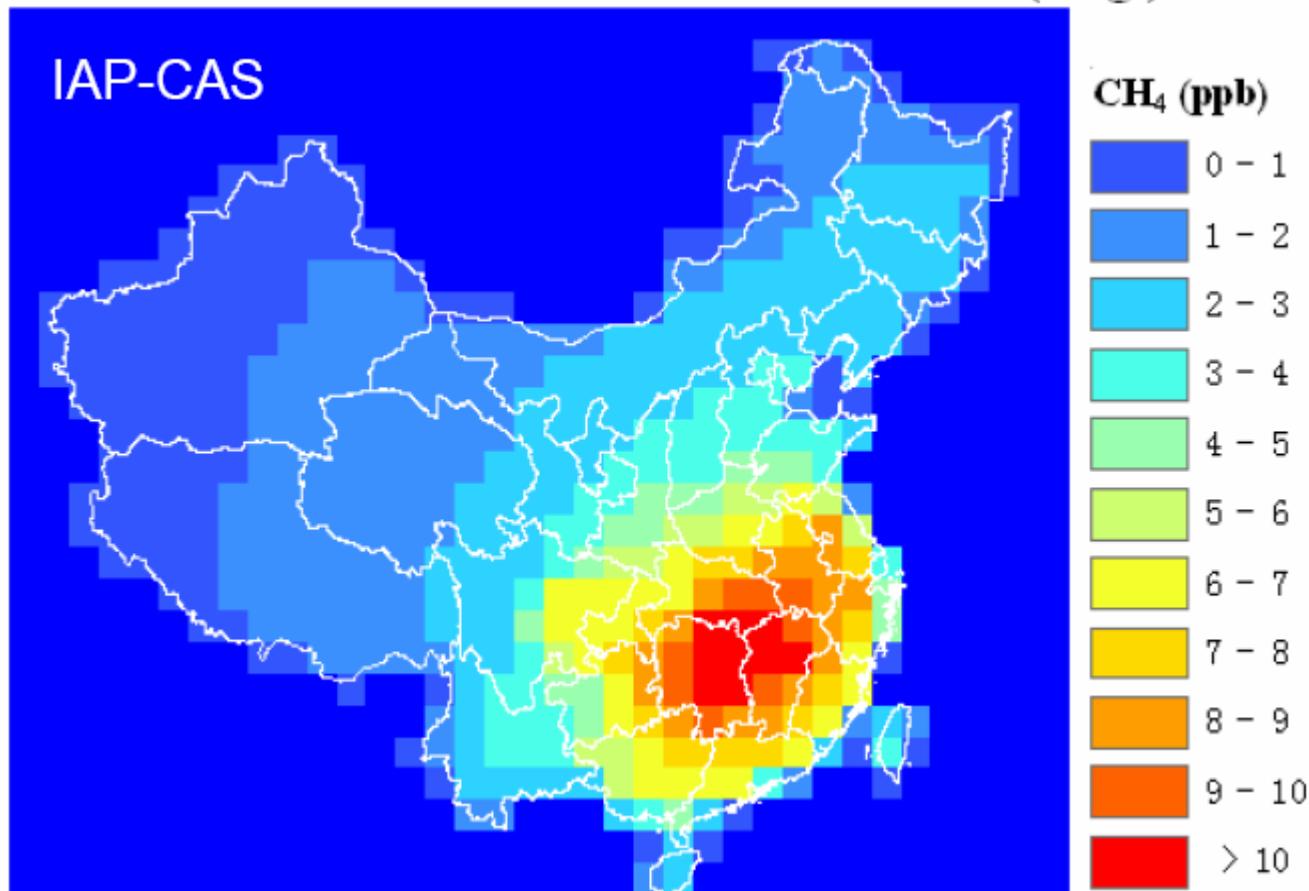
Banda Aceh le 28 décembre 2004



International charter: Space and Major Disasters (17 space agencies, free data)



Methane map on China Linked to rice production





OCEAN applications

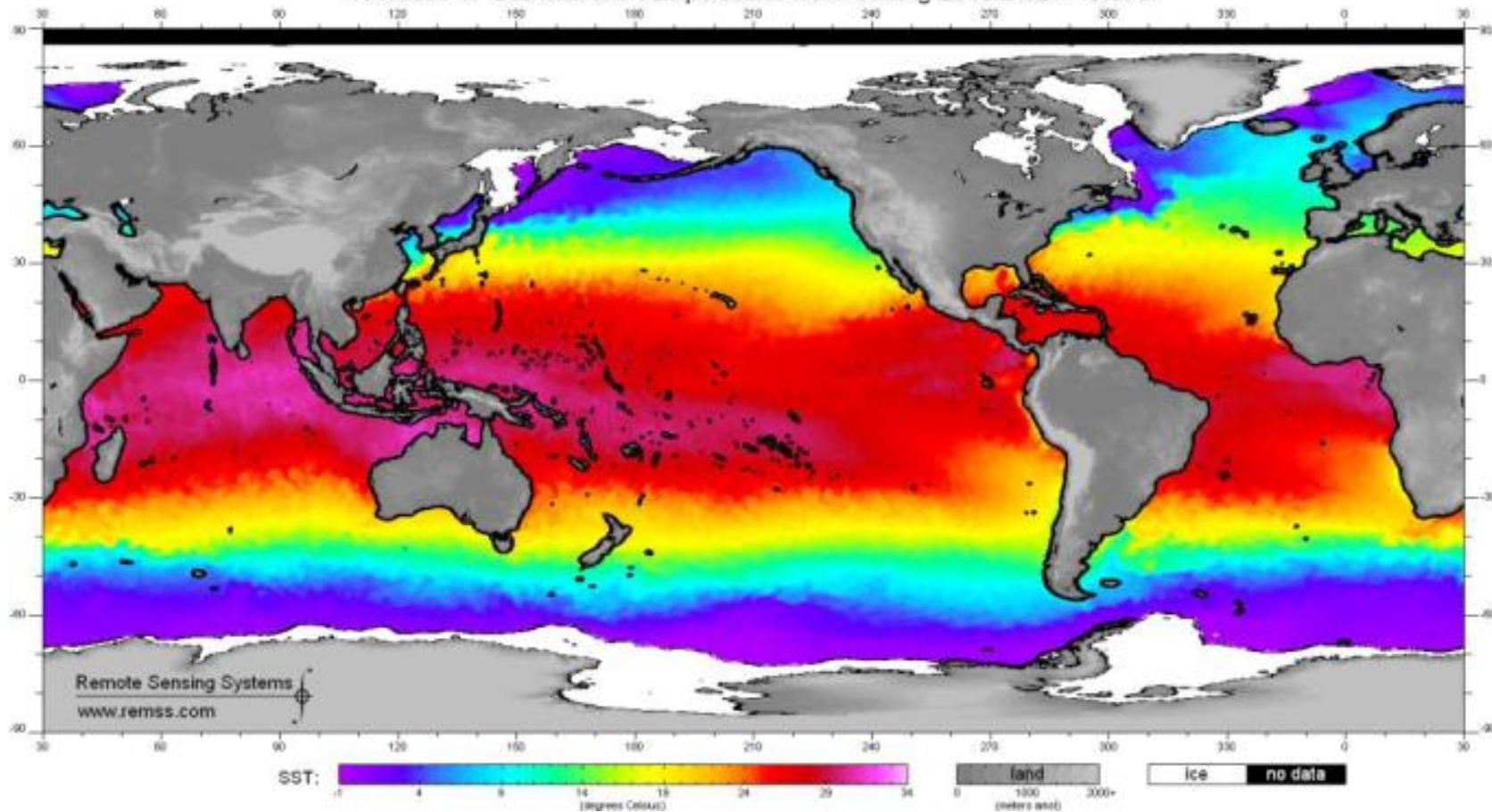
■ Ocean survey

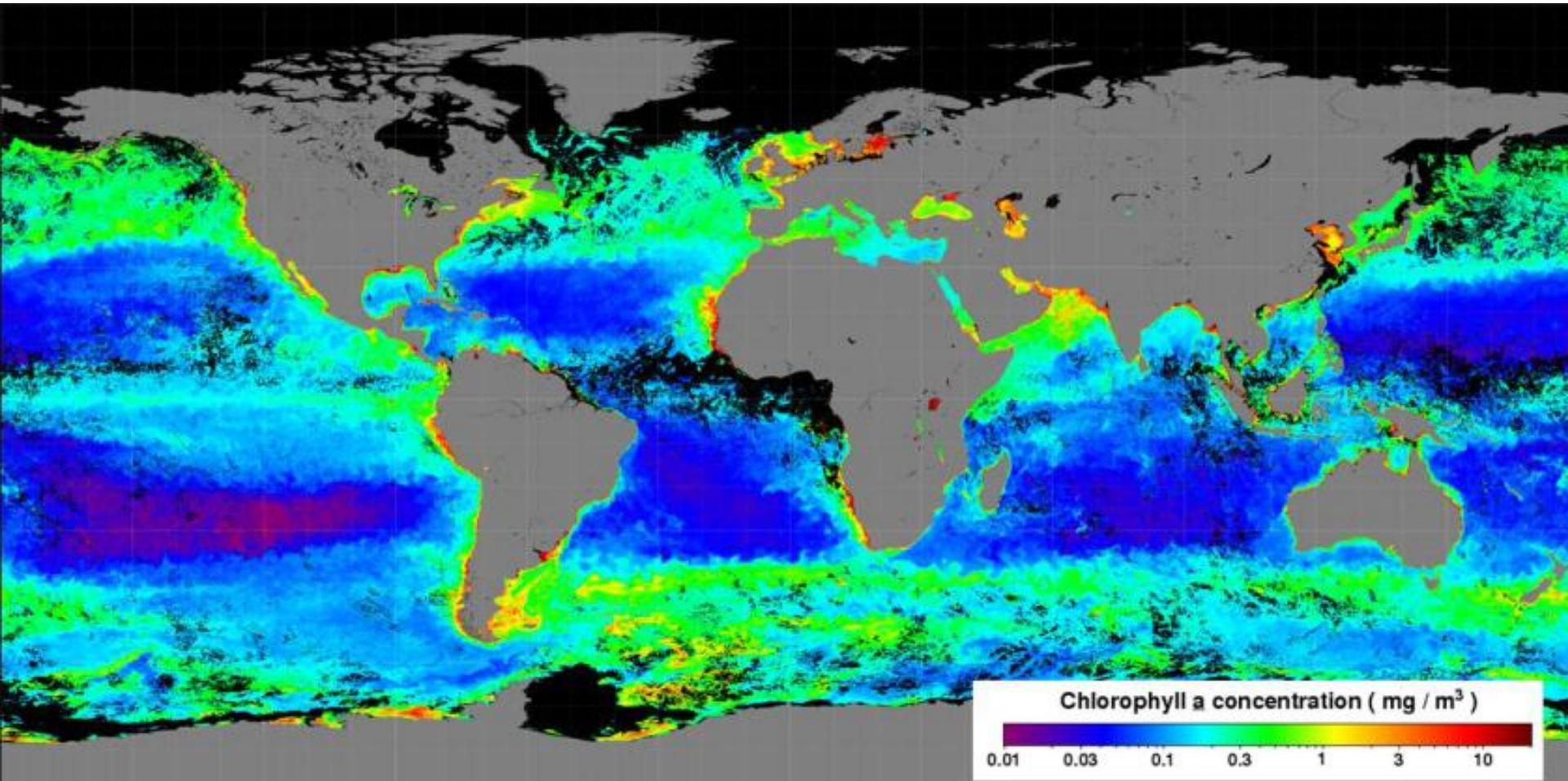
- temperature
- color
- tides,
- sea levels

Ocean survey, climate change, pollution

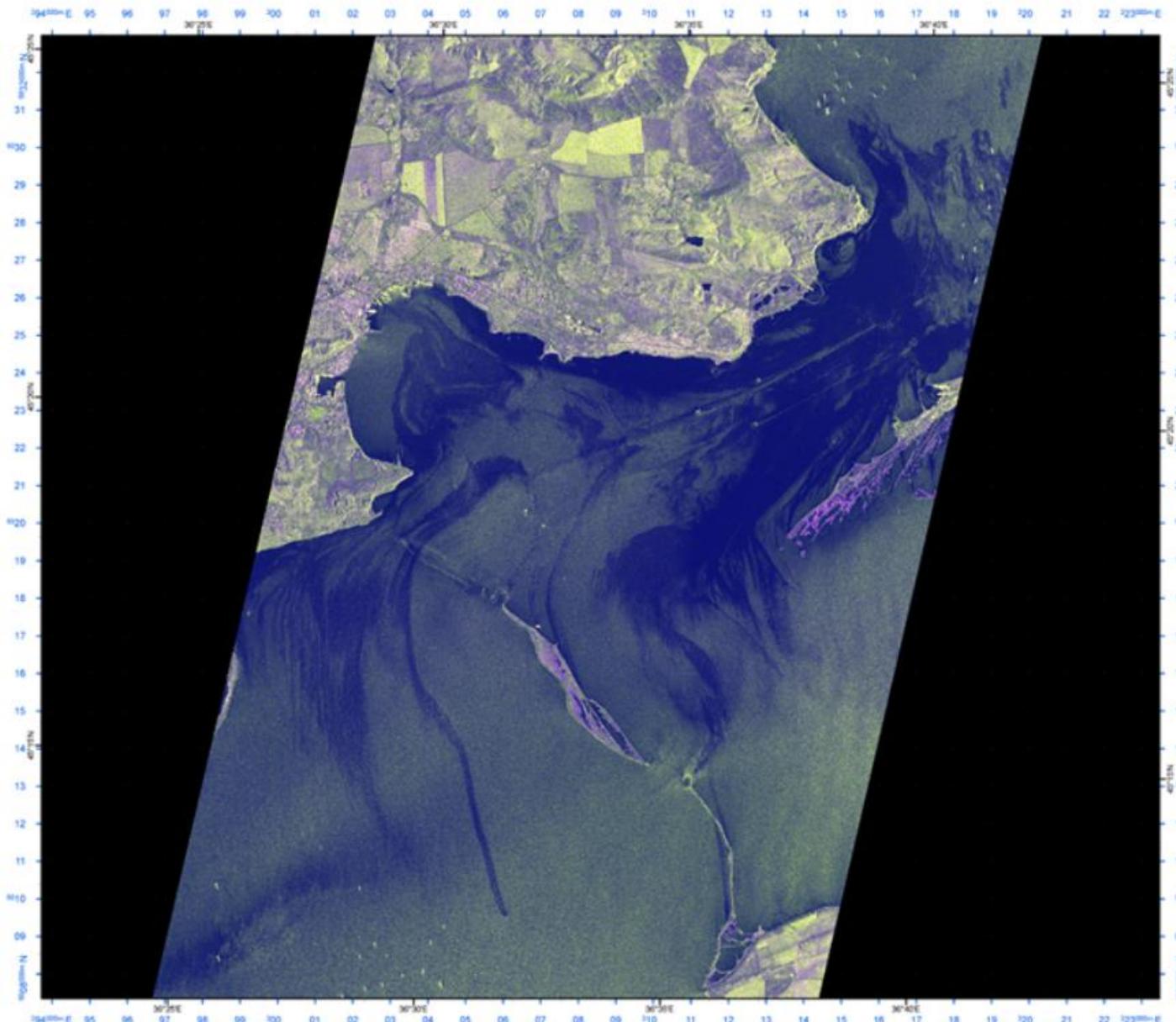


WindSat v7 Sea Surface Temperature: week ending 2013/03/23 - Global





Eastern Crimea (Ukraine) - Oil Spills



TerraSAR-X StripMap Acquisition

Location of Crimea:



Satellite Information

Satellite: TerraSAR-X
 Imaging Mode: StripMap
 Slant Range Res.: 3m
 Polarisation: HH+VV
 Pass Direction: Descending
 Acquisition Date: 2007-11-16, 03:52:06 to 03:52:14 UTC
 Product Type: Geocoded Ellipsoid Corrected
 Resolution Mode: Spectrally Enhanced



Map Projection
 Geographic: Universal Transverse Mercator
 Ellipsoid: WGS 84
 Datum: WGS 84
 Zone: 37N



DE LA TERRE AU COSMOS

