

Computer Architecture: exam

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You can use any document but communicating devices are strictly forbidden. Please number the different pages of your paper and indicate on each page your first and last names. You can write your answers in French or in English, as you wish. Precede your answers with the question's number. If some information or hypotheses are missing to answer a question, add them. If you consider a question as absurd and thus decide to not answer, explain why. If you do not have time to answer a question but know how to, briefly explain your ideas. Note: copying verbatim the slides of the lectures or any other provided material is not considered as a valid answer. Advice: quickly go through the document and answer the easy parts first.

1 CMOS logic (4 points)

The **foo** logic gate has 3 inputs **A**, **B** and **C**, one output **X**, and its CMOS schematic is represented on Figure 1.

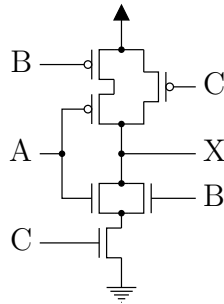


Figure 1: The **foo** logic gate

1. Write its truth table, that is, a table in which you give the value of the output for each combination of the inputs.
2. Write the boolean equation of the **X** output of **foo** using the **NOT**, **AND** and **OR** operators and parentheses. Do not assume any precedence between the boolean operators, use parentheses to make your equation non ambiguous. Example (of course this is not the correct answer): $X = ((A \text{ AND } (\text{NOT } (C \text{ OR } B))) \text{ OR } (C \text{ AND } A))$.
3. When assembling logic gates to design a circuit it is convenient to use graphical symbols instead of the CMOS schematics. You already know the

graphical symbols of several logic gates (inverter, 2-inputs NAND, 2-inputs NOR, 2-inputs AND...) Imagine a graphical symbol for the **foo** logic gate and draw it.

2 Binary representation of numbers (4 points)

There are several ways to represent signed integers using bits. In computer systems, the two most frequently encountered are *sign and magnitude* and *two's complement*. In the following we denote $a_{n-1}a_{n-2}\dots a_1a_0$ the n -bits representation of integer A . In both representations a_0 is the *Least Significant Bit* (LSB). In *sign and magnitude* a_{n-1} is the *sign* bit. In *two's complement* a_{n-1} is the *Most Significant Bit* (MSB) and has negative weight.

1. Consider integer values 56, 28 and -61 (in base 10). We want to represent these 3 values in base 2 using the *sign and magnitude* representation, on the **same** number m of bits (sign bit **included**). What is the minimum value of m (only **one** answer expected)?
2. Consider integer values 56, 28 and -61 (in base 10). Represent them in m -bits *sign and magnitude* (where m is your **unique** answer to the preceding question).
3. A p -bits adder is a hardware device that takes two p -bits inputs, adds them as if they were unsigned integers, and outputs the $p + 1$ -bits result. Example: if $p = 3$ and the inputs are 101 (5 in base 10) and 011 (3 in base 10), a 3-bits adder outputs 1000 (8 in base 10). Suppose that we consider the two inputs of a p -bits adder not as unsigned but as signed in *two's complement* representation. Is the output of the p -bits adder always the correct *two's complement* representation of their sum? If yes, explain why. If not, explain why and propose a way to fix the output of the p -bits adder such that it becomes the correct *two's complement* representation of the sum.
4. What is the pentadecimal (base 15, digits 0, 1, 2, ..., 9, A, B, C, D, E) representation of decimal value 407?
5. Consider integer values 56, 28 and -61 (in base 10). We want to represent these 3 values in base 2 using the *two's complement* representation, on the **same** number n of bits. What is the minimum value of n (only **one** answer expected)?
6. Consider integer values 56, 28 and -61 (in base 10). Represent them in n -bits *two's complement* (where n is your **unique** answer to the preceding question).

3 Branch prediction (4 points)

A processor implements the RV32I Instruction Set Architecture (RISC-V, 32 bits, no extension). It is equipped with a branch prediction unit based on the Variant of the Saturating Counter (VSC) branch predictor which diagram is represented on Figure 2.

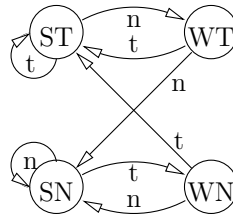


Figure 2: Variant of saturating counter branch predictor

ST, **WT**, **WN** and **SN** represent *Strong Taken*, *Weak Taken*, *Weak Not taken* and *Strong Not taken*, respectively. The transition labels **t** and **n** represent the actual branch outcomes *taken* and *not taken*, respectively. The VSC branch predictor predicts *taken* when it is in states **ST** or **WT** and *not taken* when it is in states **SN** or **WN**.

Consider the following function written in RV32I assembly code (with pseudo-instructions):

```

1 hw:
2   mv    t4, a0           # t4 ← a0
3   mv    a0, zero         # a0 ← 0
4   loop:
5     andi t5, t4, 1       # t5 ← t4 AND 1
6     add  a0, a0, t5     # a0 ← a0 + t5
7     srl  t4, t4, 1       # t4 ← t4 >> 1
8     bne  t4, zero, loop  # if t4 != 0 goto loop
9     ret                    # return
  
```

The **hw** function takes one single 32-bits argument in register **a0** and returns one single result in register **a0**.

1. Explain what the **hw** function does.
2. Assume our processor executes the **hw** function and a VSC branch predictor is used to predict the outcome of the **bne** branch instruction (Line 8). Assume also that the VSC branch predictor is in the **ST** state when entering the function. Calculate the Misspredictions Per Branch Instruction (MPBI)¹ of the VSC branch predictor at the end of the **hw** function. Warning: this depends on the value in register **a0** when the function is called; consider all cases.

4 Caches (4 points)

Definitions and notations

- The **breakdown** of a data structure is the partitioning of the data structure in separate fields.

¹The MPBI is the ratio of the number of times the branch instruction was wrongly predicted over the total number of times it was executed. It is a real number between 0 and 1; 0: excellent, 1: catastrophic.

- *Extra cache information*: control and management information stored in the cache (tags, flags, replacement policy information...)
- *Net cache data*: copies of memory data stored in the cache, that is, everything except *extra cache information*.

Questions

We consider a 64-bits computer system with 48 bits byte addresses and 64-bits addressing units (that we call double-words in the following). The computer is equipped with a **write-through** data cache, 5-ways set associative and 8 double-words per line. The total size of the **net cache data** of 327680 bytes. Ignore the replacement policy.

1. What is the breakdown of a 48-bits address? For each field specify its bit-width, the indexes of its leftmost and rightmost bits, and explain what its role is. Number the bits as usual: bit 0 is the Least Significant Bit (LSB) and bit 47 is the Most Significant Bit (MSB).
Example: *Bits 12 ... 7 (6 bits): this field blah blah ...*
2. What is the breakdown of a cache entry? For each field specify its bit-width and explain what its role is.
3. What is the **total** size of the cache (*extra cache information plus net cache data*)?

5 RISC-V 5-stages pipeline (4 points)

A processor implements the RV32I Instruction Set Architecture (RISC-V, 32 bits, no extension). It has the same 5-stages pipelined architecture as seen in class (Fetch, Decode, Execute, Memory, Write-back).

Consider the following **clz** function written in RV32I assembly code without pseudo-instructions:

```

1 clz :
2   lw      t0,0(a0)          # t0 <- mem[a0]
3   andi    t1,t0,1           # t1 <- t0 AND 1
4   beq     t1,zero,even      # if t1==0 goto even
5   add     t1,t0,t0          # t1 <- t0+t0
6   add     t0,t0,t1           # t0 <- t0+t1
7   addi    t0,t0,1           # t0 <- t0+1
8 even :
9   srli    t0,t0,1           # t0 <- t0>>1
10  sw      t0,0(a0)          # mem[a0] <- t0
11  jalr    zero,0(ra)        # return

```

We run it on our pipelined processor. We assume that the branch prediction unit predicts the branch and jump instructions perfectly and that all fetched instructions are indeed the ones that should be fetched (no need to kill). If there were no pipeline hazards the total execution time of the function would be 13 clock cycles: during clock cycle number 1 the first instruction would be in Fetch, during clock cycle 9 the last instruction would be in Fetch and during clock cycle 13 it would be in Write-back (that is, 9 instructions plus 4 clock cycles to let

the last instruction leave the pipeline). To measure the performance overhead due to pipeline hazards we use this 13 clock cycles duration as a reference. We say that a pipeline hazard *costs* 3 clock cycles if in order to handle it we use a technique that increases the total execution time by 3 clock cycles.

1. Identify all **data** hazards. For each hazard give the involved register and pair of instructions (use the line numbers).
2. Suppose our pipelined architecture handles the data hazards only with stalls (no bypass logic). How many clock cycles will be added to the reference (13) due to data hazards while executing **clz**? Warning: this depends on the outcome of the **beq** instruction (line 4); answer for each of the two cases.
3. Suppose our pipelined architecture handles the data hazards with stalls and the bypass logic we saw in class (Execute-to-Decode, Memory-to-Decode and Write-back-to-Decode). How many clock cycles will be added to the reference (13) due to data hazards while executing **clz**?