

# Automatic Compiler Backend Generation from Structural Processor Models

Compilation and Embedded Computing Systems Group  
Laboratoire de l'Informatique du Parallélisme  
Ecole Normale Supérieure de Lyon

INRIA

Florian Brandner

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- Description of processor features
  - Programmable hardware device
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  - Assembly syntax, binary encoding
  - Abstract behavior
  - *High-level view*

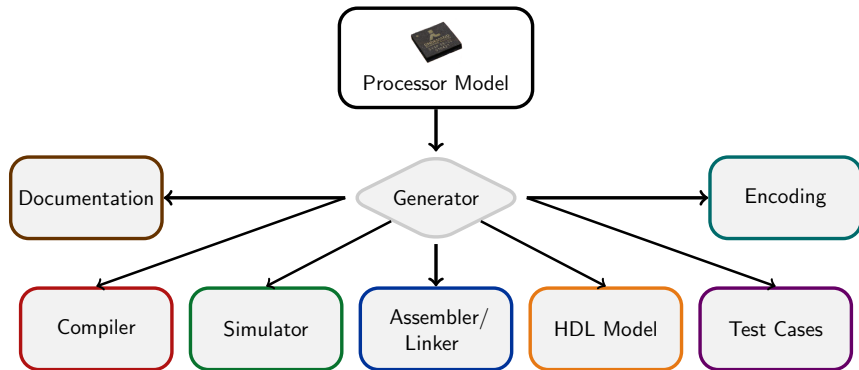
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  - Storage elements such as register files, caches, and memories
  - Wires, buses, and interconnect
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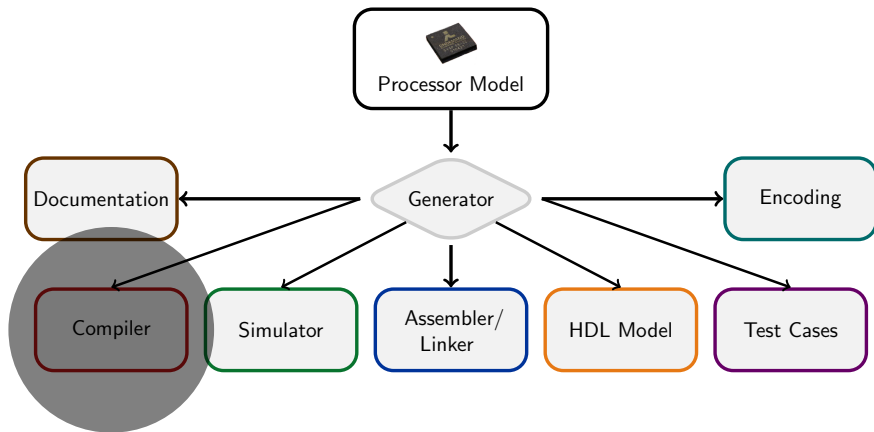
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- Language classification:
  - Behavioral (focusing on the high-level view)
  - Structural (focusing on the low-level view)
  - Mixed (covering both views)

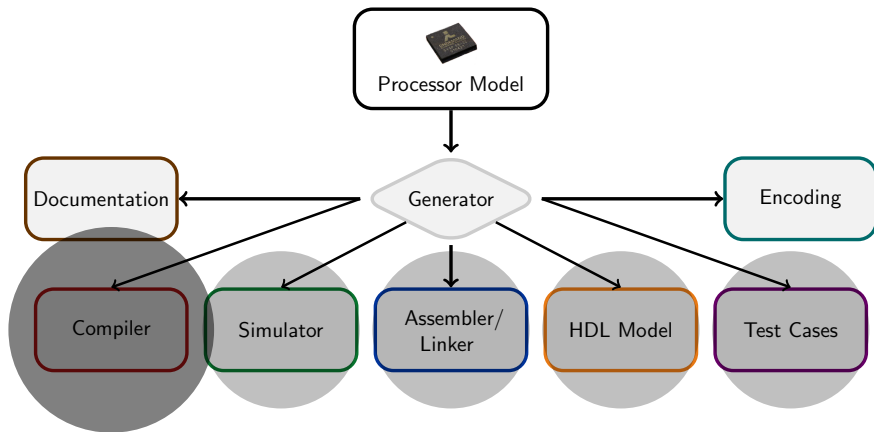
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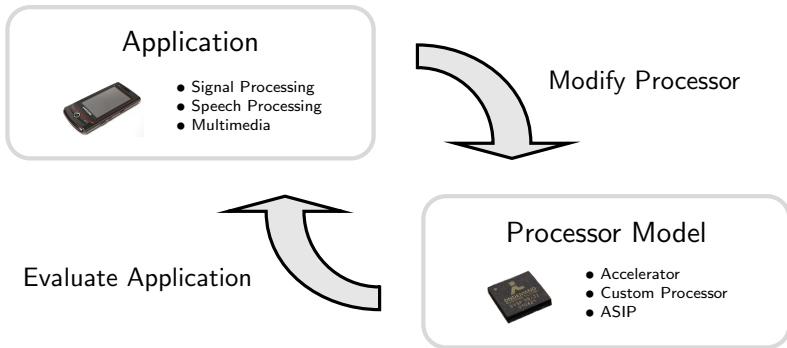


# Application of Processor Description Language





# Design Space Exploration



The ultimate goal is to support seamless Design Space Exploration using automatically generated development tools, simulation tools, automatic testing and verification, as well as hardware generation.

# xADL Processor Description Language

- Structural description of processor features
  - Components interconnected by *links*
    - Functional units, caches, memories, registers
    - Based on extensible types
    - Support for generics
    - Abstractions (bypassing, hazard resolution, pipelining, ...)

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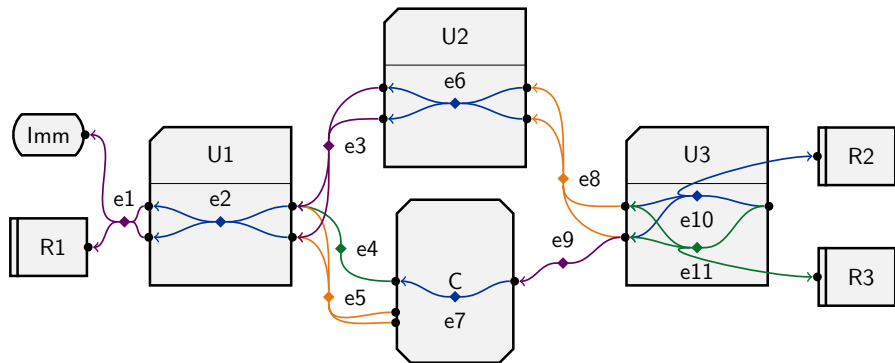
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- Available generator tools:
  - Compiler backend
  - Instruction set simulator
  - GNU binutils (in progress)
  - Instruction decoder
  - Prototype: VHDL model
  - ...

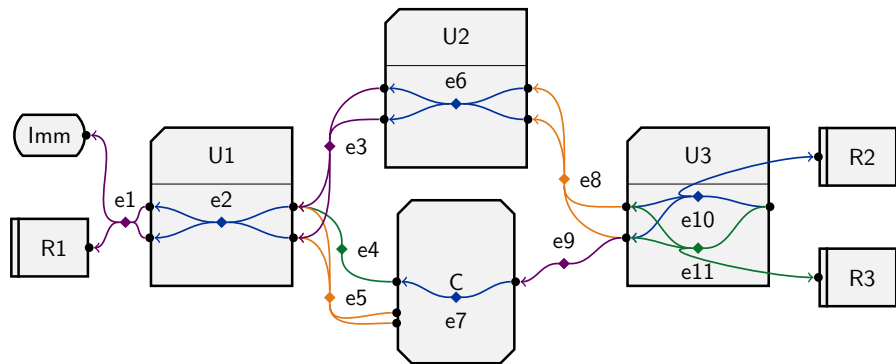
# Hypergraph Representation



Reduced, abstract model of the processor's data path

- Captures flow of instructions through the pipeline
- Legal port assignments expressed by *hyperedges*
- Ignore internal details, bypasses, hazard resolution logic, ...

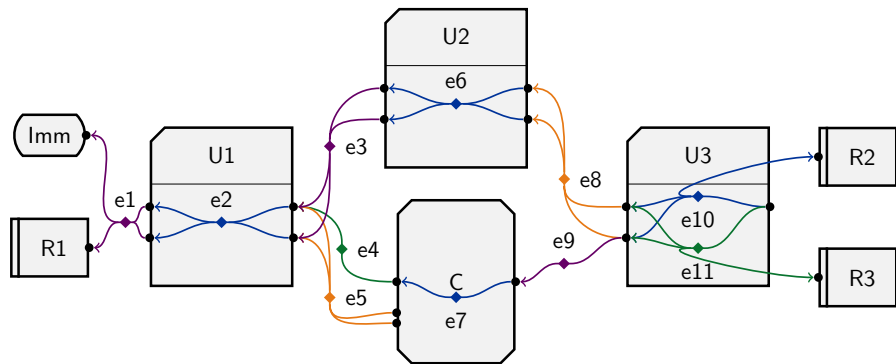
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Discover paths using a backward traversal

- Starting at *endpoints*
- Collect hyperedges until the start of the pipeline is reached

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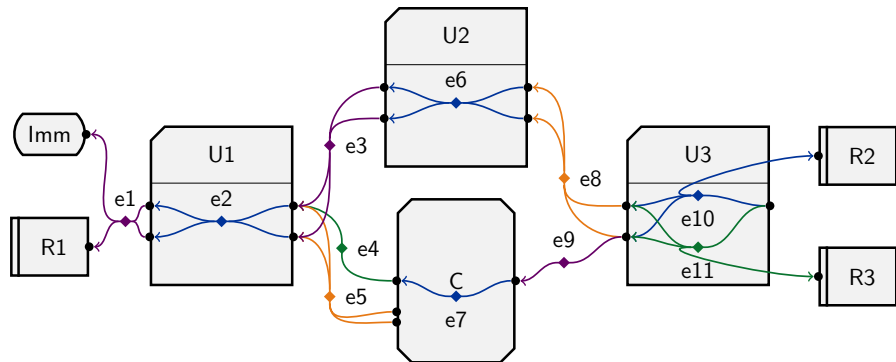


Discover paths using a backward traversal

- Starting at *endpoints* (e5, e10, e11)
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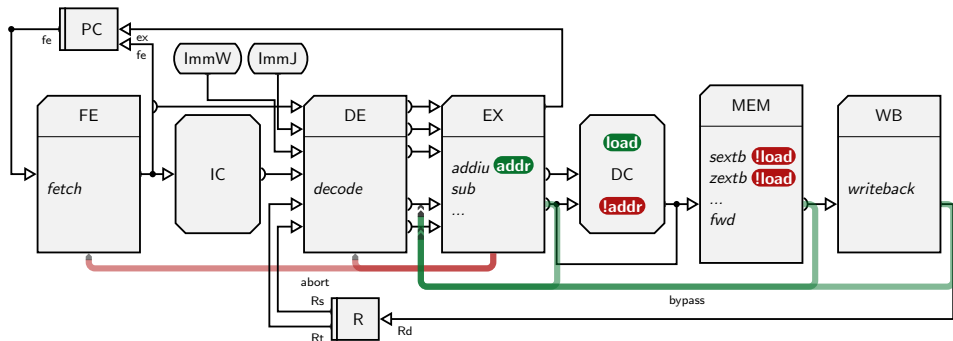
# Hypergraph Representation



Discovered paths:

- {e1, e2, e3, e6, e8, **e10**}
- {e1, e2, e4, e7, e9, **e10**}
- {e1, e2, e3, e6, e8, **e11**}
- {e1, e2, **e5**}

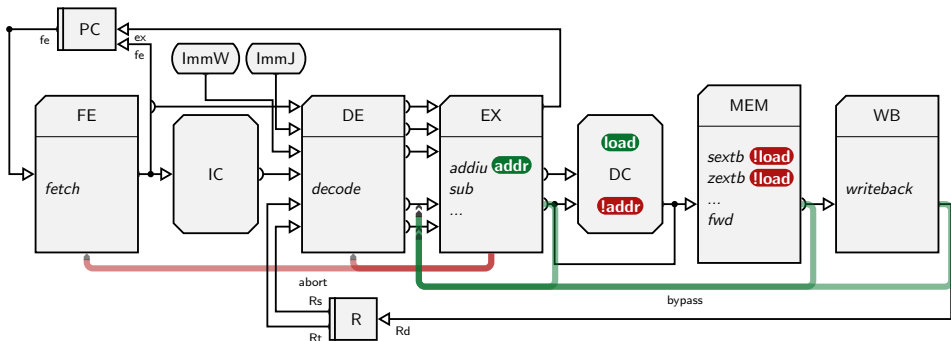
# Example: MIPS Model



## Instruction paths:

- FE:IC:DE:EX:DC:MEM::WB
- FE:IC:DE:EX:MEM::WB
- FE:IC:DE:EX
- ...

# Example: MIPS Model



## Instructions:

- FE:fetch IC DE:decode EX:ori MEM:fwd WB:writeback
- FE:fetch IC DE:decode EX:addiu MEM:fwd WB:writeback
- FE:fetch IC DE:decode EX:addiu DC MEM:zxtb WB:writeback
- ...

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Instructions are derived from paths:

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- Serialize operations
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  - Micro-operations have well-defined semantics
  - Limited control flow in behavioral model

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  - Micro-operations have well-defined semantics
  - Limited control flow in behavioral model
- Enrich the instruction model
  - Annotate with timing information
  - Information on data hazards, stalls, and bypasses
  - Analyze branching and memory access patterns

## Example: *or immediate* instruction

	FE::pc_i = <b>move</b> (pc::p_fe)	[st: 0, op: fe]
	FE::pc_o = <b>add</b> (FE::pc_i, const_4)	[st: 0, op: fe]
	pc::p_fe = <b>move</b> (FE::pc_o)	[st: 0, op: fe]
	ICache::@read = <b>move</b> (FE::pc_o)	[st: 0]
	ICache::read = <b>read</b> (ICache::@read)	[st: 0]
	<hr/>	
abort on BEX	DE::ImmW_i = <b>move</b> (ImmW)	[st: 1, op: de]
	DE::Rs_i = <b>move</b> (R::Rs[0,31])	[st: 1, op: de]
	DE::IW_i = <b>move</b> (ICache::read)	[st: 1, op: de]
	<b>decode</b> (IW_i)	[st: 1, op: de]
	DE::Rs_o = <b>move</b> (DE::Rs_i)	[st: 1, op: de]
	DE::ImmWu_o = <b>zext</b> (DE::ImmW_i)	[st: 1, op: de]
	<hr/>	
bypasses	EX::ImmWu_i = <b>move</b> (DE::ImmWu_o)	[st: 2, op: ori]
	 EX::Rs_i = <b>move</b> (DE::Rs_o)	[st: 2, op: ori]
	 EX::Rd_o = <b>or</b> (EX::Rs_i, EX::ImmWu_i)	[st: 2, op: ori]
	 MEM::Rd_i = <b>move</b> (EX::Rd_o)	[st: 3, op: fwd]
	 MEM::Rd_o = <b>move</b> (MEM::Rd_i)	[st: 3, op: fwd]
	<hr/>	
	WB::Rd_i = <b>move</b> (MEM::Rd_o)	[st: 4, op: wb]
	 WB::Rd_o = <b>move</b> (WB::Rd_i)	[st: 4, op: wb]
	R::Rd[0,31] = <b>move</b> (WB::Rd_o)	[st: 4, op: wb]



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Derive compiler backend from processor models

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  - Correspond to resource tables for scheduling in LLVM
  - Additional information required for *Operation Tables* in *acc*

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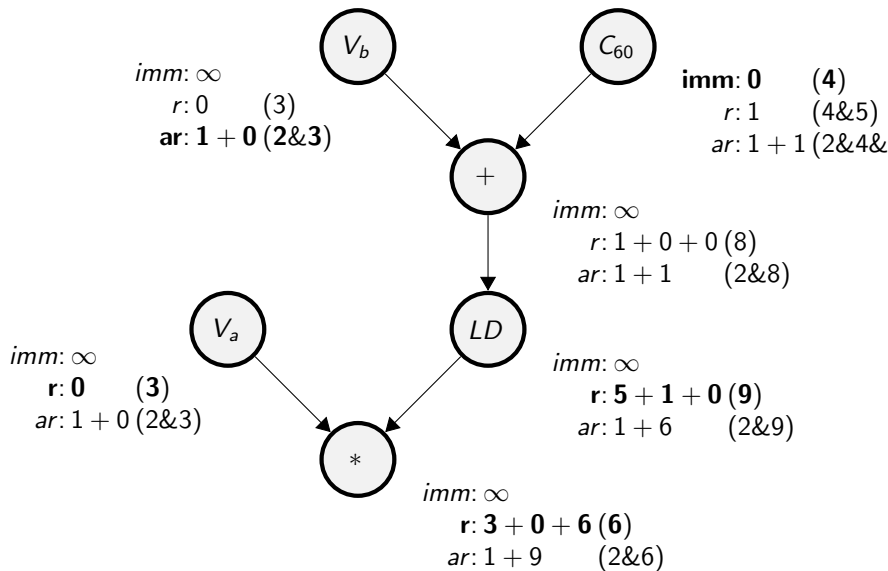
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  - Additional information required for *Operation Tables* in *acc*
- Register allocator
  - Derive register classes from register files/ports

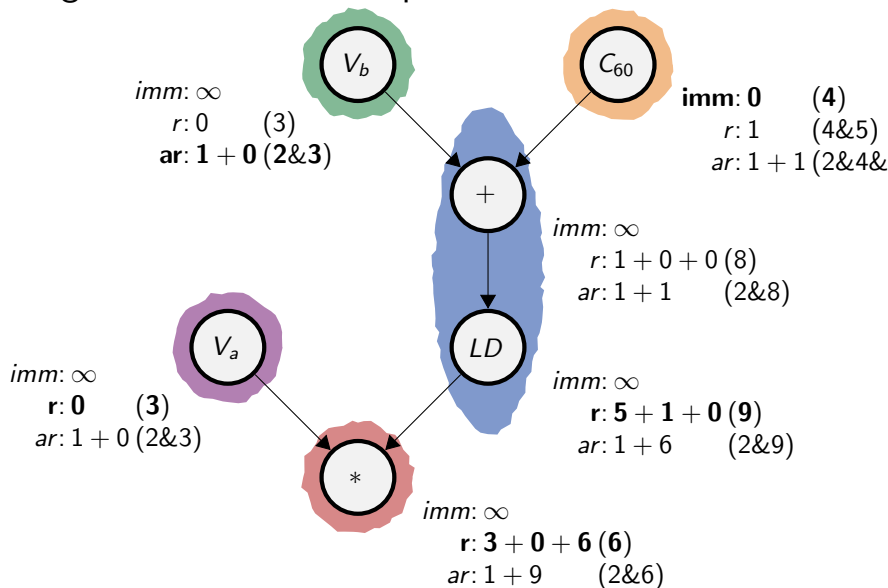
# Instruction Selection using Tree Pattern Matching

Pattern	Cost	Emit
(1) $r \rightarrow ar$	1	mov r = ar
(2) $ar \rightarrow r$	1	mov ar = r
(3) $r \rightarrow \mathbf{V}$	0	V
(4) $imm \rightarrow \mathbf{C}$	0	C
(5) $r \rightarrow imm$	1	ldi r = imm
(6) $r \rightarrow *(r_1, r_2)$	3	mul r = r <sub>1</sub> * r <sub>2</sub>
(7) $r \rightarrow +(r_1, r_2)$	1	add r = r <sub>1</sub> + r <sub>2</sub>
(8) $r \rightarrow +(r_1, imm)$	1	add r = r <sub>1</sub> + imm
(9) $r \rightarrow \mathbf{LD}(+(ar_1, imm))$	5	ld r = [ar <sub>1</sub> + imm]

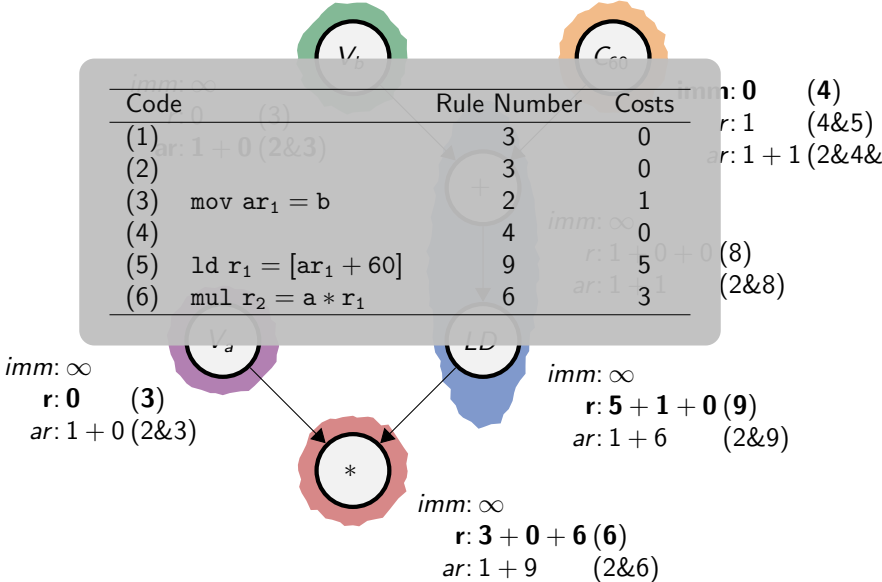
# Covering the Intermediate Representation



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# Cost Functions and Dynamic Checks

## Dynamic cost functions

- The cost of covering a tree fragment can be computed dynamically at compile time
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- May inspect compiler options, the compilation context, or the covered tree fragment
- Usually, specified using code, and is thus hardly analyzable
- What happens when a cost function returns infinity?
  - The rule is effectively disabled
  - We call such cost functions dynamic checks

# Completeness

An instruction selector is said to be complete if:

For every possible input program, accepted by the compiler frontend, a cover of the intermediate representation can be found by the instruction selector.

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  - Check emptiness of  $L_{ir} \cap \overline{L_{is}}$
- **Problem: Dynamic checks cannot be modeled!**

# Representing Dynamic Checks

We need a formalization of conditions:

- Extended tree grammars with conditions
- Associate tree terms with properties
- Conditions modeled as conjunction of simple tests
- Simple tests are modeled as subsets over property domains
- Formally:
  - Domain:  $D_1, \dots, D_n$
  - Properties:  $p = (p_1, \dots, p_n) \in D_1 \times \dots \times D_n$
  - Conditions:  $c = (c_1, \dots, c_n) \in D = \mathcal{P}(D_1) \times \dots \times \mathcal{P}(D_n)$
  - Simple tests:  $c_i$  of a condition
  - Dynamic check:  $\forall i \in \{1, \dots, n\} : \bigwedge p_i \in c_i$



# Example

- Domain

$$\{-\infty, \dots, \infty\} \times \{AR, GPR\} \times \{char, short, int\}$$

- Term with properties

$$\mathbf{CST}(\{60\} \times \{GPR\} \times \{int\})$$

- Rules with conditions

- Unconditional:

$$r \rightarrow \mathbf{CST}(\{-\infty, \dots, \infty\} \times \{AR, GPR\} \times \{char, short, int\})$$

- Unsatisfiable:

$$r \rightarrow \mathbf{CST}(\{-\infty, \dots, \infty\} \times \{AR, GPR\} \times \{\})$$

- Conditional:

$$r \rightarrow \mathbf{CST}(\{0, \dots, 65535\} \times \{GPR\} \times \{short\})$$

# Representing Emit Functions

- Sequence of instructions with *operand bindings*
- Bindings:
  - Fresh virtual register
  - Constant Immediate values
  - Output of another instruction
  - Associate with sub-terms of the tree pattern

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Note: Operand bindings can be used to express non-regular operand constraints, e.g., the equality of nodes in the intermediate representation, using the last kind of bindings.

# Discovering Instruction Selection Patterns

Construct tree patterns during a backward traversal:

- Process the micro-operations of the instruction set model
- Derive pattern, conditions, and bindings
- Additionally: Derive non-terminals, construct conversion rules, special handling of branches and memory operations, ...

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$\mu$ -op.	Tree pattern	Operand Bindings
(6)	$RC\_R\_32 \rightarrow OR(RC\_R\_32, ZEXT_{16}(immediate))$	$(ImmW, \underline{21})$
(7)	$RC\_R\_32 \rightarrow OR(RC\_R\_32, ZEXT_{16}(-))$	$(Rs, \underline{1})$
(11)	$RC\_R\_32 \rightarrow OR(-, ZEXT_{16}(-))$	
(14)	$RC\_R\_32 \rightarrow OR(-, -)$	
(19)	$RC\_R\_32 \rightarrow -$	$(Rd, new\_reg)$

# Extending the Coverage

The computed rule set is typically not complete

- Extend the coverage using *specialization* and *templates*
- Specialization: Eliminate pattern fragments using algebraic laws and special operand bindings
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Tree Pattern	Operand Binding
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(2) $RC\_R\_32 \rightarrow OR(immediate\{0, \dots, 65535\}, RC\_R)$	$(Rs, \underline{2}), (ImmW, \underline{1})$
(3) $RC\_R\_32 \rightarrow immediate\{0, \dots, 65535\}$	$(Rs, 0), (ImmW, \underline{\epsilon})$
(4) $RC\_R\_32 \rightarrow RC\_R\_32$	$(Rs, \underline{\epsilon}), (ImmW, 0)$

# Extending the Coverage

The computed rule

- Extend the coverage
- Specialization laws and specializations
- Templates: Create new patterns by combining existing rules

Note: The extended rule set may still be incomplete, due to restrictions of the instruction set of the target processor, missing specialization and/or template patterns, et cetera.

Tree Pattern	Operand Binding
(1) $RC\_R\_32 \rightarrow OR(RC\_R\_32, immediate\{0, \dots, 65535\})$	$(Rs, \underline{1}), (ImmW, \underline{2})$
(2) $RC\_R\_32 \rightarrow OR(immediate\{0, \dots, 65535\}, RC\_R)$	$(Rs, \underline{2}), (ImmW, \underline{1})$
(3) $RC\_R\_32 \rightarrow immediate\{0, \dots, 65535\}$	$(Rs, 0), (ImmW, \underline{\epsilon})$
(4) $RC\_R\_32 \rightarrow RC\_R\_32$	$(Rs, \underline{\epsilon}), (ImmW, 0)$



# Instruction Selector Completeness

Based on tree automata theory:

- Express both the instruction selector ( $G_{is}$ ) and intermediate representation ( $G_{ir}$ ) using *normalized* tree grammars with conditions
- Transform these grammars into regular tree automata
- Examine languages accepted by the respective automata

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Terminal Splitting:

Split the rules in the grammars such that for any two rules  $r_1$  in  $G_{ir}$  and  $r_2$  in  $G_{is}$ , where  $term(r_1) = term(r_2)$  the following condition holds:

$$cond(r_1) = cond(r_2) \vee \neg overlap(cond(r_1), cond(r_2)).$$

$cond(r) \rightarrow D$  ... condition of rule  $r$

$term(r) \rightarrow \mathcal{F}$  ... terminal symbol of rule  $r$ .

## Instruction Selector Completeness (2)

After terminal splitting:

- Construct equivalent automata using dedicated terminal symbols representing the conditions and terminal symbols of the rules in the original grammars
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$$\begin{array}{ll} v \rightarrow INT\_CONST & \{-\infty, \dots, \infty\} \\ v \rightarrow +(v, v) & \{-\infty, \dots, \infty\} \end{array}$$

(a) Intermediate Representation

$$\begin{array}{ll} r \rightarrow INT\_CONST & \{-32768, \dots, 32767\} \\ r \rightarrow INT\_CONST & \{0, \dots, 65535\} \\ r \rightarrow +(r, r) & \{-\infty, \dots, \infty\} \end{array}$$

(b) Instruction Selector

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$v \rightarrow INT\_CONST$	$\{-32768, \dots, -1\}$
$v \rightarrow INT\_CONST$	$\{0, \dots, 32767\}$
$v \rightarrow INT\_CONST$	$\{32768, \dots, 65535\}$
$v \rightarrow INT\_CONST$	$\{65536, \dots, \infty\}$
$v \rightarrow +(v, v)$	$\{-\infty, \dots, \infty\}$

(a) Intermediate Representation

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(b) Instruction Selector

# Evaluation

- Architecture models
  - Subset of MIPS-I (RISC), SPEAR2 (RISC), CHILI
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  - Model statistics, relate to other processor description systems
- Compiler generation
  - Retarget LLVM compiler framework for CHILI
  - Code size and performance measurements
  - Comparison with hand-crafted production compilers
  - Results obtained using validated simulators
  - Subset of the MiBench benchmark suite

# The CHILI Processor

## Configurable media processor

- 32-bit data path
- 64 general purpose registers
- 2-way or 4-way parallel VLIW
- 7-stage pipeline
  - Large number of branch delay slots (4 cycles)
  - Long load delay (5 cycles)
  - Identical parallel pipelines
- Instruction set
  - Almost all instructions can be predicated
  - Rich set of predicated instruction variants
  - Dedicated instructions for video en-/decoding



# Processor Models

Model	LOC	Syntax		Encoding		Types		Components	
		LOC	#Tmpl.	LOC	#Tmpl.	LOC	#Ty.	LOC	#Ists.
CHILI-v2	1580	191	12	141	6	800	20	350	14
CHILI-v4	1739	220	12	156	6	830	20	454	24
MIPS	1143	183	14	134	9	592	14	157	12
SPEAR	1298	109	5	223	12	733	13	172	14

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The specifications are compact, due to the use of types. Furthermore, the number of instruction paths is relatively low in comparison to the number of actual instructions.

# Processor Models

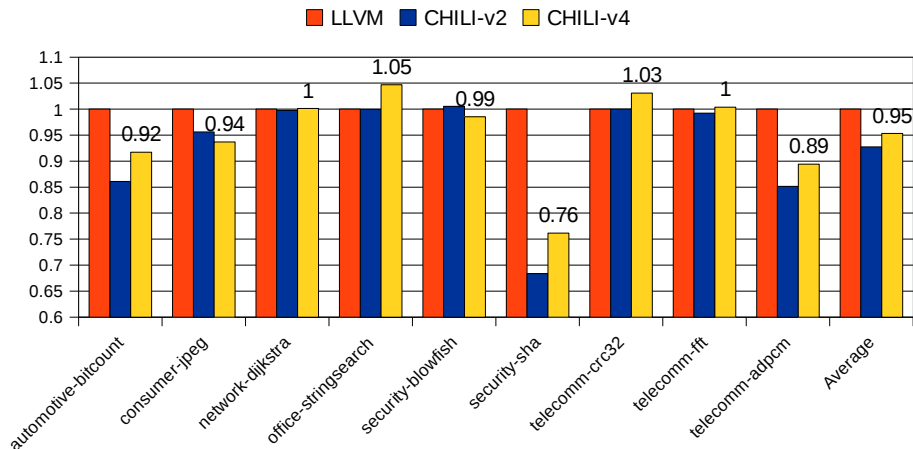
Model	LOC	Syntax		Encoding		Types		Components	
		LOC	#Tmpl.	LOC	#Tmpl.	LOC	#Ty.	LOC	#Ists.
CHILI-v2	1580	191	12	141	6	800	20	350	14
CHILI-v4	1739	220	12	156	6	830	20	454	24
MIPS	1143	183	14	134	9	592	14	157	12
SPEAR	1298	109	5	223	12	733	13	172	14

Model	Definitions		Expanded		Instruction Set			
	#Uts.	#Ops.	ISA	#Instrs	Behavior	Structure	#Insts.	Compiler
	Model	LOC	LOC	#Instrs	LOC	LOC	LOC	LOC
CHILI-v2	R3000	2533	386	58	2121	-	-	-
CHILI-v4	acesMIPS	4184	828	85	-	533	2353	173
MIPS								
SPEAR								

Low specification overhead compared to other processor description systems!

The specifications are compact, due to the use of types. Furthermore, the number of instruction paths is relatively low in comparison to the number of actual instructions.

# LLVM Compiler Generator - Results for CHILI



Relative performance results of LLVM-based vs. xADL-generated LLVM compilers for two configurations of the CHILI VLIW.

# LLVM Compiler Generator - Results for CHILI-v4

Benchmark	Code Size			Cycles		
	GCC	xADL	%	GCC	xADL	%
automotive-bitcount	348,892	296,376	-15	881,144	1,183,104	+34
consumer-jpeg	2,341,904	1,241,408	-47	10,794,047	9,976,958	-8
network-dijkstra	485,560	470,744	-3	2,894,236	2,414,124	-17
office-stringsearch	334,004	303,384	-9	624,087	738,406	+18
security-blowfish	400,160	306,192	-23	1,541,883	1,491,519	-3
security-sha	351,860	327,608	-7	10,791,045	12,215,822	+13
telecomm-crc32	353,980	327,132	-8	8,637,327	9,520,911	+10
telecomm-fft	415,184	400,884	-3	187,968,275	188,243,462	+1
telecomm-adpcm	338,988	324,728	-4	10,116,131	9,755,433	-4

Runtime and code size results for GCC version 4.2.0 and the xADL-generated LLVM compiler for the four-way parallel CHILI.

# Conclusion

- Structural xADL processor description language
  - Extensible types
  - Compact and intuitive specifications
  - Instruction set extraction along instruction paths
  - No redundant specification of behavior

# Conclusion

- Structural xADL processor description language
  - Extensible types
  - Compact and intuitive specifications
  - Instruction set extraction along instruction paths
  - No redundant specification of behavior
- Generator tools
  - High-quality code generation
    - Competitive with production compilers
    - Slightly slower code by 5%
  - Automatic completeness test
    - Verifies completeness of the derived instruction selector
    - Provides valuable feedback using counter examples
  - In addition
    - High-speed simulation
    - ...