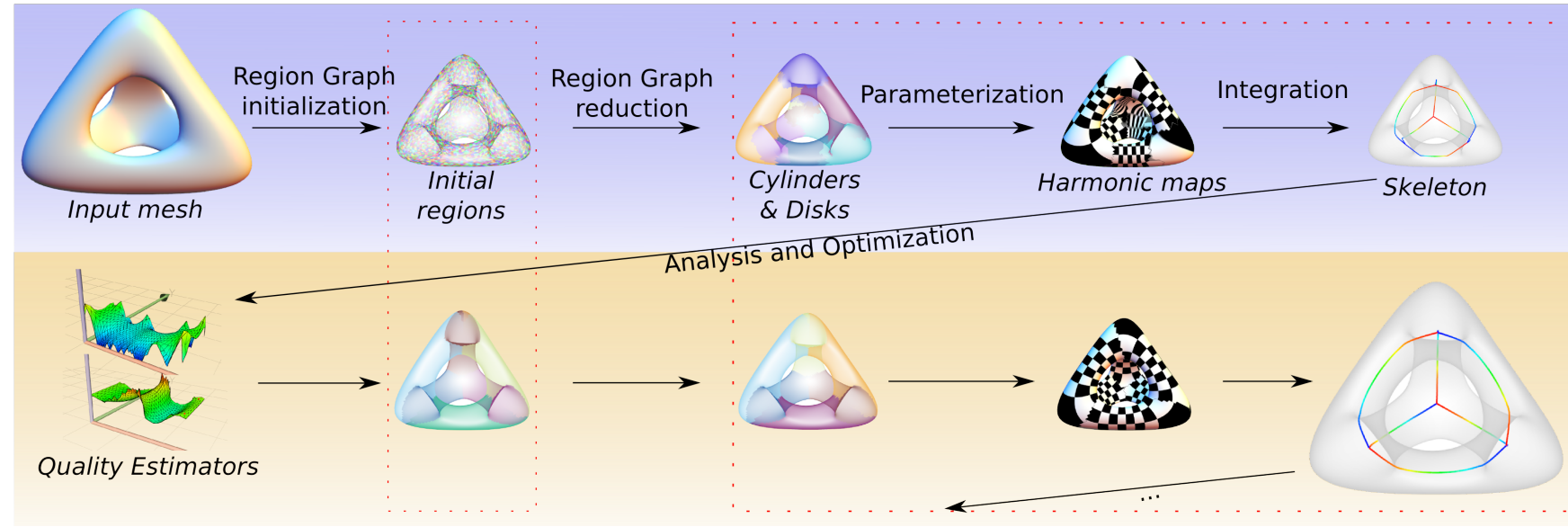


Abstract

We present a new curve skeleton designed for surface modeling and processing. This skeleton is defined as the geometrical integration of a piecewise harmonic parameterization defined over a disk-cylinder surface decomposition. This decomposition is computed using a progressive Region Graph reduction based on both geometric and topological criteria. The skeleton has an analytical form with regularity inherited from the surface one. This form offers well-defined surface-skeleton and skeleton-surface projection. A large repository of *skeletal* shape modeling and processing methods can be derived from it: we illustrate this with an inset surface modeling tool and a new signal filtering operator.

Overview



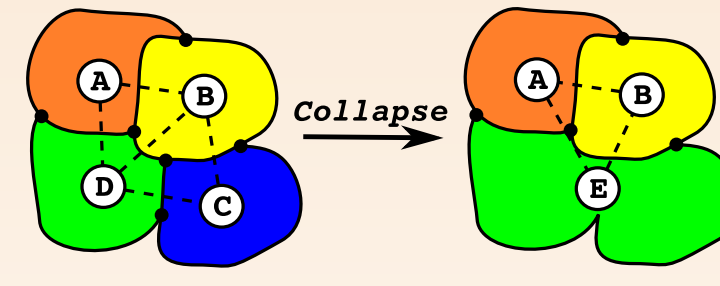
Input : Manifold triangle mesh.

1. Topological **cylinders & disks decomposition**
2. Harmonic cylinder & disks **parameterization**
3. **Skeletonization** by geometrical cylinder integration
4. Connection of the bones
5. *Optional: improved segmentation from skeleton; go to 2.*

Output : Parametric curve skeleton

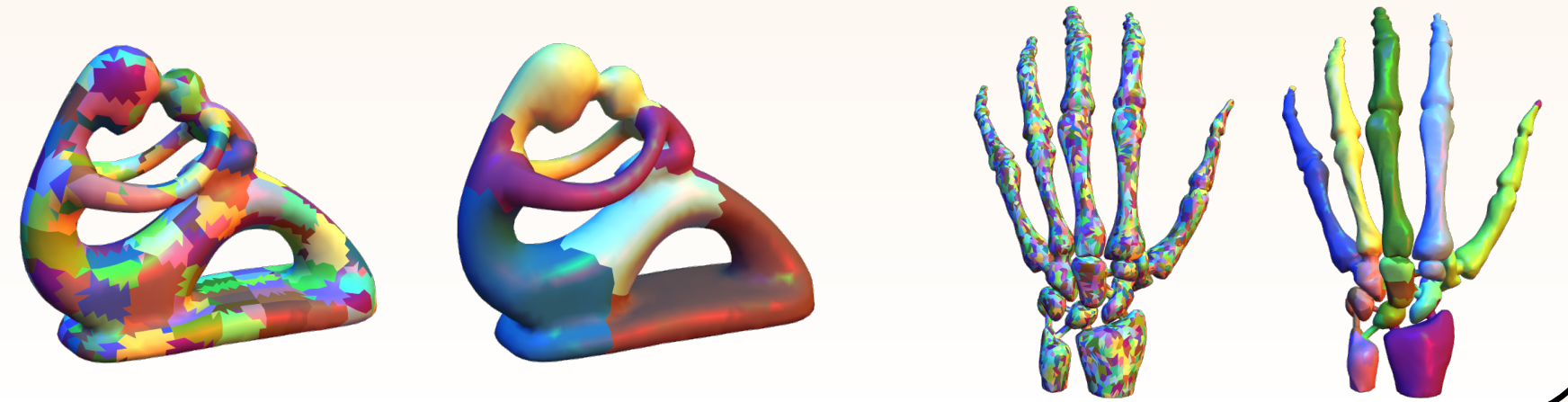
Cylinders & Disks Decomposition

Region Graph = dual graph of the input segmentation
Edge collapse in Region Graph = Regions merging

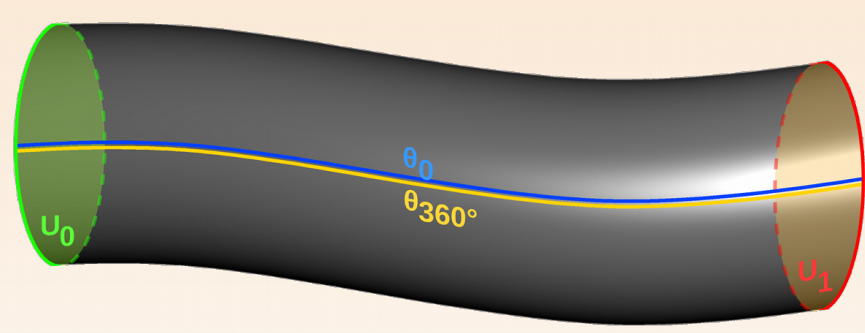


Topology			Class	e_T
R^A	R^B	$R^A \cup R^B$		
Cyl.	Disk	Disk	Fill Hole	0
Disk	Disk	Cyl.	Create Cylinder	1
Disk	Disk	Disk	Grow Disk	2
Cyl.	Disk	Cyl.	Grow Cylinder	3
Cyl.	Cyl.	Cyl.	Merge Cylinders	4
Other cases			Skip	∞

- * Bottom-up segmentation by progressive, error-driven Region Graph edge collapse.
- * Error metric from dominant integer topological classes, independently ordered by geometric terms defined for each topological class.
- * Edge-collapses discarded if their topological term is ∞ , or by geometric tests.

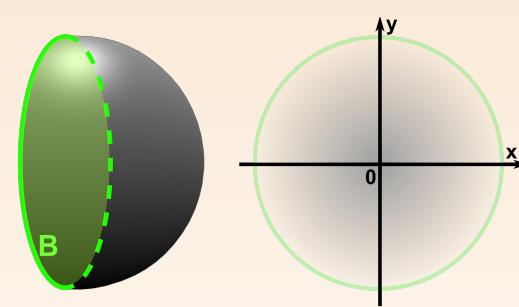


Parameterization



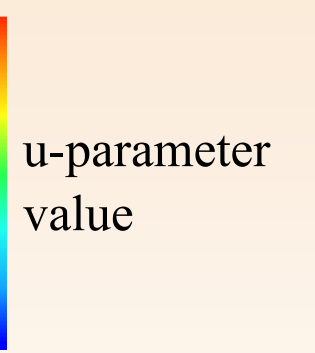
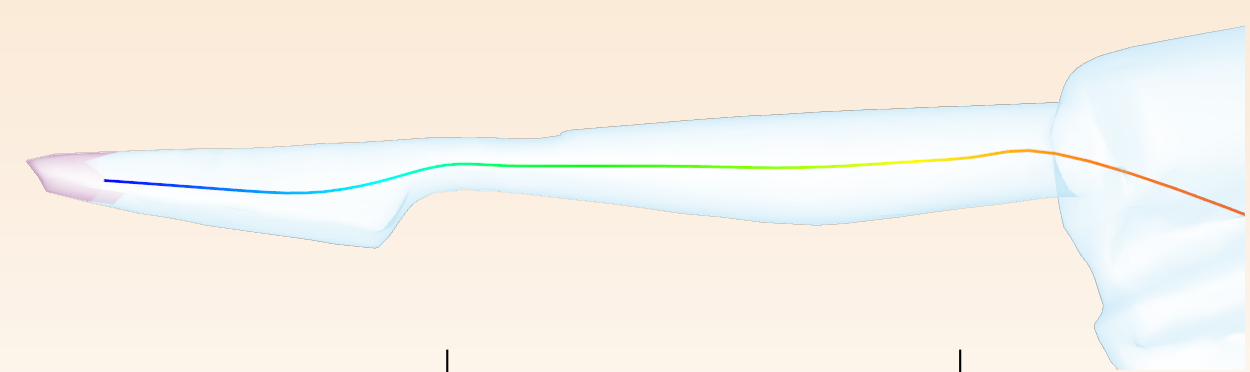
$$\begin{cases} u(v) = 0 & \forall v \in U_0 \\ u(v) = 1 & \forall v \in U_1 \\ \Delta u(v) = 0 & \forall v \notin U_0 \cup U_1 \end{cases} \quad \begin{cases} \theta(v) = 0 & \forall v \in \theta_0 \\ \theta(v) = 360 & \forall v \in \theta_{360} \\ \Delta \theta(v) = 0 & \forall v \notin \theta_0 \cup \theta_{360} \end{cases}$$

- * Harmonic map for each region
- * Discrete laplacian using cotangent weights
- * Solved in the least squares sense



$$\begin{cases} x(v) = \cos(\theta(v)) & \forall v \in B \\ y(v) = \sin(\theta(v)) & \forall v \in B \\ \Delta x(v) = 0 & \forall v \notin B \\ \Delta y(v) = 0 & \forall v \notin B \end{cases}$$

Skeletonization



Analytical form
by integration

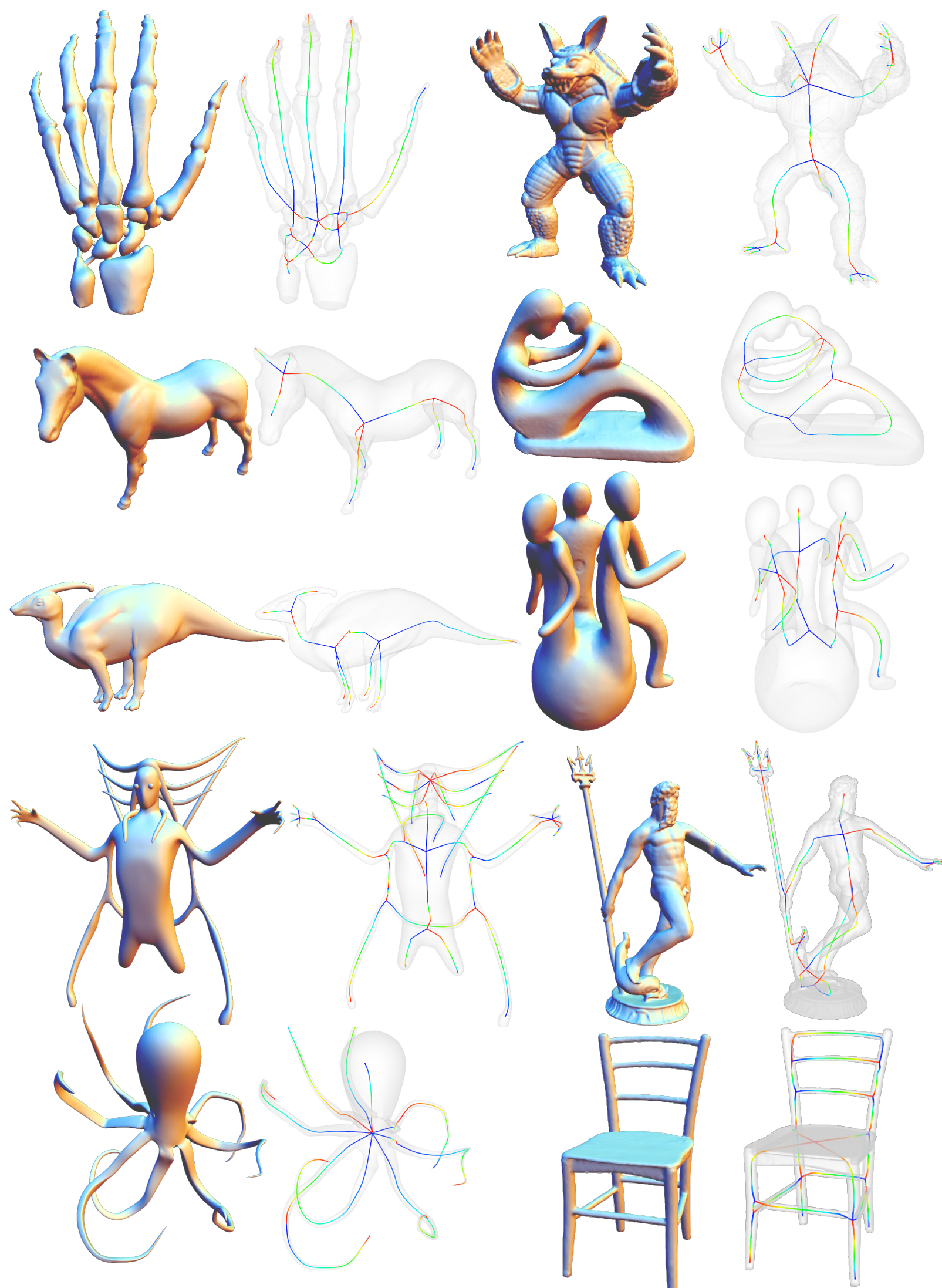
$$b(u) = \frac{\int_0^{2\pi} p(u, \theta) d\theta}{\int_0^{2\pi} d\theta}$$

Regularity

$$\begin{array}{ccc} M & \xrightarrow{p} & \mathbb{R}^3 \\ \mu \searrow & & \nearrow \hat{p} \\ & \mathbb{R}^2 & \\ \lambda \swarrow & & \nwarrow \hat{\lambda} \\ & \mathbb{R}^2 & \end{array}$$

- * skeleton regularity inherited from the surface
- * spline representation

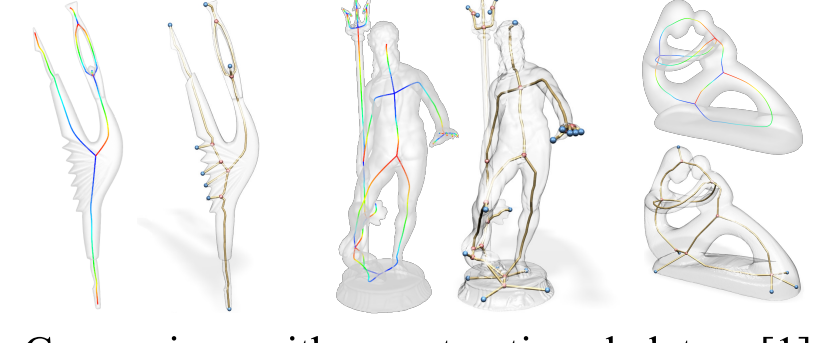
Resulting Skeletons



Properties

- * **Analytical** and mathematically **smooth** skeleton
- * Parametric skeleton $\Leftrightarrow$ surface projection
- * Interactive skeleton editing

Comparison



Comparison with a contraction skeleton [1]

New Applications

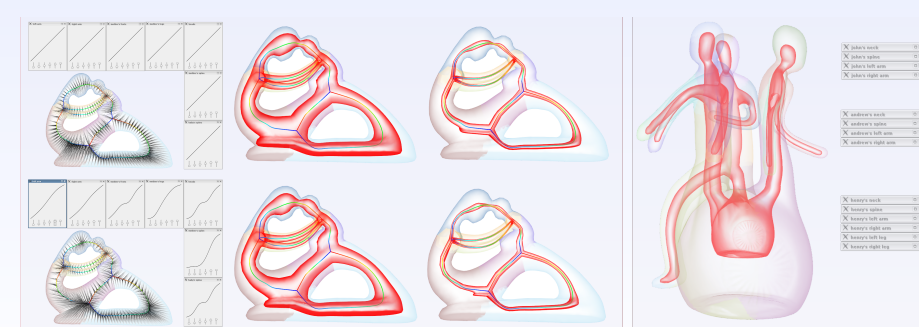
- * Signal processing and editing
- * Inset surfaces and volume editing
- * Generalized cylinders reconstruction
- * Adaptive FFD cage creation
- * Detection of constriction lines
- * Quad-dominant meshing

Skeletal signal

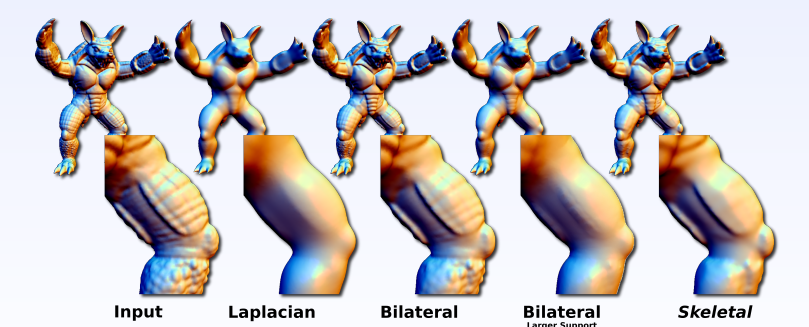
	Skeletal signal	
	Euclidean	Skeletal
Domain	World basis	Skeleton
Range		

Normal variation cannot model mid and large scale features

Inset surfaces and volume editing



New bilateral mesh filter



References

- [1] AU O. k.-c., TAI C.-L., CHU H.-K., COHEN-OR D., LEE T.-Y.: Skeleton extraction by mesh contraction. *ACM Transactions on Graphics* 27, 3 (2008)
- [2] SHAMIR A.: A survey on mesh segmentation techniques. *Computer Graphics Forum* 27, 6 (2008), 1539-1556.
- [3] JONES T. R., DURAND F., DESBRUN M.: Non-iterative, feature-preserving mesh smoothing. In *ACM SIGGRAPH* (2003)