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**Static analysis techniques to verify
mutual exclusion situations within
SysML models**

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Outline

Introduction

Context

AVATAR and TTool

Contributions

Model transformation

Computations of P-invariants

Model backtracing

Conclusion



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Rationale

Context: Formal verification, SysML

- ▶ Formal verification enables early detection of design errors in the life cycle of real-time and distributed systems
- ▶ Formal verification tools face state explosion problem when models must be executed
 - ▶ SysML models are usually executed to be formally verified

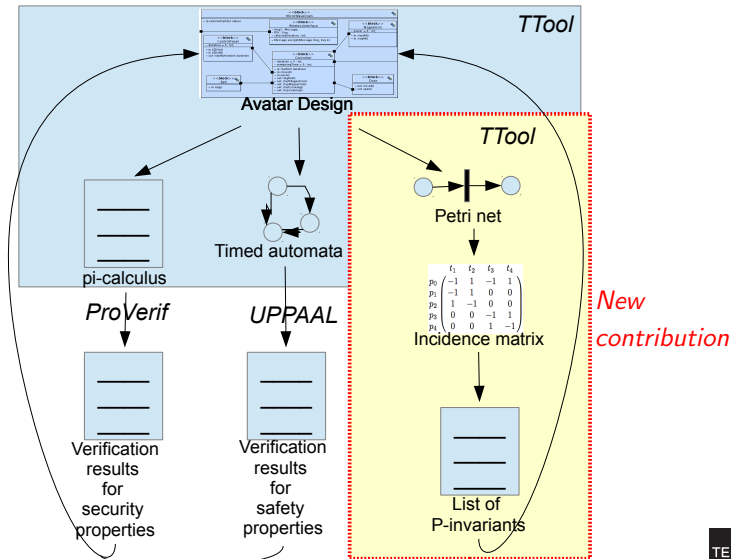
Contribution: static analysis of models

- ▶ AVATAR
 - ▶ Formal SysML environment
- ▶ TTool
 - ▶ Toolkit supporting AVATAR
 - ▶ Static analysis based on Petri nets invariants

AVATAR and TTool: Method

1. Requirement capture
 - ▶ Requirement diagrams: goals, assumptions, requirements
 - ▶ Property expression in TEPE (parametric diagrams extension)
2. Analysis
 - ▶ Use case driven analysis (use case diagrams)
 - ▶ Use cases documented by scenarios (sequence diagrams) and flow charts (activity diagrams)
3. Design
 - ▶ Architecture (block instance diagrams)
 - ▶ Behaviors (state machines diagrams)
 - ▶ Formal verification against the requirements and the properties defined in the AVATAR model
4. Prototyping
 - ▶ Generation of C/POSIX executable code
 - ▶ Integration with SoCLib

Formal Verification in AVATAR/TTool



Overview of Contributions

1. AVATAR design model transformation to Petri Net
2. Computation of incidence matrix
3. Computation of minimal P-invariants
 - ▶ Farkas algorithm
4. Backtracing to the AVATAR design model

Case study: a microwave oven



Outline

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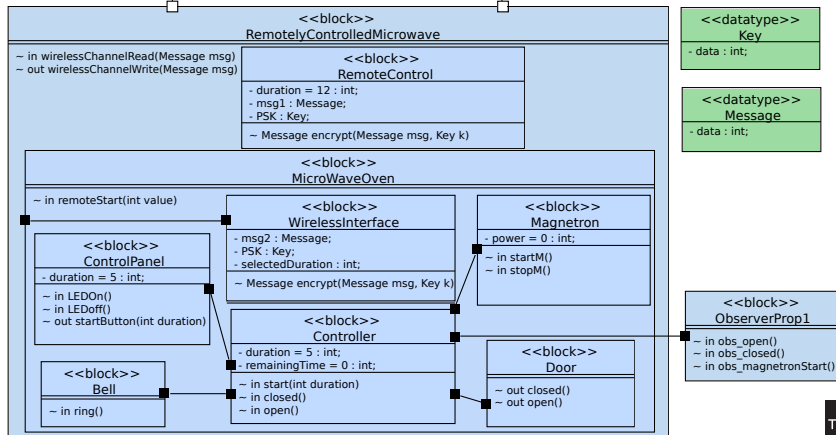
Contributions

- Model transformation
- Computations of P-invariants
- Model backtracing

Conclusion

AVATAR Design of a Microwave Oven

```
#Confidentiality RemoteControl.duration
#Authenticity RemoteControl.SendingRemoteOrder.msg1 WirelessInterface.gotWirelessOrder.msg2
#InitialSystemKnowledge RemoteControl.PSK WirelessInterface.PSK
```



Overview of Model Transformation

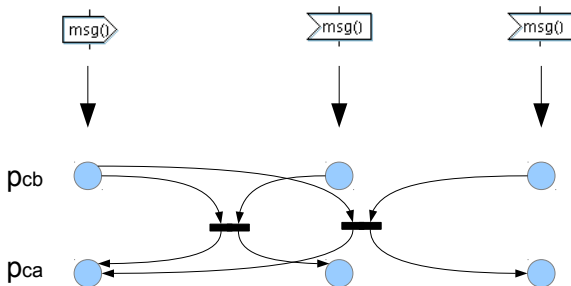
Translation of state machines

- ▶ State \rightarrow PN place, Transition \rightarrow PN transition
- ▶ Non-deterministic choice \rightarrow PN place from which starts a set of non deterministic PN transitions
- ▶ Communication operators \rightarrow one translation pattern is used for each communication semantics
 - ▶ Synchronous, blocking asynchronous, non blocking asynchronous
- ▶ Timers, guards and time constraints are ignored

Translation of the architecture

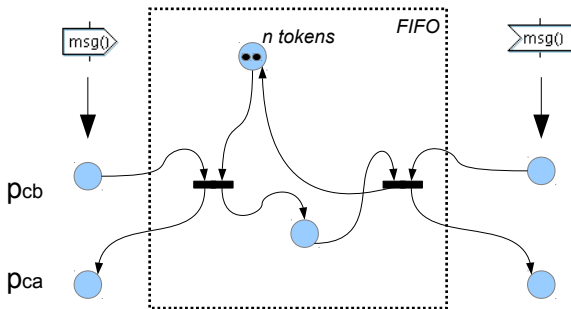
- ▶ Variables and methods are ignored
- ▶ Communication channels and signals are taken into account by the translation of communication operators

Synchronous Communications

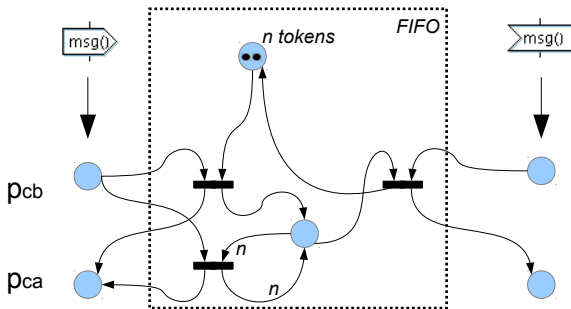


(p_{cb} means "place channel before" and p_{ca} means "place channel after")

Blocking Asynchronous Communications

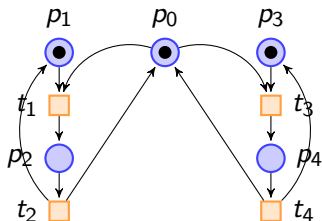


Non Blocking Asynchronous Communications



Petri Net: Example

► Petri Net



► Transposed incidence matrix

$$A^t = \begin{matrix} & \begin{matrix} t_1 & t_2 & t_3 & t_4 \end{matrix} \\ \begin{matrix} p_0 \\ p_1 \\ p_2 \\ p_3 \\ p_4 \end{matrix} & \begin{pmatrix} -1 & 1 & -1 & 1 \\ -1 & 1 & 0 & 0 \\ 1 & -1 & 0 & 0 \\ 0 & 0 & -1 & 1 \\ 0 & 0 & 1 & -1 \end{pmatrix} \end{matrix}$$

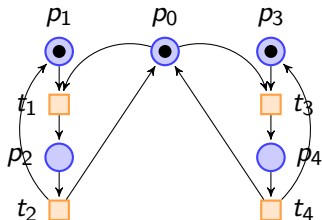
Computation of P-invariants

General approach

- ▶ The matrix A^t is made triangular, as for solving a linear system e.g. $\mathcal{W}.A = 0$
 - ▶ Lines of A^t can be exchanged, multiplied by a given integer value, or one line can be added to another one
 - ▶ Use of the *Farkas* algorithm

$$A_{triangular}^t = \begin{matrix} p_0 \\ p_4 \\ p_0 + p_2 + p_4 \\ p_3 + p_4 \\ p_1 + p_2 \end{matrix} \begin{matrix} t_1 & t_2 & t_3 & t_4 \\ \left(\begin{array}{cccc} -1 & 1 & -1 & 1 \\ 0 & 0 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right) \end{matrix}$$

P-invariants of the example PN



Finally, P-invariants are:

- ▶ $p_1 + p_2$
- ▶ $p_3 + p_4$
- ▶ $p_0 + p_2 + p_4$

We are interested in P-invariants

- ▶ Whose places do not relate to only one AVATAR block
 - ▶ This is an obvious P-invariant since one block has only one flow of execution
- ▶ Whose value = 1 \rightarrow all listed places are in mutual exclusion

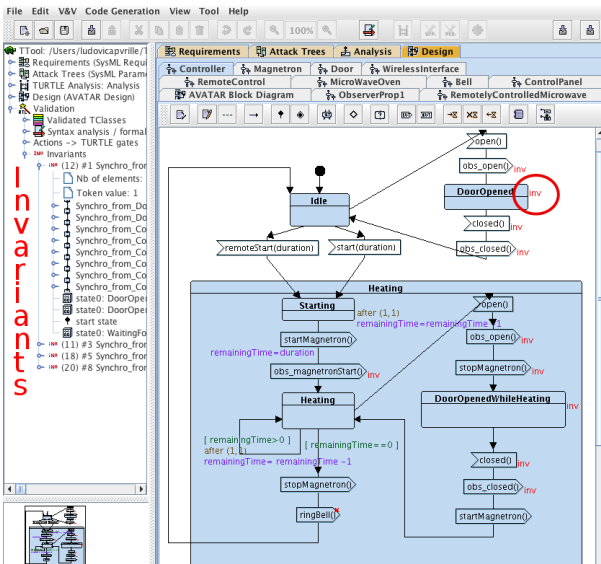
Complexity

- ▶ Farkas: exponential time in the number of places of the net
- we have defined heuristics to reduce that complexity

Heuristics

- ▶ Memo: We are interested in mutual exclusions i.e. in P-invariants whose value is 1
- ▶ When combining lines, each time the line contains two times the same place, we delete the line
 - ▶ Unfortunately: we may remove invariants for which all places are listed the same number n of times, with $n > 1$
- ▶ Computations of invariants is instantaneous on all AVATAR models on which we have tested these heuristics
 - ▶ Without heuristics: up to an hour
 - ▶ No difference in the list of computed P-invariants

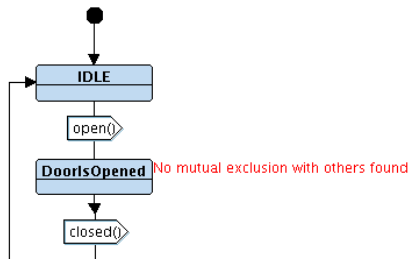
Invariants as displayed by TTool



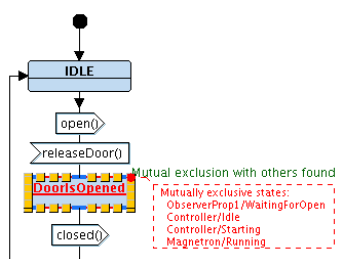
Mutual Exclusion of States

- ▶ **Example:** search of the mutual exclusion of the state Door/DoorOpened with the state Magnetron/Running

Version 1



Version 2





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Contributions

- ▶ Static analysis of AVATAR models searching for mutually exclusive states
- ▶ TTool hides Petri nets and displays results on AVATAR models

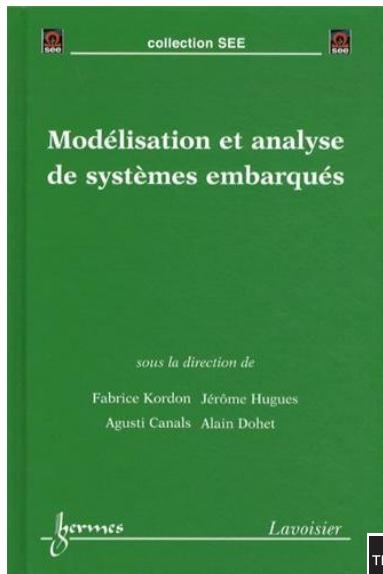
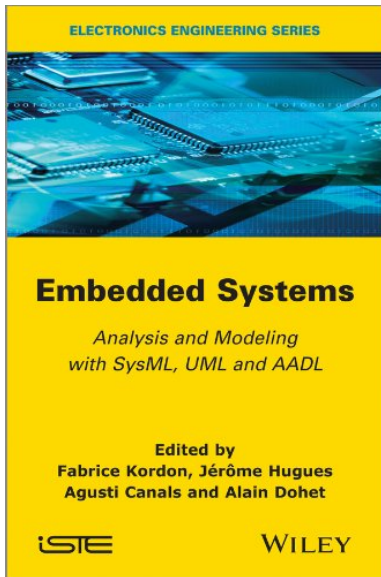
Limitations

- ▶ Basic Petri nets
- ▶ No support of H and H* operators
- ▶ No support of continuous flows

Future work

- ▶ Invariants for extended Petri nets
- ▶ Application to other real-time UML profiles

To Go Further ...



To Go Further: TTool, AVATAR

TTool

- ▶ <http://ttool.telecom-paristech.fr>
- ▶ Can be executed on usual operating systems (Windows, Linux, MacOS)
- ▶ Supports several profiles (e.g., DIPLODOCUS, AVATAR)
- ▶ Open-source, contributions are welcome
- ▶ Support from industrial and academic partners

AVATAR

- ▶ <http://ttool.telecom-paristech.fr/avatar.html>
- ▶ Tutorials, examples