



# UMLEmb: UML for Embedded Systems II. Modeling in SysML

Ludovic Apvrille,  
ludovic.apvrille@telecom-paris.fr

LabSoC, Sophia-Antipolis, France



Case Study ●○○ Method ○○ Requirements ○○○○ (Partitioning) ○○○○○○○○ Analysis ○○○○○○○○○○○○○○○○○○○○○ Design ○○○○○○○○○○○○○○○○○○○○○

## Outline

Case Study

Method

Requirements

(Partitioning)

Analysis

Design





## Outline

Case Study

**Method**

Requirements

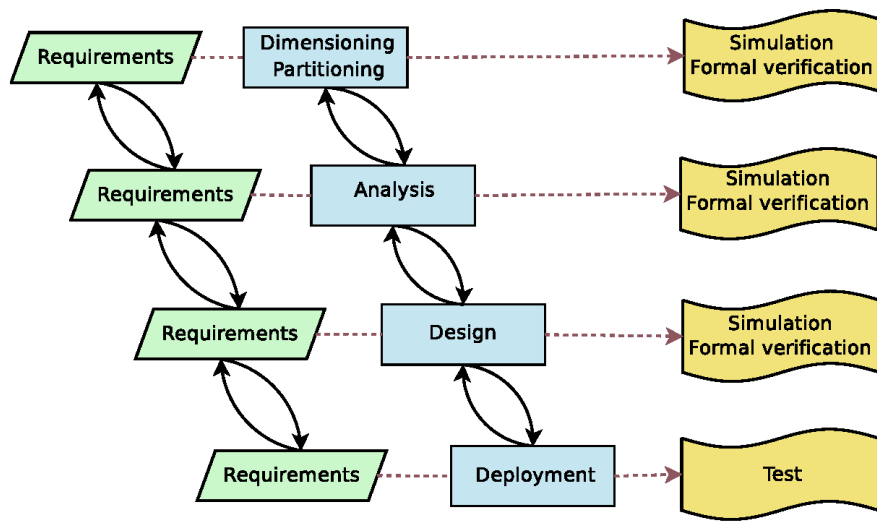
(Partitioning)

Analysis

Design



## Overview of the V Cycle



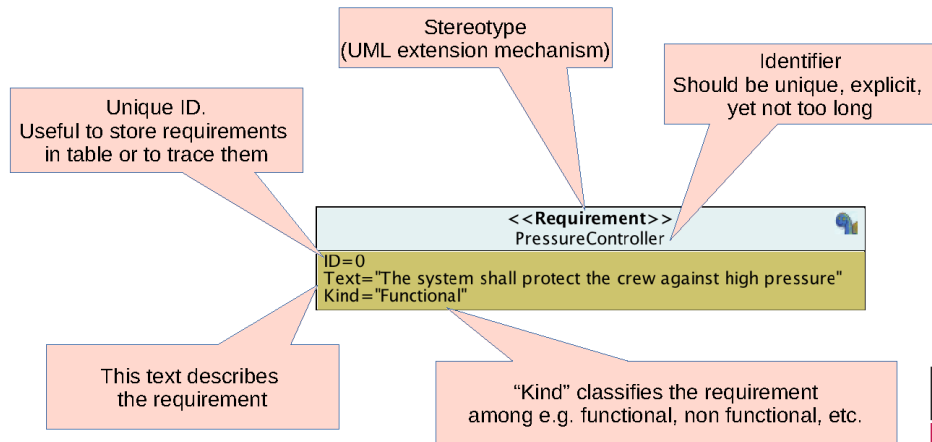
# Outline

- Case Study
- Method
- Requirements**
- (Partitioning)
- Analysis
- Design



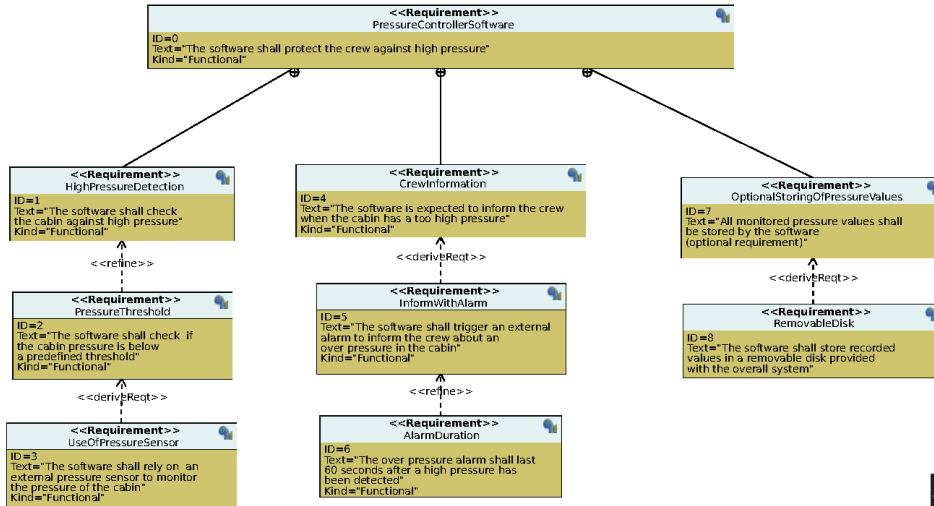
# Requirement Node

- **A requirement node identifies a requirement** by:
  - A unique identifier (so as to achieve tracability)
  - A description in plain text
  - A type (functional, non functional, performance, security, ...).





# Requirement Diagram - Pressure Controller - Software View



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## Complex Embedded Systems

- Complex Embedded System = set of SW and HW components intended to perform a predefined set of functions for a given market
- Constraints
  - Right market window
  - Performance and costs



## Design Challenges



**Complexity**

- Very high software complexity
- Very high hardware complexity

**Problem**

How to decide whether a function should be implemented in SW or in HW, or both?

**Solution**

Design Space Exploration!  
(a.k.a. "Partitioning")



## Design Space Exploration

### Design Space Exploration

- Analyzing various functionally equivalent implementation alternatives
- → Find an optimal solution

### Important key design parameters

- Speed
- Power Consumption
- Silicon area
- Generation of heat
- Development effort
- ...



## Level of Abstraction

### Problematic

- Designers struggle with the complexity of integrated circuits (e.g. System-on-chip)
- Cost of late re-engineering
  - Right decisions should be taken as soon as possible ...
  - And quickly (time to market issue), so simulations must be fast

### → System Level Design Space Exploration

- Reusable models, fast simulations / formal analysis, prototyping can start without all functions to be implemented

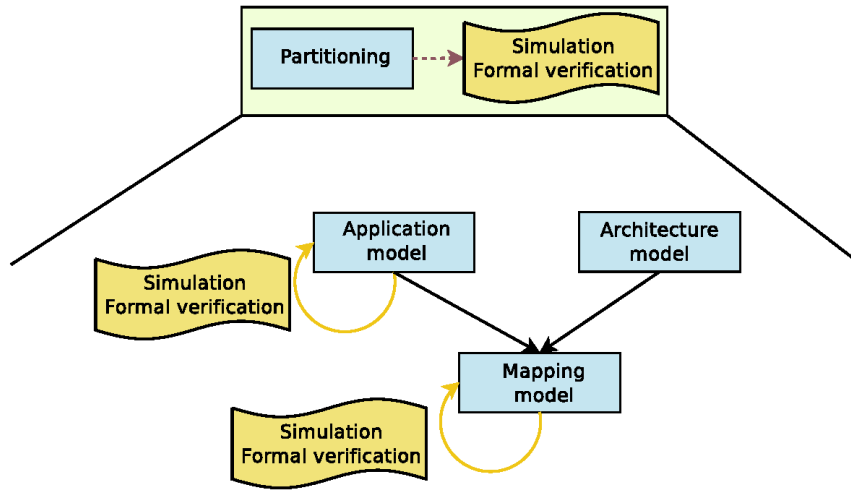
But: high-level models must be closely defined so as to take the right decisions (as usual ...).



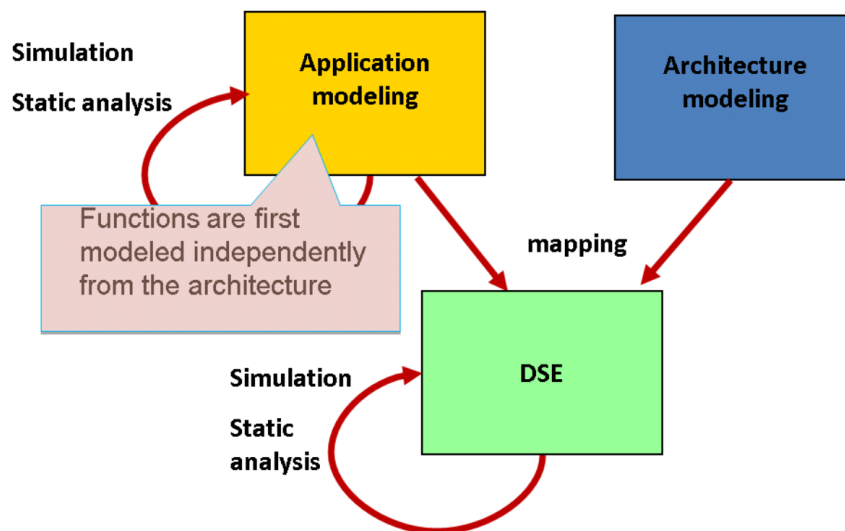


# Partitioning with the Y-Methodology

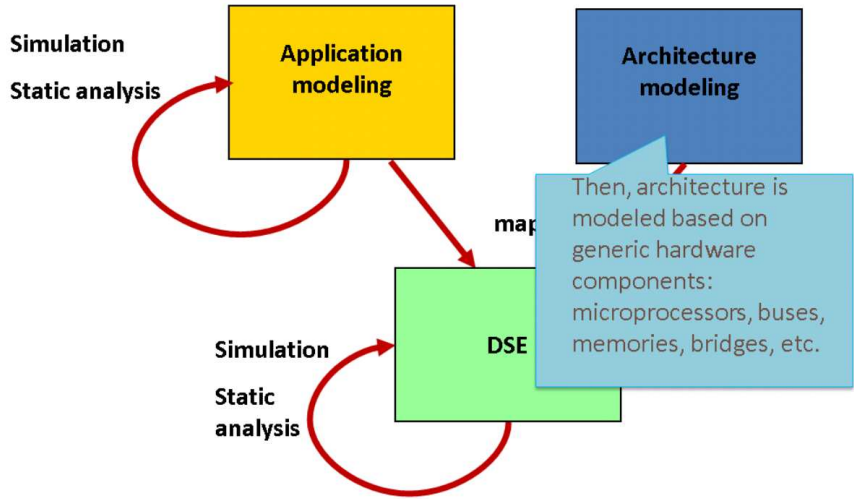
- Example: the DIPLODOCUS methodology



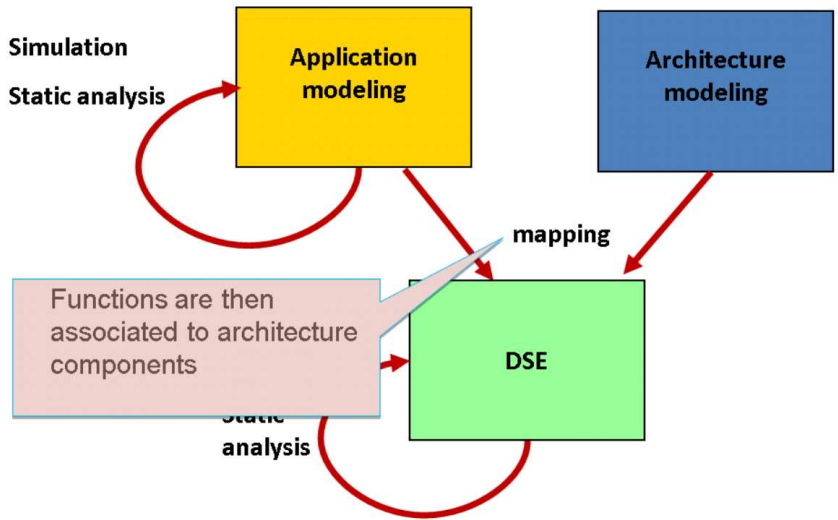
# Application Modeling



# Architecture Modeling



# Mapping



# Outline

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(Partitioning)

**Analysis**

Design



# System Analysis

## Analysis = Understanding what a client wants

- So, it does not mean "creating a system", but rather "understanding the main functionalities" of the system to be designed
- Can be performed before or after the partitioning stage

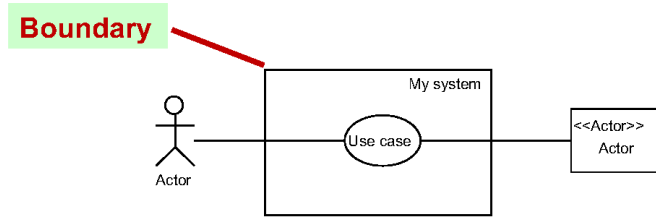
## Analysis method

1. System boundary and main functions → *Use Case Diagram*
2. Relations between main functions → *Activity Diagram*
3. Communications between main system entities and actors → *Sequence Diagram*

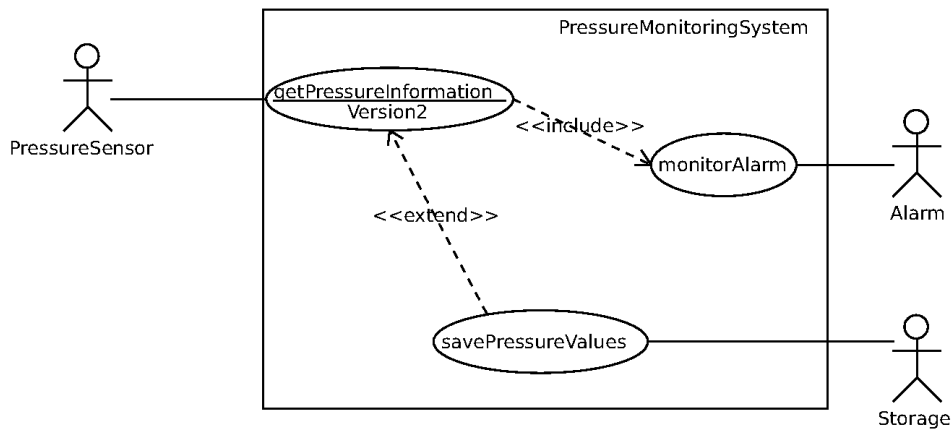


## Use Case Diagram: Method

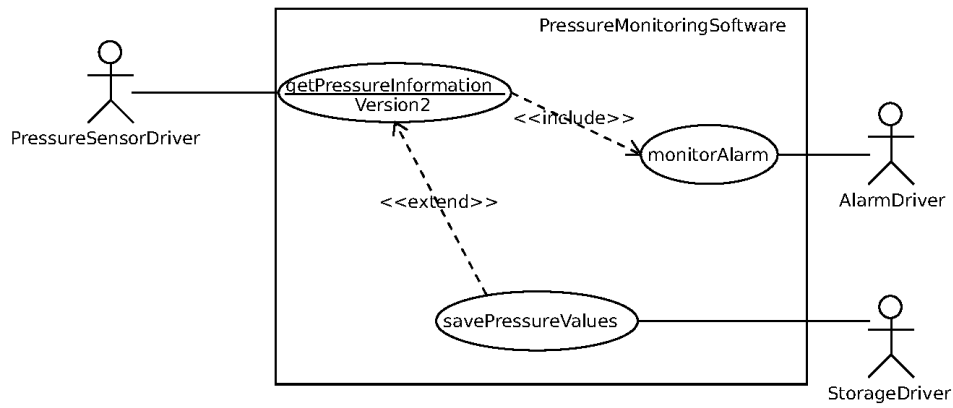
- Shows what the system does and who uses it
- 1. Define the boundary of the system
  - Inside of the rectangle → What you promise to design
  - Outside of the rectangle → System environment (= Actors)
    - This is not part of what you will have to design
- 2. Name the system
- 3. Identify the services to be offered by the system
  - Only services interacting with actors
- 4. Draw interactions between functions and actors



## Use Case Diagram - Pressure Controller - System View

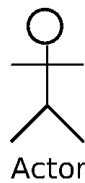


# Use Case Diagram - Pressure Controller - Software View

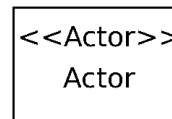


## Actors

■ Syntax 1: Stickman



■ Syntax 2: <<Actor>>



### Method

- An actor identifier is a substantive
- An actor must interact with the system



## Use Case

- **Syntax:** ellipse with exactly one use case



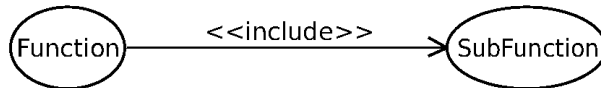
### Method

- A use case is described by a verb
  - The verb should describe **the point of view of the system**, not the point of view of the actors
- A use case diagram must **NOT** describe a step-by-step algorithm
  - A use case describes a high-level service/function, not an elementary action of the system

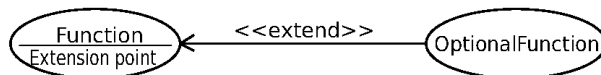


## Use Case to Use Case Relations

- **Inclusion**
  - A function mandatorily includes another function



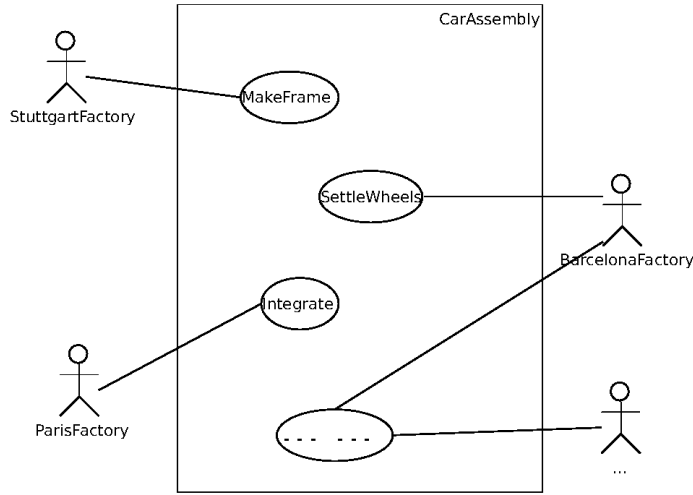
- **Extension**
  - A function optionally includes another function



- **Inheritance**
  - A "child" function specializes a "parent" function

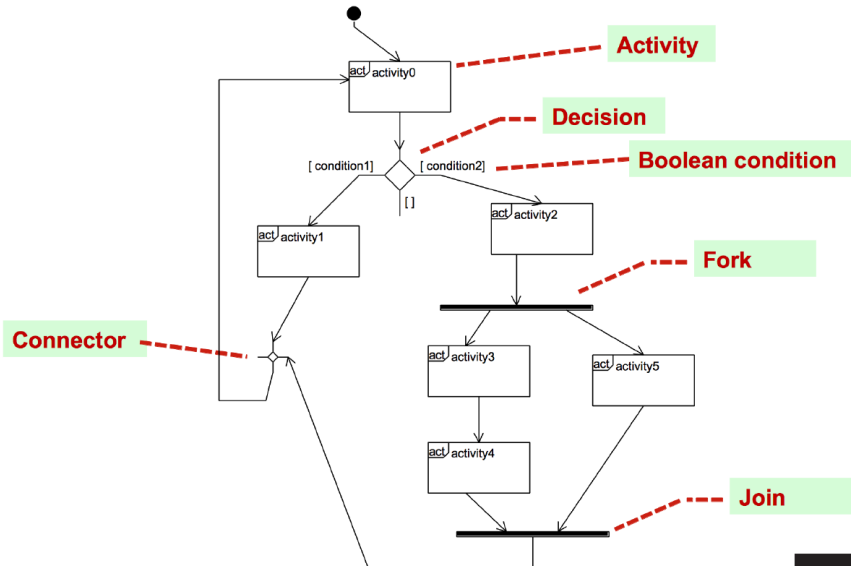


# Location-Driven Use Case Diagram



# Activity Diagram - Syntax

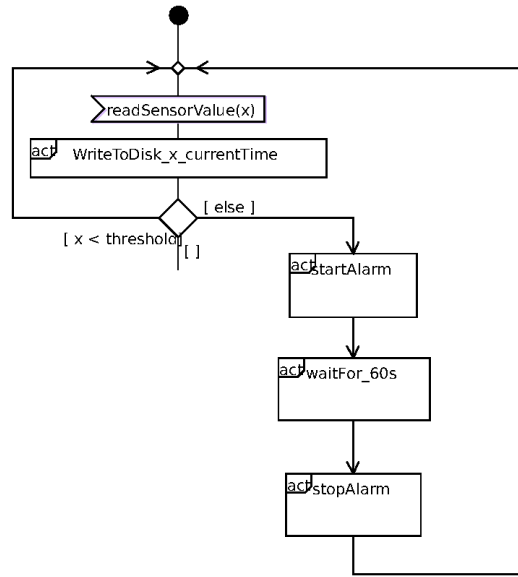
Shows functional flows in the form of succession of actions



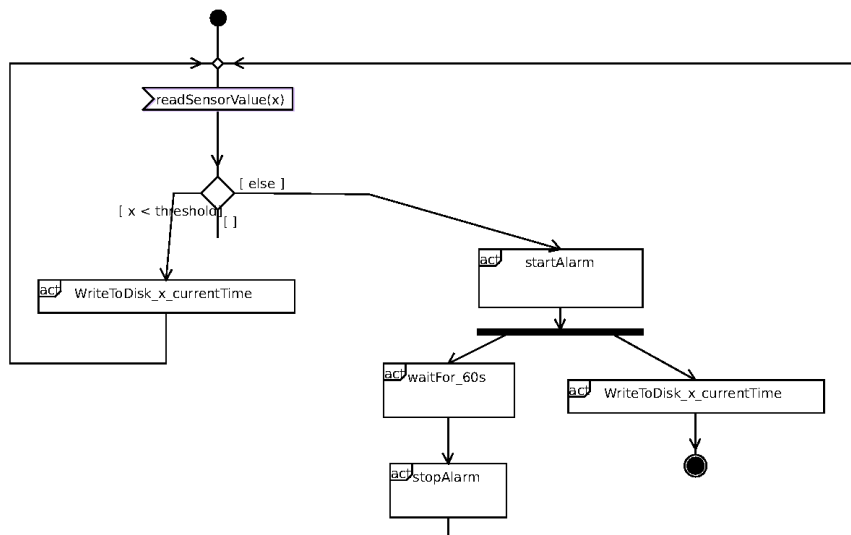




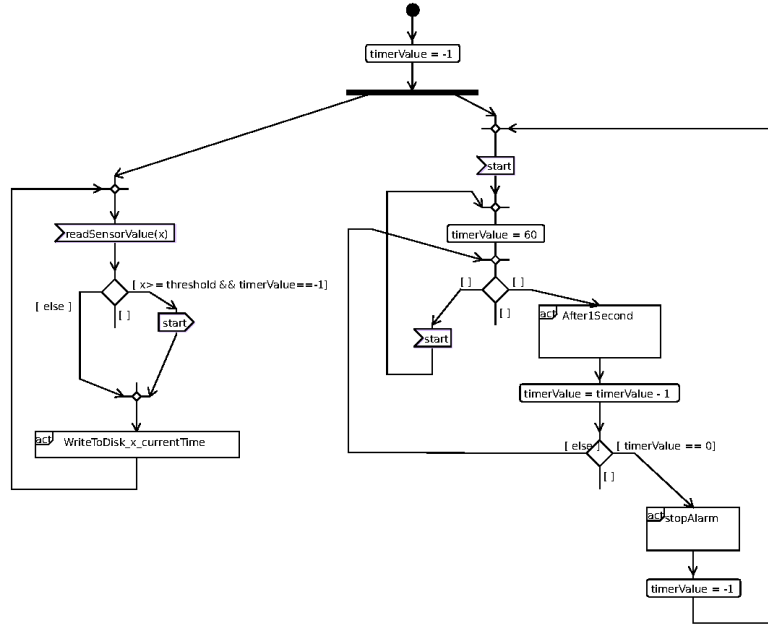
## Activity Diagram - Pressure Controller



## Activity Diagram - Pressure Controller

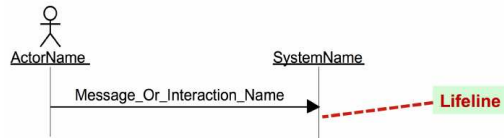


# Activity Diagram - Pressure Controller

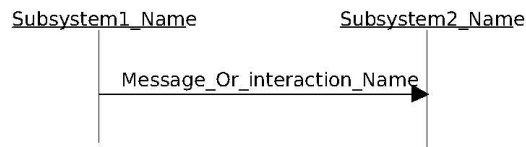


# Sequence Diagram

- An actor interacting with a system

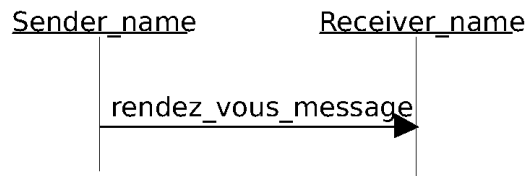


- Two interacting "parts" of the system

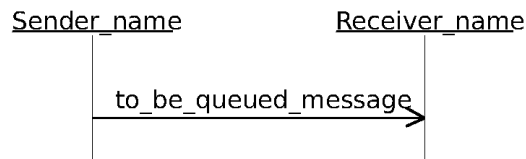


## Sequence Diagram - Messages

- Synchronous communication (black arrow)



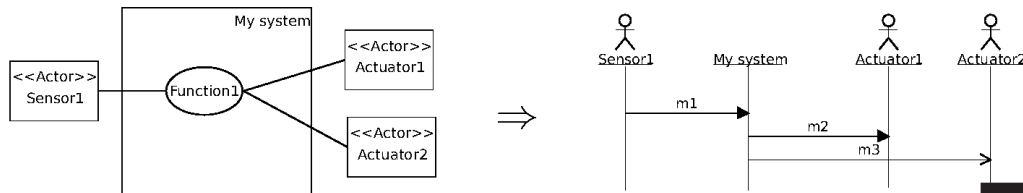
- Asynchronous communication (regular arrow)



## Using Sequence Diagrams

### Method

- A sequence diagram depicts one possible execution run, **NOT** the entire behavior of the system
- **NO message between actors**
- All actors must be defined in the use case diagram
  - WARNING: Coherence between diagrams

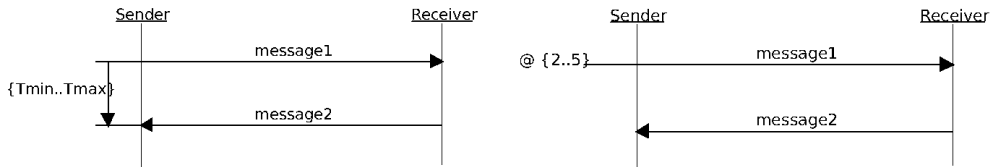


# Sequence Diagram - Time (1/2)

- Semantics**
- One global clock (applies to the entire system)
  - Time uniformly progresses (lifelines are read top-down)
  - Causal ordering of events on lifelines
    - Time information must be explicitly modeled

■ **Relative dates**

■ **Absolute date**



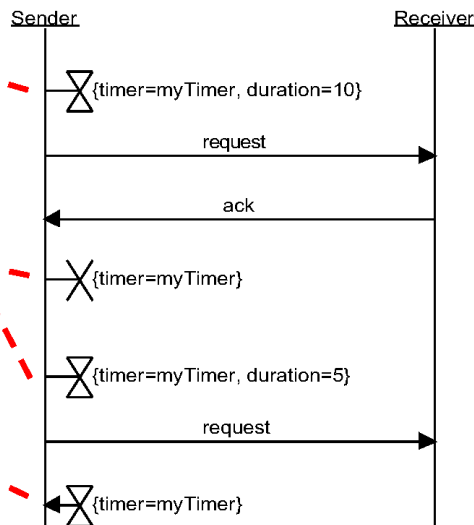
# Sequence Diagram - Time (2/2)

■ **Timers**

Set timer

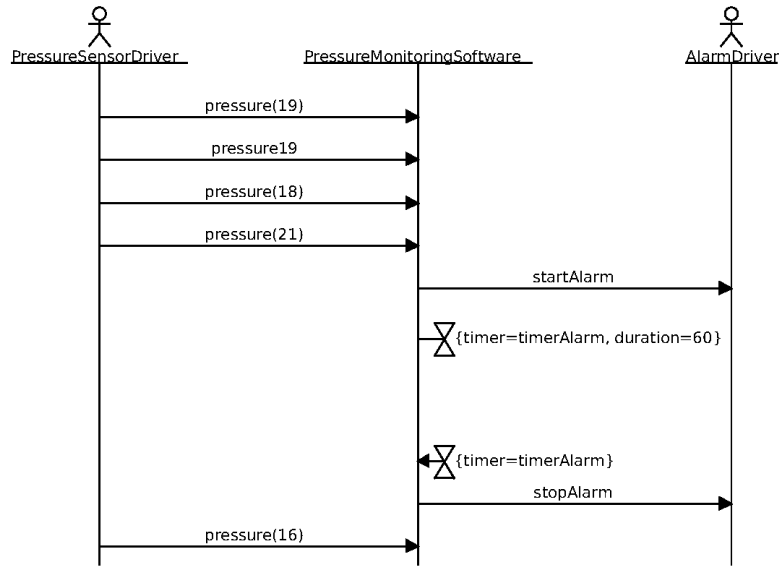
Reset timer

Timer expiration



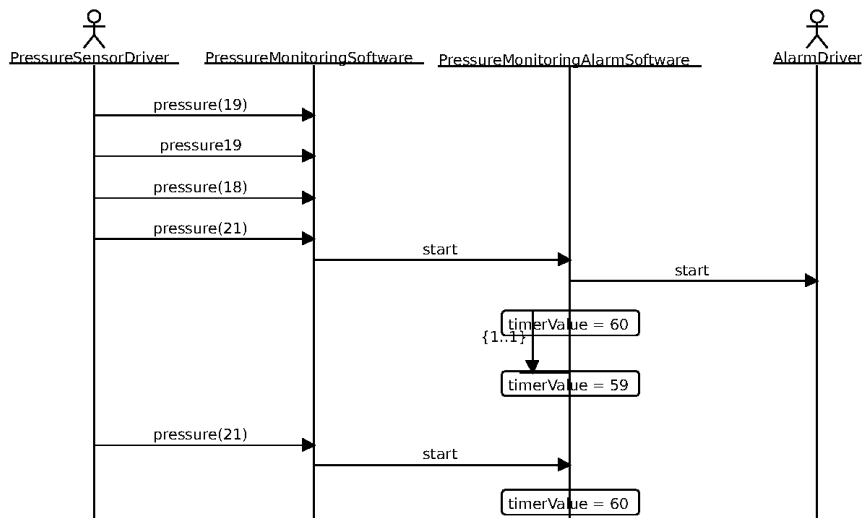
# Sequence Diagram - Pressure Controller

## Nominal trace



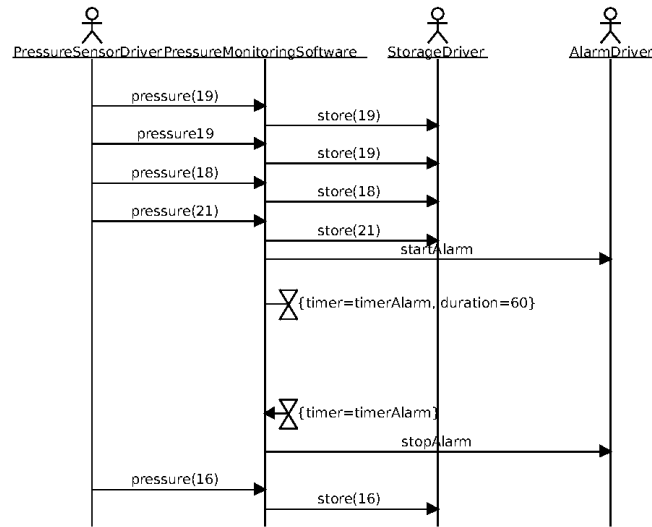
# Sequence Diagram - Pressure Controller

## Advanced trace



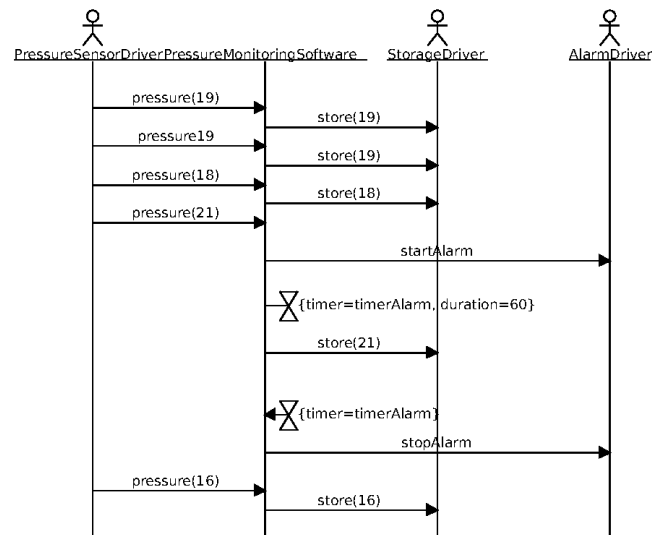
## Sequence Diagram - Pressure Controller

### Nominal trace - version 2 (save before alarm)



## Sequence Diagram - Pressure Controller

### Nominal trace - Version 2 (save after alarm)



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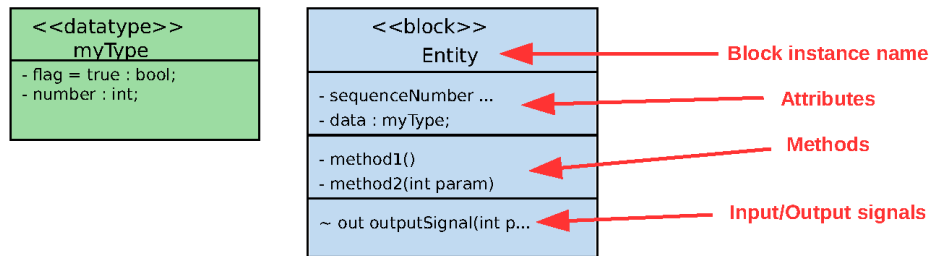
# System Design

**Design = Making what a client wants**  
So, it means "inventing a system", "creating a system" that complies with the client requirements.

- System architecture → *Block Definition Diagram and Internal Block Diagram*
  - In AVATAR, they are merged in one diagram that contains:
    - The definition of blocks
    - The interconnection of these blocks
- Behaviour of the system → *State Machine Diagram*
  - One state machine diagram per block



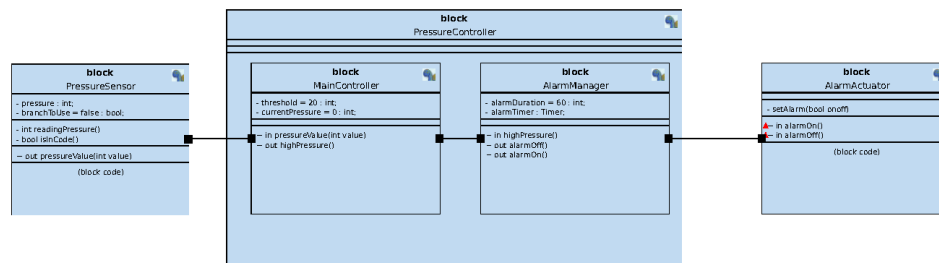
## (Instance) Block Diagram: Syntax of Blocks



**Note**

- Upper-case and lower case characters
- Attributes are *private* elements
- Signals have the *package* access right
  - Package = a block + its sub-blocks

## (Instance) Block Diagram: Connecting Blocks

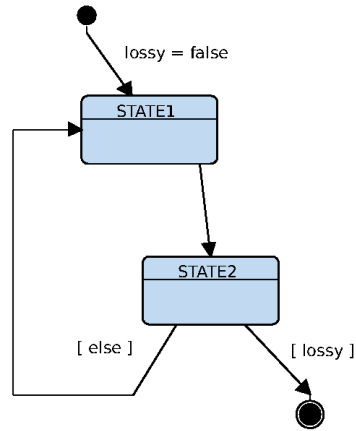


- Ports are connected to allow the state machines of blocks to exchange signals
- A block instance may nest one or several block instances



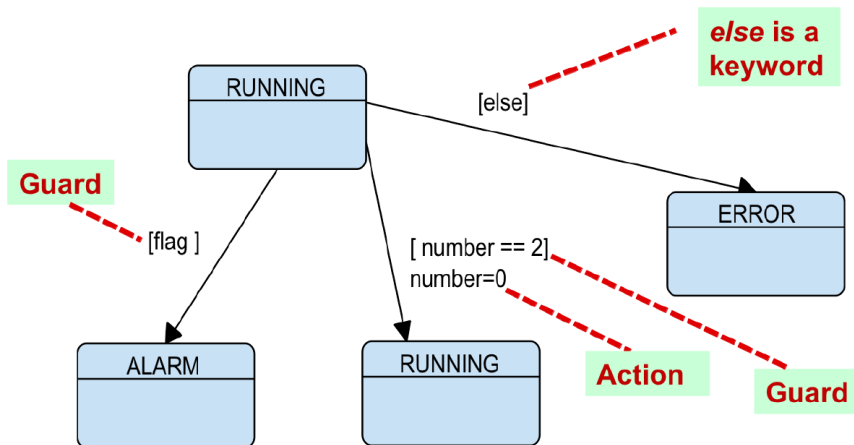
# State Machine - States and Transitions

- Note
- No parallelism
  - States can have several output transitions



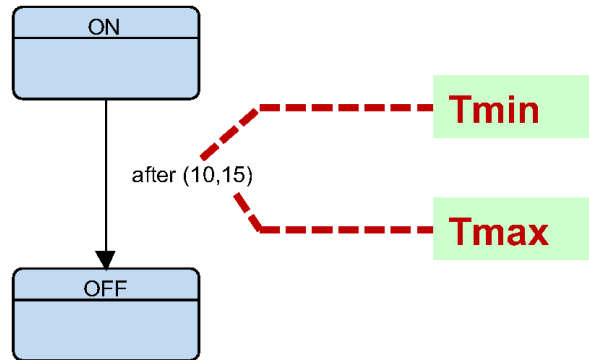
# State Machines - Guards

- A transition guard contains a *boolean expression* built upon boolean operators and attributes



## State Machines - Time Intervals

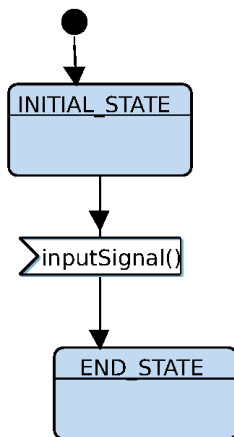
- *after* clause with a [Tmin, Tmax] interval



- A transition with no *after* clause has de facto an **after(0,0)** clause, which means the transition may be fired "immediately"

## State Machine - Inputs (1/3)

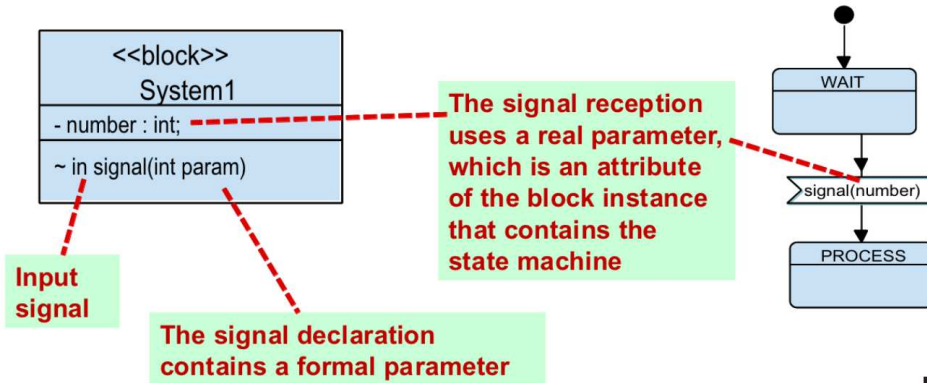
- A signal reception is a **transition trigger**



- The transition between INITIAL\_STATE and END\_STATE is triggered by a signal reception
- **Asynchronous communication**
  - FIFO-based
  - The transition is fired if  $size(FIFO, inputSignal) > 0$
- **Synchronous communication**
  - The transition is fired whenever a rendezvous is possible
- Signals can convey parameters

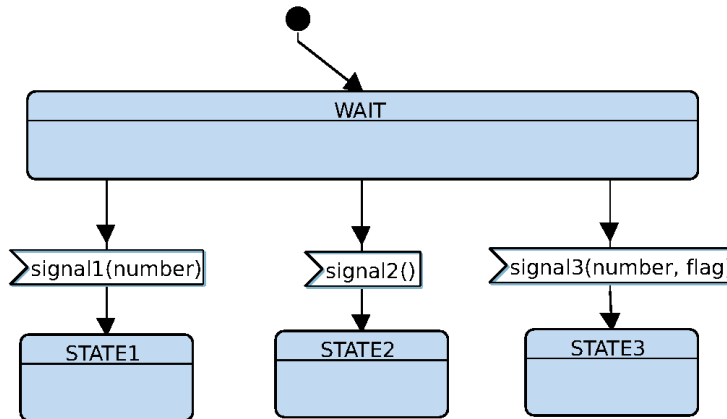
## State Machine - Inputs (2/3)

- Signal parameters, if any, are stored in attributes of the block instance that receives the signal



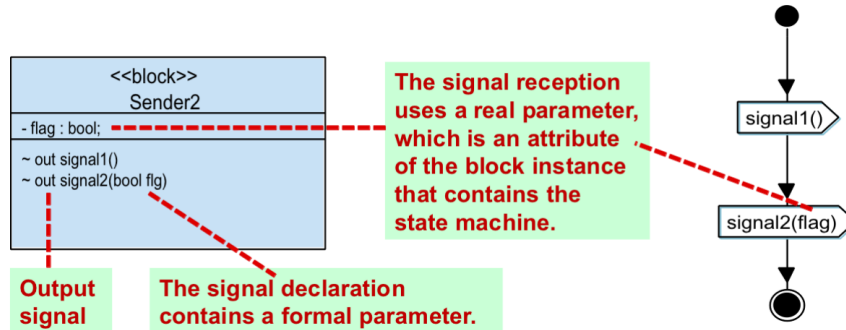
## State Machine - Inputs (3/3)

- From the same state it is possible to wait for several signals
  - Asynchronous communication: the first signal in the input queues triggers the transition
  - Synchronous communication: The first ready-to-execute rendezvous triggers the transition



## State Machine - Ouputs

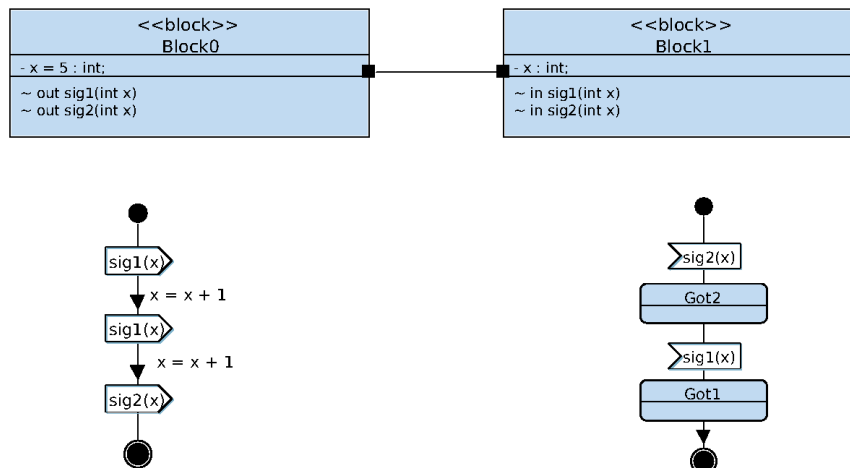
- A block instance can send signals with several parameters
  - Constant values may not be used as real parameters → use attributes instead



- A block instance cannot send two or several signals in parallel but it can send two or more signals in sequence

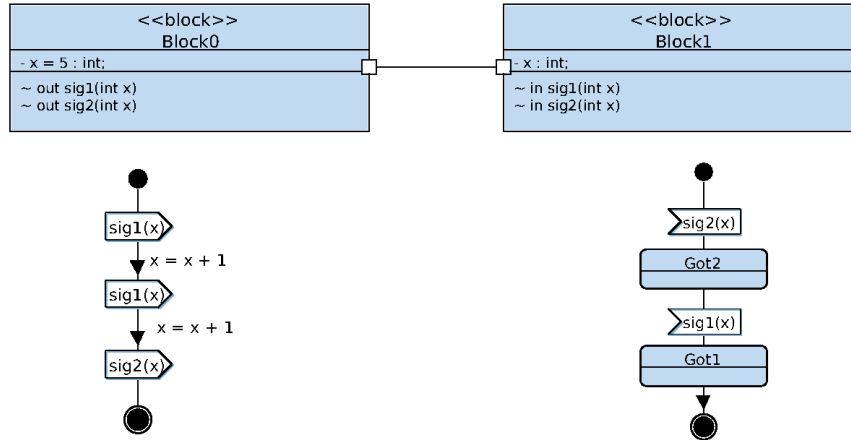
## Synchronous Communications

- Sender and receiver synchronizes on the same signal
- Data exchange from the writer to the reader



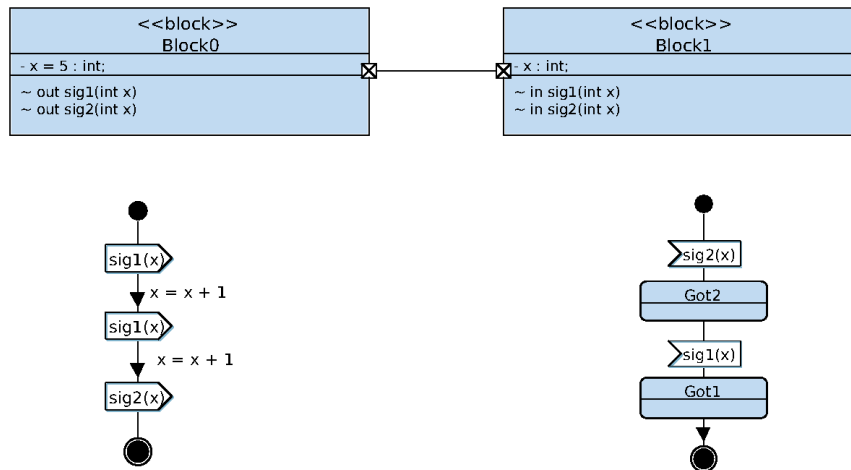
## Non-Blocking Asynchronous Communications

- One FIFO per signal association
- Writing is **NOT** blocked when the FIFO is full
  - Bucket approach when FIFO is full: new messages are dropped
- Example: we assume a FIFO of size 1



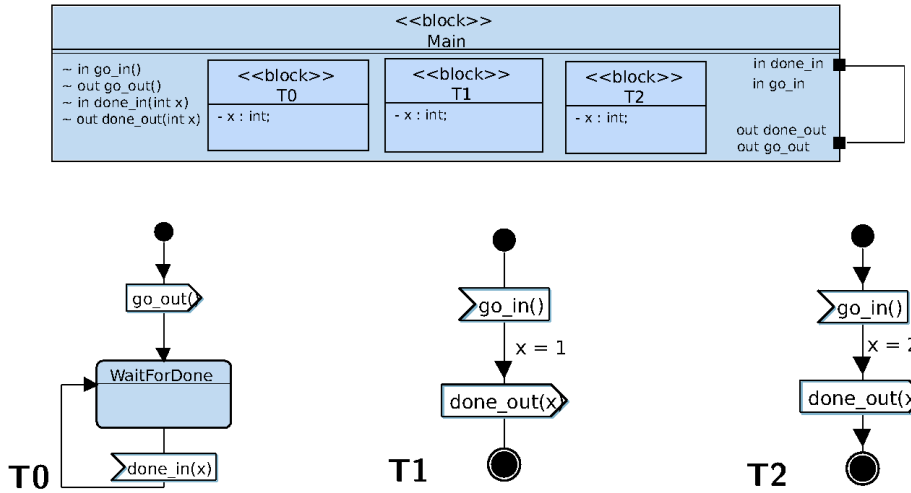
## Blocking Asynchronous Communications

- One FIFO per signal association
- Writing is blocked when the FIFO is full
- Example: we assume a FIFO of size 1



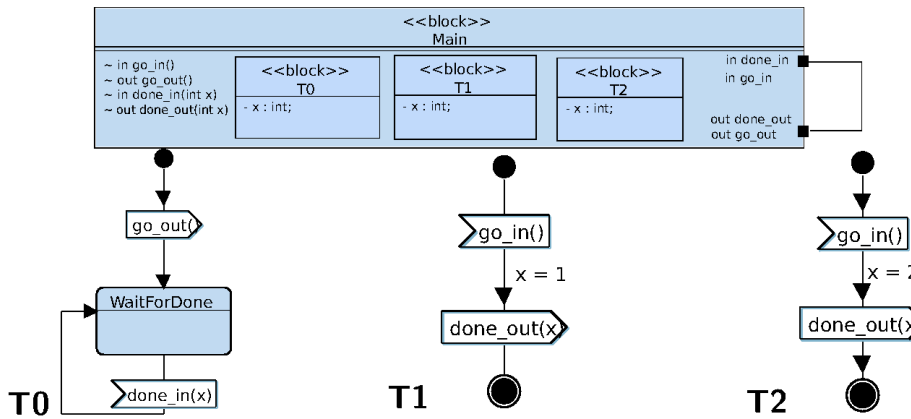
# State Machine - Advanced I/O

- Signals declared by a block may be used by its sub-blocks



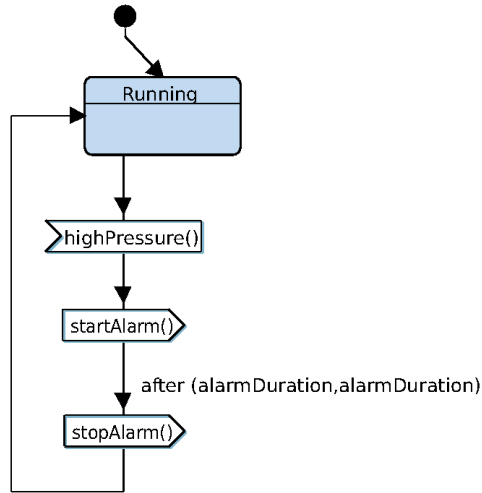
# Broadcast Channel

- All blocks ready to receive a signal sent over a broadcast channel receive it
- So, what happens if the channel below is now set to *broadcast*?



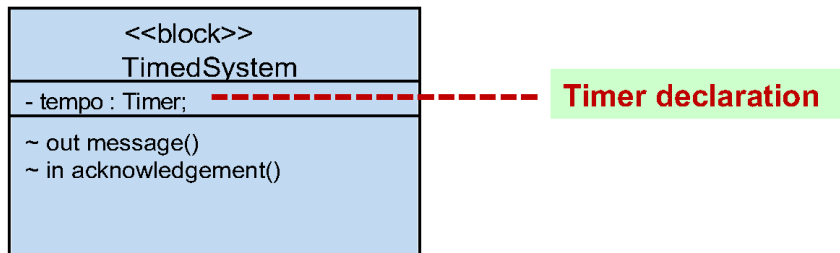
# State Machine Diagram - Pressure Controller

- Shows the inner functioning of the *Controller* block instance



# State Machines - Timers (1/3)

- **A timer must be declared as an attribute of the block instance which uses it**
  - Unlike attribute declarations, a timer declaration cannot contain an initial value
    - Use the set operator to initialize the duration of a timer
  - The signal issued by the timer at expiration time does not need to be declared



## State Machines - Timers (2/3)

**Set**

- The "set" operation starts a timer with a value given as parameter
- The timer is based on a global system clock

**Reset**

Prevents a previously set timer to send an expiration signal

**Expiration**

- A timer "timer1" sends is a signal named "timer1" to the block instance it belongs to
- ⇒ A timer expiration is handled as a signal reception



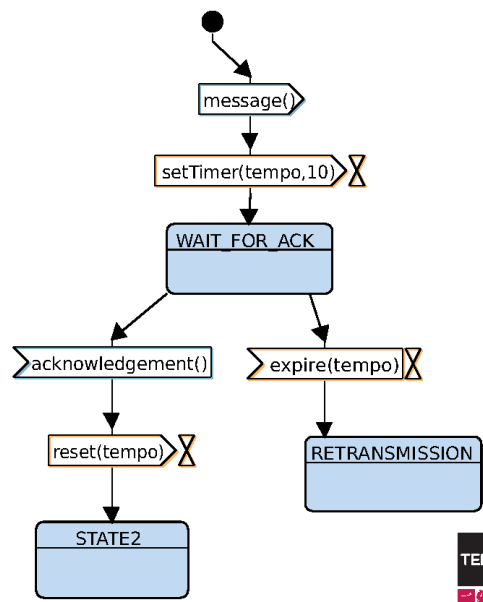
## State Machines - Timers (3/3)

"Temporally limited acknowledgement" with timers

A block instance may take decisions depending on the signal which arrives first: either a "normal" signal or a timer expiration

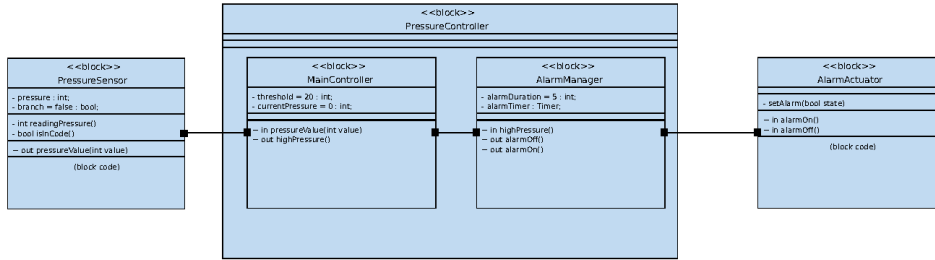
**Question**

Could we use an *after* clause instead of the *tempo* timer?

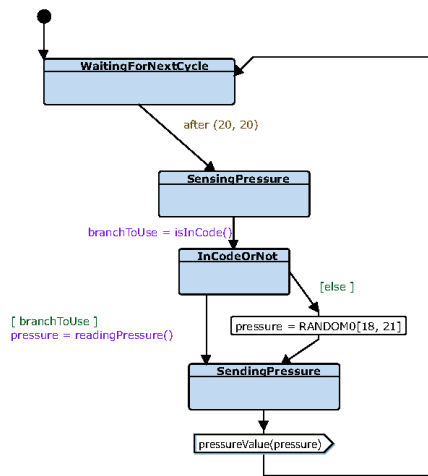




# Pressure Controller

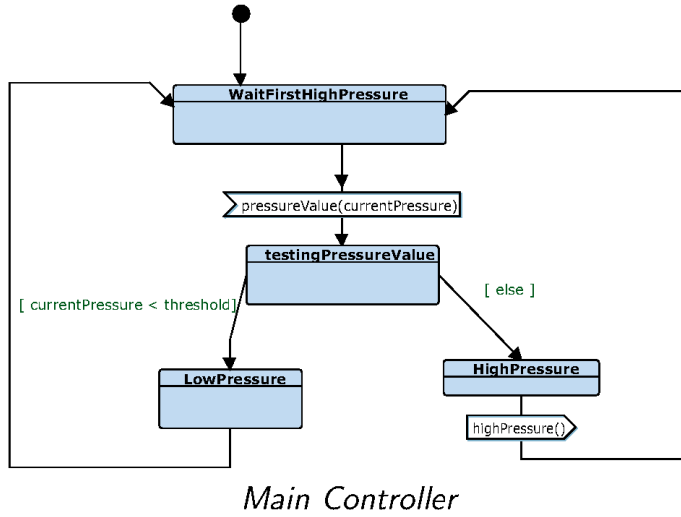


# Pressure Controller: States Machines

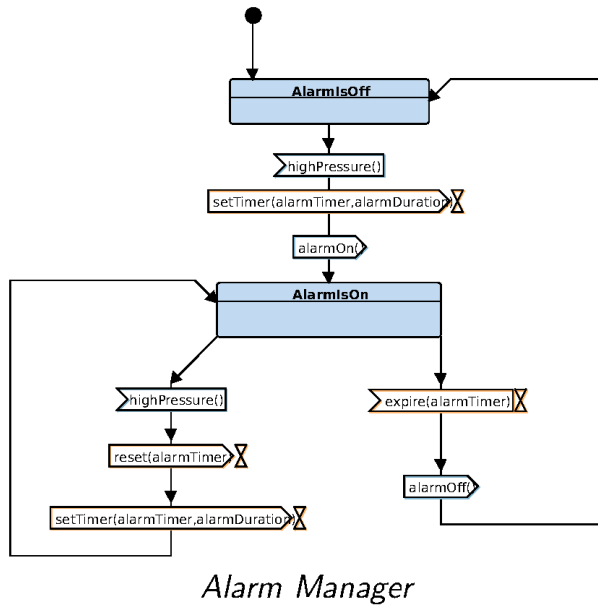


Pressure Sensor

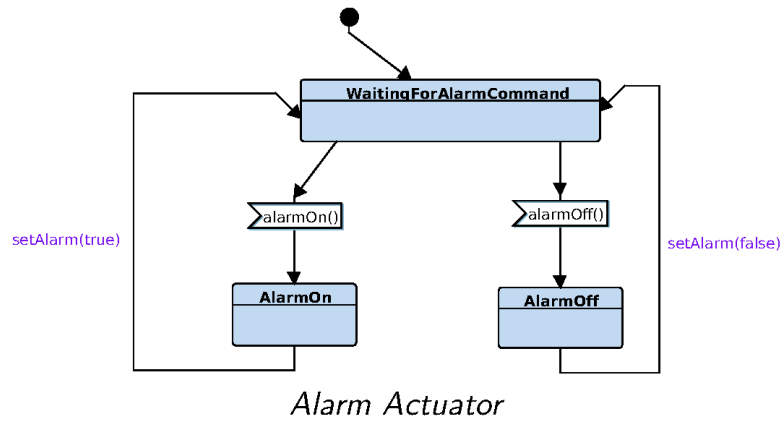
## Pressure Controller: States Machines



## Pressure Controller: States Machines



## Pressure Controller: States Machines



## How to Make "Good" Models?

Practice, Practice and Practice!!!

- Knowledge of various diagrams capabilities
- Accurate understanding of the system to model
- "Reading" your diagrams, reading diagrams of your friends, reading diagrams on Internet
- **Experience is a key factor**

→ **Make exercises!**