

V) Rethinking Disclosure Prevention with PML

1) Differential Privacy

How to keep **anonymity** when computing statistics about medical records, personal incomes, survey responses, ... ?

Let X be the set of values that individuals can have, and let $\mathcal{D} = X^N$ where N is the number of individuals.

d and d' of \mathcal{D} are called **neighbors** if they differ in only one individual.

Let \mathcal{Y} be the set of possibly outputted values and let Y be the outputted value characterized by $P_{Y|D}$. Since \mathcal{Y} can be infinite, we call \mathcal{T} the set of measurable sets by any $P_{Y|D=d}$. We call $\mathcal{M}(d)$ the random variable $Y|D=d$. We say

that \mathcal{M} is ϵ -differentially private iff $\forall S \in \mathcal{T}, \log\left(\frac{P(\mathcal{M}(d) \in S)}{P(\mathcal{M}(d') \in S)}\right) \leq \epsilon$,
for any pair of neighbors (d, d') .

k-anonymity characterizes a dataset $d \in \mathcal{D}$ and it is just the fact that $\forall x \in X, |\{i \in [N] \mid d_i = x\}|$ is either bigger than k or equal to zero.

↳ This way we can release data about what do people vote or what is the frequency of a given disease, right? \rightarrow Well we need to be cautious; what if k persons voted for the same person and live in the same place (like a family) then we can identify them. We introduce **l-diversity**: we add the condition that the groups should have **diversity** so we can't identify them all.

We can represent a data-set by a table :

id	QI	SA

- id : Not directly in the matrix, this is only the number of the line

$T =$

- Quasi-Identifiers : Zip code, Age, ...

- Sensitive-Attributes : Disease, Vote, ...

k -anonymity only is for QI, so if there is a leak, we cannot know what are your SA, unless all k have the same SA.

We can easily define the k -anonymity equivalence classes by $a \sim b$ iff $QI[a] = QI[b]$.

k -anonymity $\Leftrightarrow \forall EC, |EC| \geq k$ (EC means Equivalence Class)

l -diversity $\Leftrightarrow \forall EC, |SA(EC)| \geq l$ (implies l -anonymity)

↪ One can find other variants of l -diversity.

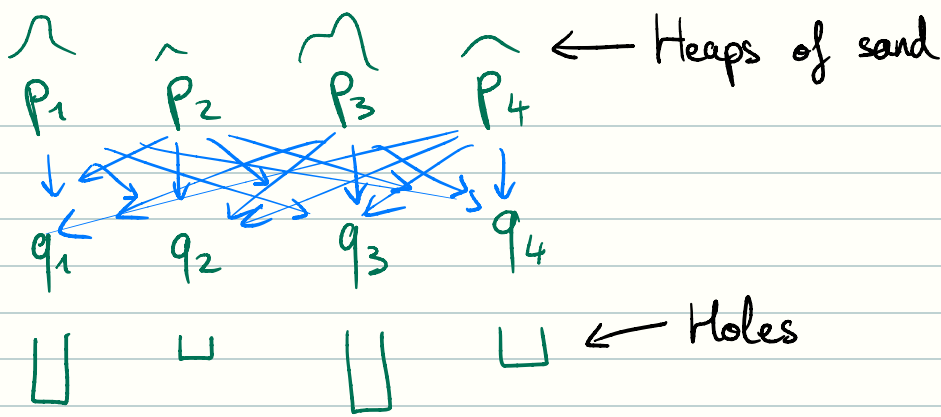
l -diversity is still weak : imagine an EC with 99% of a very rare SA, then it leaks very strong information. The empirical distribution of $SA(EC)$ must be close to the whole database SA distribution.

The data-base T satisfies t -closeness according to some distance $D: \Delta(SA) \rightarrow \mathbb{R}_+$ iff $\forall EC, D(P_{SA|_{i \in EC}}^{(emp)}, P_{SA}^{(emp)}) \leq t$. Emp means "empirical".

Remark: t -closeness gives l -diversity and k -anonymity guarantees (for every distance?).

Example: Given $P = (p_1, \dots, p_k)$ and $Q = (q_1, \dots, q_k)$ element of $\Delta(SA)$, a transport plan is a $k \times k$ matrix γ such that γ_{ij} shows the amount that we take from p_i to put it on q_j (could be negative but this is useless). This transport plan is said to be valid if

$$\begin{cases} \forall i \in [k], \sum_j \gamma_{ij} = p_i \\ \forall j \in [k], \sum_i \gamma_{ij} = q_j \end{cases}$$



The set of valid transport matrices is called $\Gamma(P \rightarrow Q)$. For instance, we can simply check that $\Gamma(P \rightarrow Q) = \Gamma(Q \rightarrow P)^T$.

Finally, we define a function between the heaps $(x_i)_{i \in [k]}$ and the holes $(y_j)_{j \in [k]}$. The Earth Mover's Distance or the Optimal Transport Distance, is defined by:

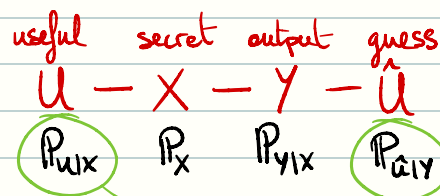
$$EMD(P, Q) = \inf_{\gamma \in \Gamma(P \rightarrow Q)} \sum_{i,j} \gamma_{ij} d(x_i, y_j).$$

A particular case of this, is if we only have a distance $d: SA^2 \rightarrow \mathbb{R}_+$ on SA , then

$$EMD(P, Q) = \inf_{\gamma \in \Gamma(P \rightarrow Q)} \sum_{i,j} \gamma_{ij} d(i, j).$$

2) Preliminaries

Again we recall the setup:



The min-entropy is defined as $H_\infty(X) = -\log(\max_x P_X(x))$ or, accordingly to its name, $H_\infty(X) = \log(\min_x \frac{1}{P_X(x)})$.

The min-leakage is given by $L_\infty(X, Y) = H_\infty(Y) - H_\infty(Y|X)$.

The min-capacity is given by $C_\infty(P_{Y|X}) = \sup_{P_X} L_\infty(X, Y)$.

Let $(\Omega, \mathcal{X}, \mu)$ be a measure space and let P and Q random variables $\ll \mu$ of Ω with respective pmf p, q . The Renyi Divergence of order ∞ of P from Q is defined by $D_\infty(P \| Q) = \text{ess sup} [\log(p) - \log(q)]$ assuming that $(-\infty) - (-\infty) = 0$.

We recall that Maximal Leakage is given by:

$$L(X \rightarrow Y) = \inf_{P_Y^*} D_\infty(P_X P_Y^* \| P_{X,Y})$$

Surprisingly, for a fixed support of X , this only depends on $P_{Y|X}$

Well Pointwise Maximal Leakage is given by:

$$l(X \rightarrow Y) = D_\infty(P_{X|Y=y} \| P_X)$$

Let \mathcal{P} be a subset of all possible distributions for X . A channel $X \rightarrow Y$ is said to satisfy (ϵ, \mathcal{P}) -PML if $\forall P_X \in \mathcal{P}, P_Y(\{y \in \mathcal{Y} \mid l(X \rightarrow y) \leq \epsilon\}) = 1$
or, equivalently, $\sup_{P_X \in \mathcal{P}} D_\infty(P_{X,Y} \| P_X P_Y) \leq \epsilon$.

Proof of the equivalence: $D_\infty(P_{X,Y} \| P_X P_Y) = \text{ess sup} \log i(x, y)$

and $l(X \rightarrow Y) = \max_x i(x, y)$, so we just follow the definitions.

If the density of Y is continuous for a given $X = x$, then the two conditions above also are equivalent to $\forall P_X \in \mathcal{P}, \forall y \in \mathcal{Y}, l(X \rightarrow y) \leq \epsilon$.

A channel $X \rightarrow Y$ is said to satisfy ϵ -PML if $\max_{x \in \mathcal{X}} i(x, y) \leq \epsilon$ almost everywhere on \mathcal{Y} , i.e. $D_\infty(P_{X,Y} \| P_X P_Y) \leq \epsilon$, for the real distribution of x .

The leakage capacity can be defined as

$$C_{\mathcal{L}}(X \rightarrow Y) = \max_{x, x'} \sup_y \log \frac{P_{Y|X=x}(y)}{P_{Y|X=x'}(y)}$$

Why sup instead of essup?

Can be infinite

Theorem: $\sup_{P_x} D_{\infty}(P_{xy} \| P_x P_y) = C_{\mathcal{L}}(X \rightarrow Y)$

Proof: On the LHS, we have $\log \frac{P_{Y|X=x}(y)}{P_Y(y)}$ ⁽¹⁾. On the RHS, we have

$\log \frac{P_{Y|X=x}(y)}{P_Y(y)} - \log \frac{P_{Y|X=x'}(y)}{P_Y(y)}$ ⁽²⁾. LHS \leq RHS is clear since we can

easily find an x' such that $P_{Y|X}(y|x') \leq P_Y(y)$. We now want LHS \geq RHS.

Let $y^* \in \mathcal{Y}$ as close to the supremum as we need, and let x_{\min} and x_{\max} the values maximizing the expression. Then we chose the following P_x : $\begin{cases} P_x(x_{\min}) = 1 - \alpha \\ P_x(x_{\max}) = \alpha \end{cases}$

Then LHS $\geq \max_x \log \frac{P_{Y|X}(y^*|x)}{P_Y(y^*)} = \log \frac{P_{Y|X}(y^*|x_{\max})}{\alpha P_{Y|X}(y^*|x_{\max}) + (1-\alpha)P_{Y|X}(y^*|x_{\min})}$ \rightarrow Definition of x_{\max}

The limit when $\alpha \rightarrow 0$ is RHS \square

⁽¹⁾ Depends on P_x ⁽²⁾ Does not depend on P_x

3) Impossibility of Absolute Disclosure Prevention

Setup of Dwork and Naor (2010): - P_x is known

- The classic Markov chain $U - X - Y$:

* $P_{U|X}$ is known

* $H(P_U)$ is large

* $\exists y, H(P_{U|Y=y})$ is small

- There is another Markov chain $W - X - Y$:

* $H(W) < H(U)$

* $H(P_W)$ is large

* $\forall y, H(P_{W|Y=y})$ is large

Global = Small entropy i.e. less useful information that is commonly known.

Local = High entropy i.e. very rare and useful information.

Our setup: Prior belief $Q_X \in \Delta(X)$. But actually, we don't care. \rightarrow Worst case: $Q=P$.

We say that the channel $X \rightarrow Y$ **discloses** the value of u iff $\inf_y H_\infty(P_{u|Y=y}) = 0$.

Theorem 3.5: $\epsilon \geq 0$

Assume $H_\infty(P_u) > \epsilon$. If $D_\infty(P_{XY} \| P_X P_Y) \leq \epsilon$, then any disclosure is impossible for any prior.

Remarks: i) It does not mean that we leak the same information to all priors. If $I_Q(X \rightarrow Y) > I(X \rightarrow Y)$ then we give more info to Q . If $I(X \rightarrow Y) > I_Q(X \rightarrow Y)$ then that's a pity since Q will not realize how rare is this information

ii) We only care of the true prior P .

iii) The condition of the theorem simply is $(\epsilon, \{P_X\})$ -PML. However, if P_X is unknown but we know that P_X is in some \mathcal{P} , then the theorem remains valid with (ϵ, \mathcal{P}) -PML guaranty.

Theorem 3.7 (Absolute Disclosure Prevention): Let V be a non-constant but deterministic function of X . Therefore,

$$H_\infty(P_{V|Y=y}) \geq \log\left(1 + \frac{\min_x q_X(x)}{1 - \min_x q_X(x)} e^{-C_X(X \rightarrow Y)}\right)$$

So if $C_X(X \rightarrow Y) < +\infty$ then any disclosure is impossible.

Note: $P_{V|Y=y}$ can be replaced by any adversarial prior $Q_{V|Y=y}$.

Understanding theorem 3.5: U is what we call a feature of X .

The main condition is $(\mathcal{E}, \mathcal{P})$ -PML with $P_x \in \mathcal{P}$. It splits the features of X in two categories:

$$H_\infty(P_u) > \mathcal{E}$$

Local features

"cannot be disclosed"

$$H_\infty(P_u) \leq \mathcal{E}$$

Global features

"May be disclosed"

How to pick \mathcal{E} ? Let x_{\min} be the least likely realization of X , $p_{\min} = P_x(x_{\min})$.

Let $\mathcal{E}^* = \log \frac{1}{1 - p_{\min}}$. Assume $P_{Y|X}$ satisfies $(\mathcal{E}, \{P_x\})$ -PML.

• If $\mathcal{E} < \mathcal{E}^*$, then no feature is disclosable; $C_x(X \rightarrow Y) < +\infty$.

• If $\mathcal{E} \geq \mathcal{E}^*$, then there exist a disclosable feature of X .

Proof: i) Assume $C_x(X \rightarrow Y) = +\infty$. We recall that:

Therefore, there exist $y_{\mathcal{E}} \in \mathcal{Y}$ such that $C_x(X \rightarrow Y) = \max_{x, x'} \sup_y \log \frac{P_{Y|X=x}(y)}{P_{Y|X=x'}(y)}$.

$$\max_{x, x'} \frac{P_{Y|X=x}(y)}{P_{Y|X=x'}(y)} \geq \frac{1}{\mathcal{E}}$$

Then, we can easily show that $\text{ess sup}_y I(X \rightarrow Y) \geq \mathcal{E}^*$.

ii) Let $U = \delta_X^{x_{\min}}$, and assume $\mathcal{E} = \mathcal{E}^*$. Let $\alpha > 0$. We construct

the following channel: • if $X = x_{\min}$, then $Y = 1$

• if $X \neq x_{\min}$, then $Y \hookrightarrow \mathcal{B}(1 - \alpha)$

The more α is small, the less $P_{Y|X}$ leaks about x_{\min} . For α small enough, we have (\mathcal{E}, P_x) -PML, and we easily verify that

$P_{Y|U}(0|u) = \begin{cases} 0 & \text{if } u=0 \\ \alpha & \text{if } u=1 \end{cases}$. So if we observe $Y=1$, we reduced U to a single point. $H(U|Y=1) = 0$ and we're done. \square

We say that $X \rightarrow Y$ singles out if it discloses the value of X :

$$\inf_y H_\infty(P_{X|Y=y}) = 0$$

If we have (ϵ, P) -PML then if $\epsilon < H_\infty(X)$, we are guaranteed the channel does not single out.

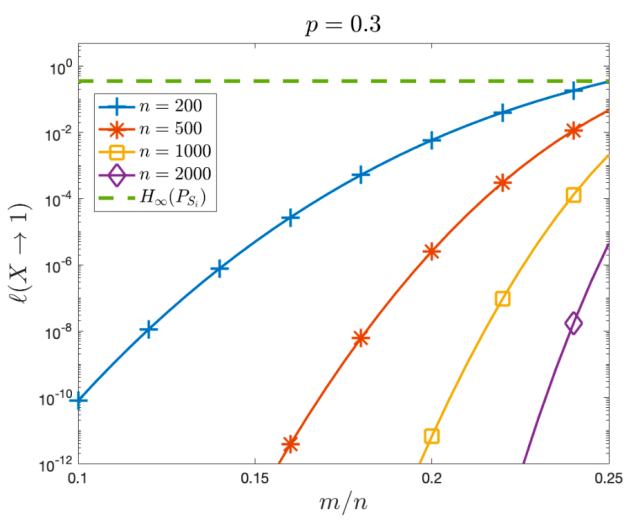
Example 3.11: $X = (D_1, \dots, D_n)$ let $S_i = 1$ iff i is a woman, and $Y =$ "More than m women?" then $S_i - X - Y$.

We assume that $p = 0.3$ and $\frac{m}{n} \leq p$. We have that

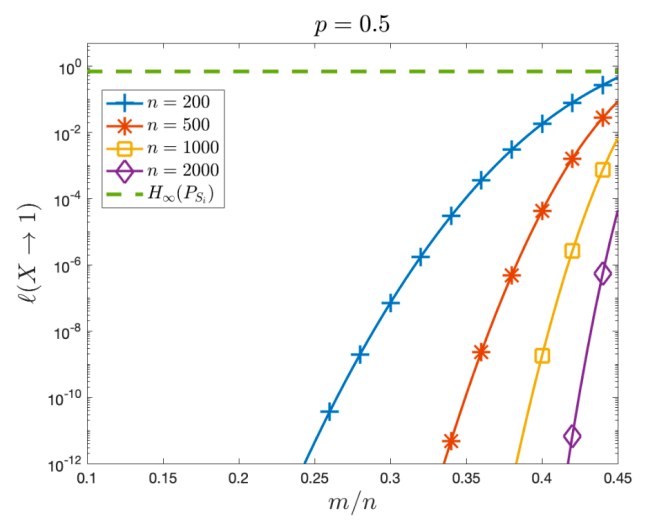
$$l(X \rightarrow 1) = \log \max_x \frac{P_{Y|X=x}(1)}{P_Y(1)} = \log \frac{1}{P_X(\text{more than } m \text{ women})} = -\log(1 - \sum_{k=0}^m p^k (1-p)^{n-k} \binom{n}{k})$$

let $i \in [n]$. $H_\infty(P_{S_i}) = \log\left(\frac{1}{1-p}\right) \approx 0.36$.

The gender of no individual will be disclosed as long as $\begin{cases} l(X \rightarrow 1) \leq 0.36 \\ l(X \rightarrow 0) \leq 0.36 \end{cases}$.



(A) Leakage bounds when $p = 0.3$.



(B) Leakage bounds when $p = 0.5$.