# Optimal transport between GMM for multiscale texture synthesis

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# 1) Patch Optimal Transport for Texture Synthesis

GOAL: Texture synthesis from an example  $u: \Omega \to \mathbb{R}^d$ 

Proposed Solution: Patch-based Multiscale Synthesis:

• Compute original at scales  $s = 0, \ldots, S - 1$ ,

 $u_s: \Omega_s \to \mathbb{R}^d$  with  $\Omega_s \subset 2^s \mathbb{Z}^2$ 

- Extract target patch distributions  $\nu_s$  at scale s



# 2) Gaussian Mixture Models

**Definition 1** We say that  $\mu \in \mathsf{GMM}_d(K)$  if

$$\mu = \sum_{k=1}^{K} \pi_k \mathcal{N}(m_k, \Sigma_k) \text{ with } \begin{cases} \pi \in \mathbb{R}^K_+, \ \sum \pi_k = 1\\ m_k \in \mathbb{R}^d, \ \Sigma_k \text{ s.d.p} \end{cases}$$

The set of such GMM is denoted by  $\operatorname{GMM}_d(K)$ , and let

 $CNANA = \int \int CNANA (K)$ 

• Apply patch optimal transport at each scale in order to reimpose the patch distribution  $\nu_s$  on the gravity current synthesis.

Patches are defined on a square domain  $\omega$  of size  $w \times w$ .

# 3) Gaussian Optimal Transport

Let  $\mu_0, \mu_1$  be two probability measures on  $\mathbb{R}^d$ .

$$W_2^2(\mu_0,\mu_1) := \inf_{\gamma \in \Pi(\mu_0,\mu_1)} \int \|y_0 - y_1\|^2 d\gamma(y_0,y_1),$$

where 
$$\Pi(\mu_0, \mu_1)$$
 is the set of measures on  $\mathbb{R}^d \times \mathbb{R}^d$   
with marginals  $\mu_0, \mu_1$ .  
If  $\mu_0 = \mathcal{N}(m_0, \Sigma_0), \mu_1 = \mathcal{N}(m_1, \Sigma_1)$ , then  
 $W_2^2(\mu_0, \mu_1) = ||m_0 - m_1||^2$   
 $+ \operatorname{Tr} \left( \Sigma_0 + \Sigma_1 - 2 \left( \Sigma_0^{\frac{1}{2}} \Sigma_1 \Sigma_0^{\frac{1}{2}} \right)^{\frac{1}{2}} \right),$ 

If  $\Sigma_0$  is non-singular, there is an optimal map

## 4) GMM Optimal Transport

Let 
$$\mu_0 = \sum_{k=1}^{K_0} \pi_0^k \mu_0^k$$
,  $\mu_1 = \sum_{k=1}^{K_1} \pi_1^k \mu_1^k \in \mathsf{GMM}_d$ .

**Definition 2** The GMM-OT cost is defined as

$$\inf_{\gamma \in \Pi(\mu_0,\mu_1) \cap GMM_{2d}} \int \|y_0 - y_1\|^2 d\gamma(y_0,y_1).$$

A solution  $\gamma^*$  will be called a **GMMOT plan**.

**Proposition 1** The GMM-OT cost has an equivalent discrete formulation:

$$MW_2^2(\mu_0,\mu_1) = \min \sum w_{kl} W_2^2(\mu_0^k,\mu_1^l)$$

$$\bigcup_{K\geq 1} \operatorname{Giviv}_d(K).$$

 $\rightarrow$  Inference from samples via Expectation-Maximization (EM algorithm)

### 5) GMM Transport map

The GMMOT plan between  $\mu_0$  and  $\mu_1$  is

 $\gamma(x,y) = \sum_{k,l} w_{k,l}^* g_{m_0^k, \Sigma_0^k}(x) \delta_{y=T_{k,l}(x)}.$ 

where  $(w_{k,l}^*)$  is a discrete OT plan for  $W^2(\pi_0, \pi_1)$ and  $T_{k,l}$  is the OT map between  $\mu_0^k$  and  $\mu_1^k$ .

**PROBLEM:** The GMMOT plan is not of the form  $(Id, T) # \mu_0!$ In practice, we use the **barycentric projection** 

$$T(x) = \frac{\sum_{k,l} w_{k,l}^* g_{m_0^k, \Sigma_0^k}(x) T_{k,l}(x)}{\sum_k \pi_0^k g_{m_0^k, \Sigma_0^k}(x)}.$$

 $\forall x \in \mathbb{R}^d, \quad T(x) = m_1 + \Sigma_0^{-1} (\Sigma_0 \Sigma_1)^{\frac{1}{2}} (x - m_0).$ 



The solution will be denoted by  $w^*$ .

### 6) Construction of the TextoGMM Model

**Initialize** with the Gaussian model  $U_{S-1} = \bar{u}_{S-1} + (u_{S-1} - \bar{u}_{S-1}) * Z$  (Z Gaussian white noise) For  $s = S - 1, \dots, 0$ ,

- Fit a GMM  $\mu_s$  (resp.  $\nu_s$ ) to the patch distribution of  $U_s$  (resp.  $u_s$ )
- Compute the GMMOT plan  $\gamma_s$  from  $\mu_s$  to  $\nu_s$ , and associated map  $T_s$
- Transport patches  $T_s(U_{s|a+2^s\omega})$  and find nearest neighbor  $u_{s|C_s(a)+2^s\omega}$  in  $u_s$
- Recompose patches:  $\forall a \in 2^s \mathbb{Z}^2$ ,  $V_s(a) = \frac{1}{|\omega|} \sum_{b \in 2^s \omega} u_s (C_s(a-b) + b)$
- Upsample:  $\forall a \in 2^s \mathbb{Z}^2, \forall k \in \{0, 2^{s-1}\}^2, \quad U_{s-1}(a+k) = \frac{1}{|\omega|} \sum_{b \in 2^s \omega} u_{s-1} (C_s(a-b) + b + k)$

**Output:** Synthesized texture  $V_0$ 

#### 7) Results: Synthesis with TextoGMM

#### Remarks - Conclusion

- One can estimate the model offline
- Patches are transformed independently  $\rightarrow$  Parallel computations
- Costly steps: EM, NN projections  $\rightarrow$  Random subsampling (10<sup>4</sup> patches)
- GMMOT compares favorably to other OT methods in terms of time. With patches:
   1' to solve GMMOT (including EM step)
   40' for 10<sup>3</sup> iterations of Sinkhorn
   150' for 10<sup>5</sup> iterations of stochastic solver

#### CONCLUDING REMARKS:

✓ TextoGMM can model structured textures.
 ✓ Model estimation is much faster than previous models based on semi-discrete OT.
 ✓ TextoGMM allows for mixing and inpainting.
 ✗ Still requires patch NN search/averaging...



 $\bigstar$  ... and the EM algorithm to learn GMM.

#### References

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