

# Parcimonie et Analyse de Données en Astrophysique

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Sparsity Everywhere

Sparsity Tour

Sparsity and inverse problems

Sparsity and PLANCK

Sparsity and Euclid

# What is Sparsity?

A signal  $s$  ( $n$  samples) can be represented as sum of weighted elements of a given dictionary

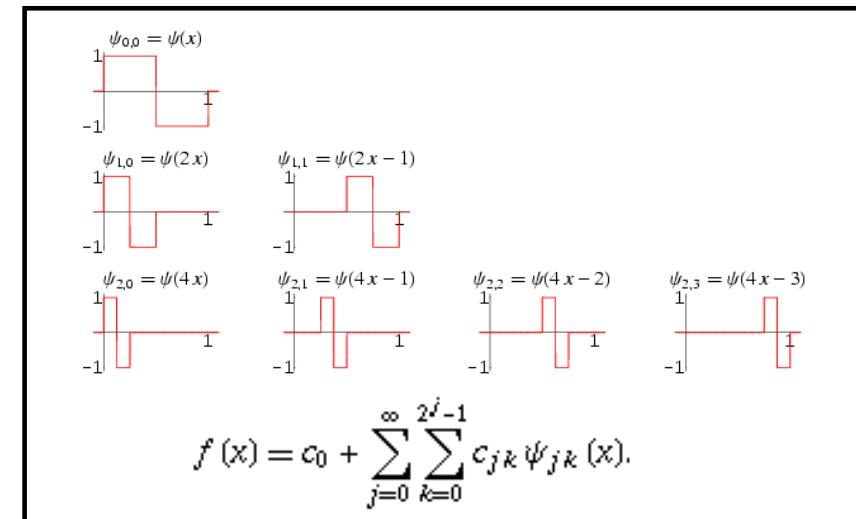
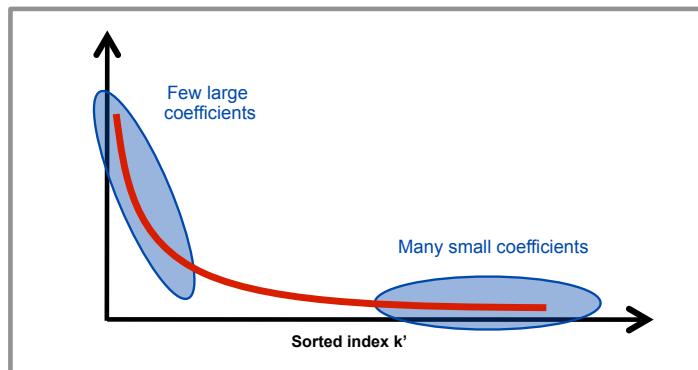
$$\Phi = \{\phi_1, \dots, \phi_K\}$$

Dictionary  
(basis, frame)

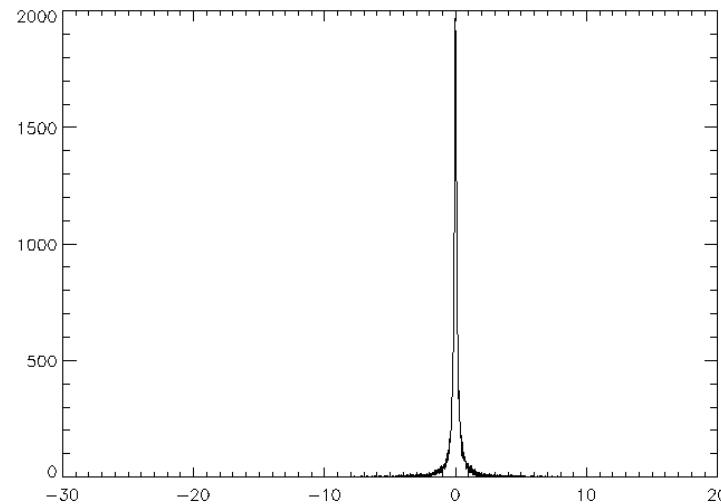
$\sum_{k=1}^K$  Atoms

$$s = \sum_{k=1}^K \alpha_k \phi_k = \Phi \alpha$$

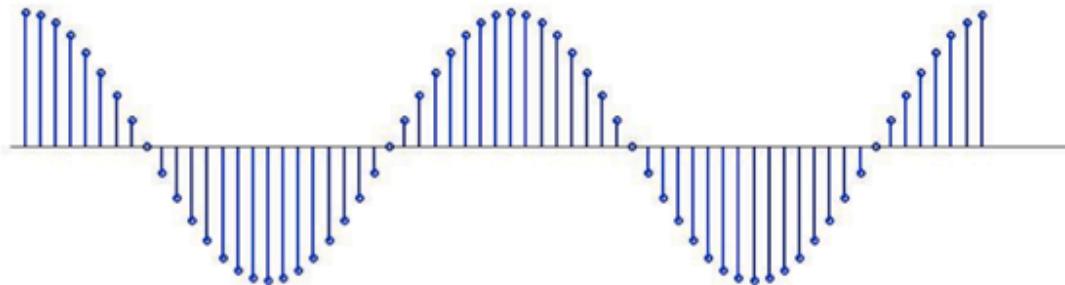
coefficients



- Fast calculation of the coefficients
- Analyze the signal through the statistical properties of the coefficients
- Approximation theory uses the sparsity of the coefficients



# Strict Sparsity: k-sparse signals



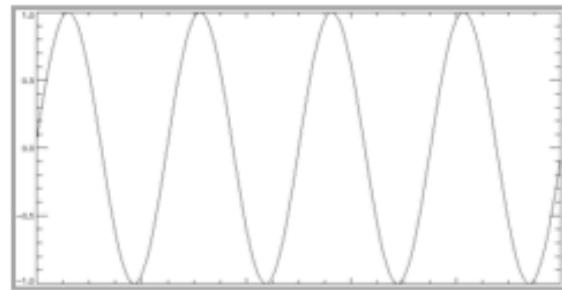
A sine wave in  
real space...

...can be a Dirac  
in Fourier space.

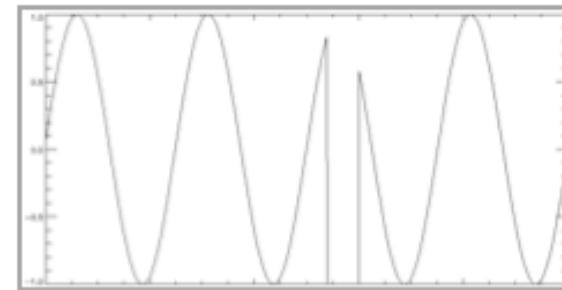


Sinusoids are  
sparse in the  
Fourier domain.

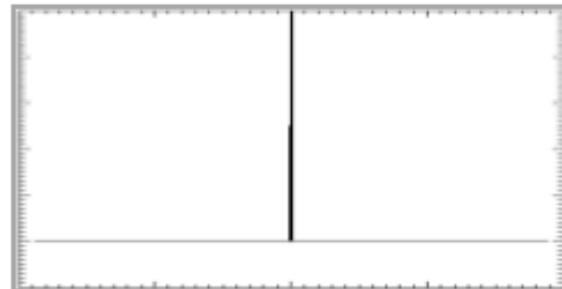
## Minimizing the $\ell_0$ norm



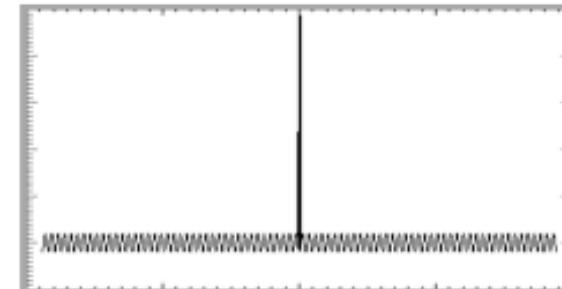
Sine curve



Truncated sine curve

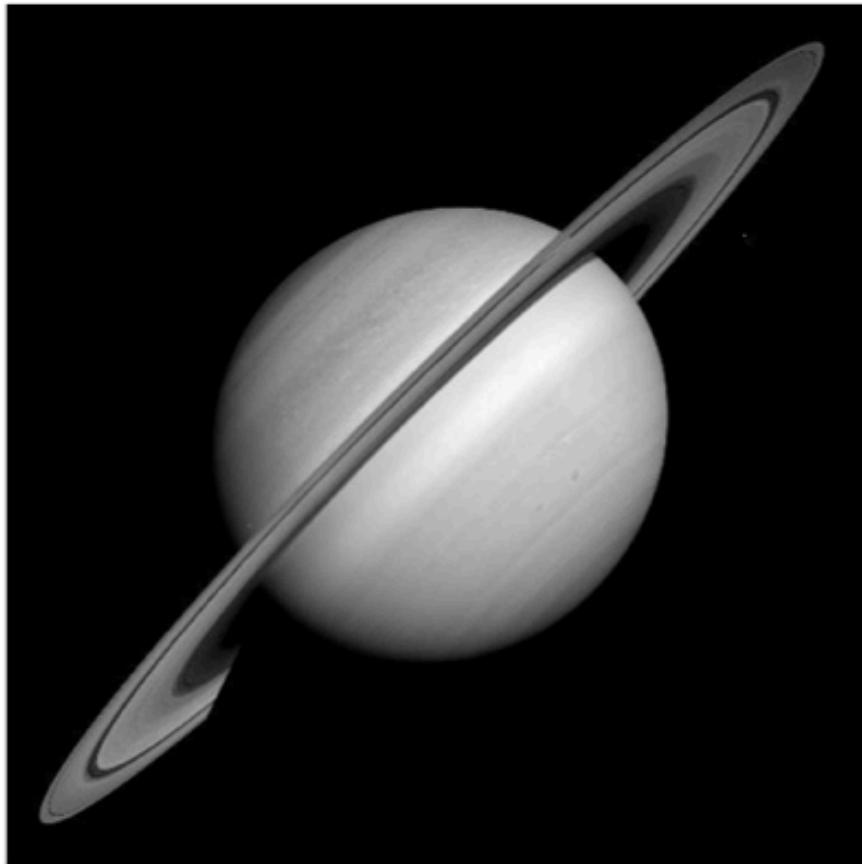


TF of a sine curve



TF of a truncated sine curve

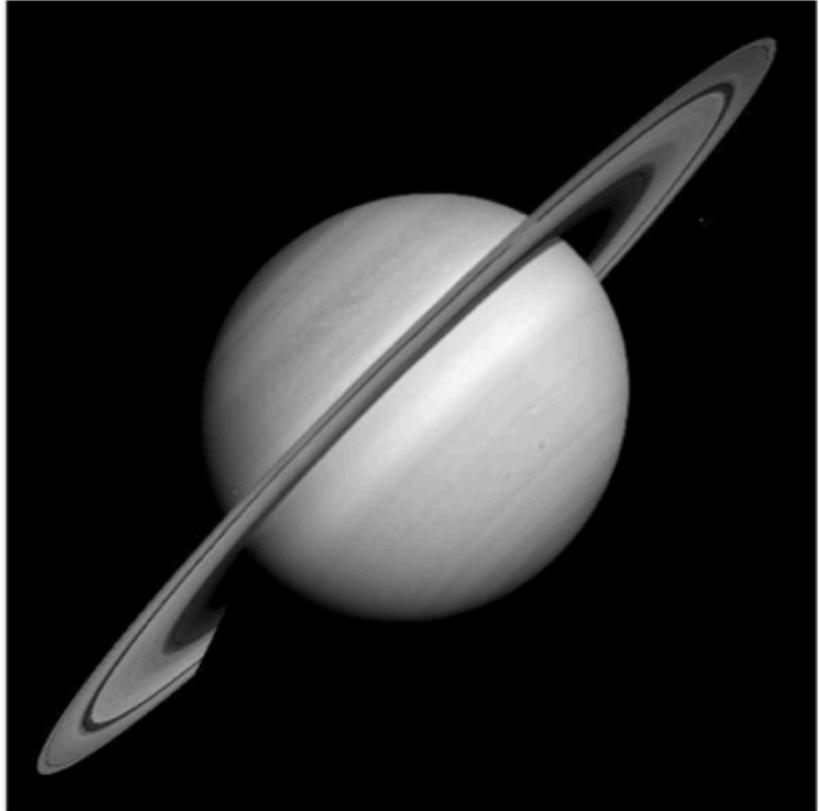
with  $0^0 = 0$ ,       $\| \alpha \|_0 = \sum_k \alpha_k^0 = \# \{ \alpha_k \neq 0 \}$



The top 1% of the  
coefficients concentrate  
only 8.66% of the energy.  
**Not sparse...**



1% largest coefficients in real space  
(the others are set to 0)

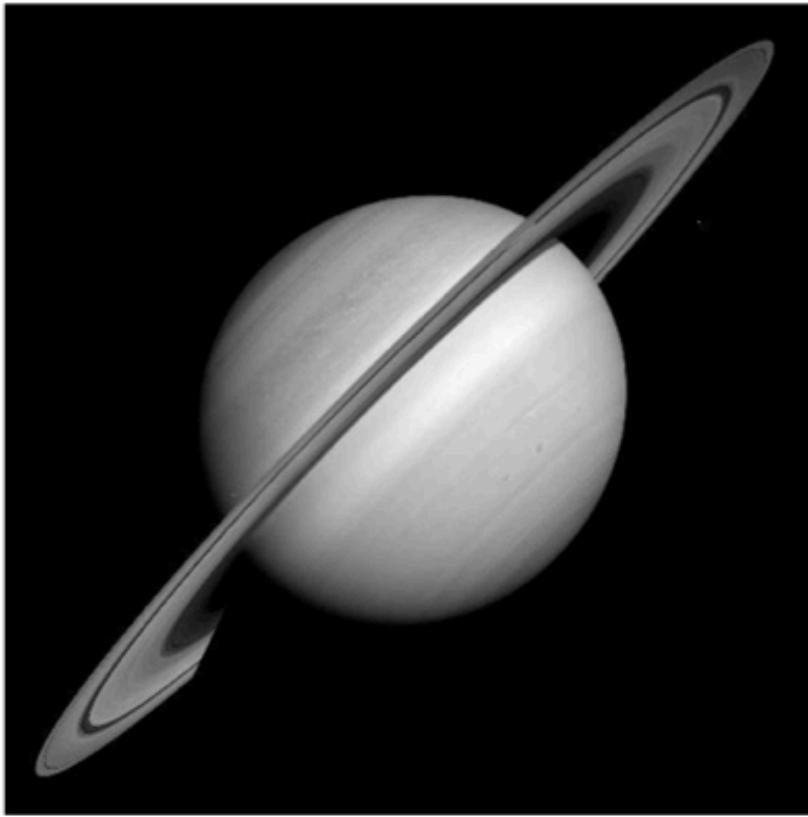


The wavelet  
coefficients encode  
edges and large scale  
information.

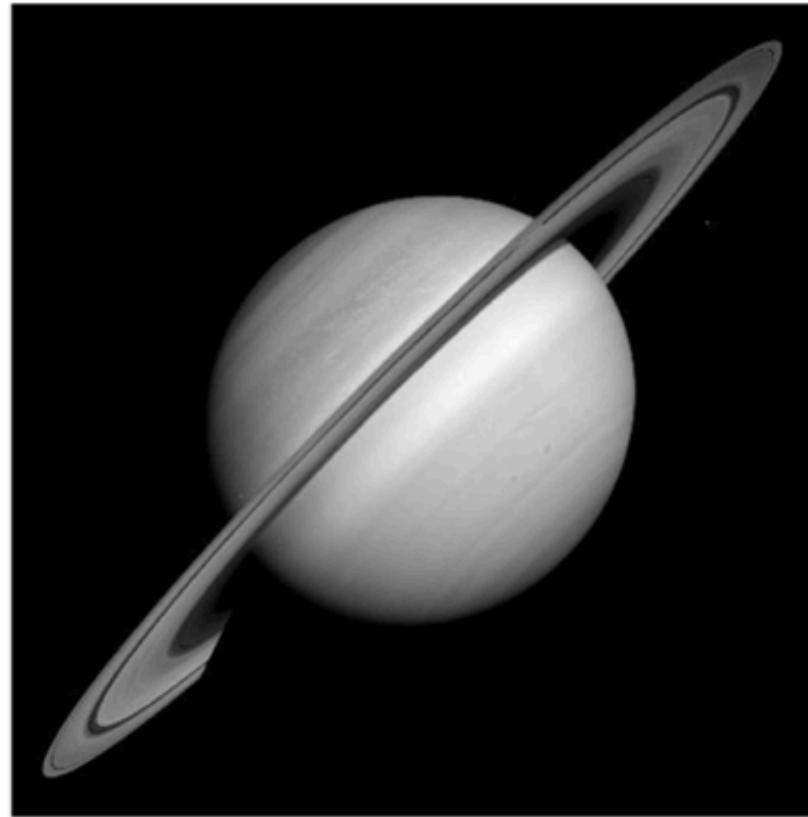


Wavelet transform

1% largest coefficients in wavelet space  
(the others are set to 0)



**1% of the wavelet coefficients  
concentrate 99.96% of the energy:  
This can be used as a *prior*.**



Reconstruction, after throwing away  
99% of the wavelet coefficients

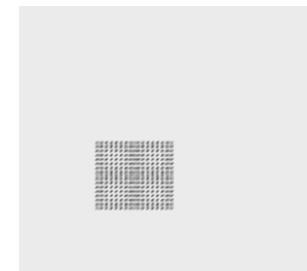
**Sparsity Model 1:** we consider a dictionary which has a fast transform/reconstruction operator:

$$\Phi = \{\phi_1, \dots, \phi_K\}$$

$$s = \sum_{k=1}^K \alpha_k \phi_k = \Phi \alpha$$

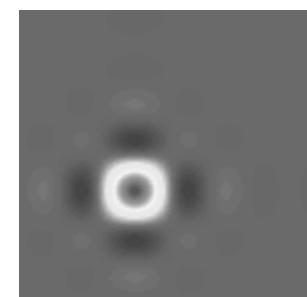
Local DCT

Stationary textures  
Locally oscillatory



Wavelet transform

Piecewise smooth  
Isotropic structures

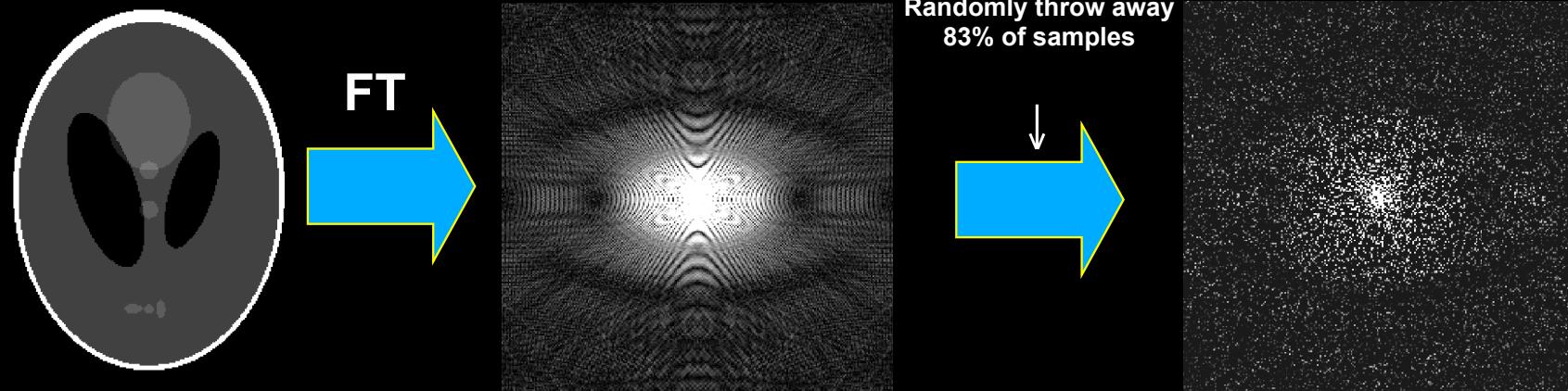


Curvelet transform

Piecewise smooth,  
edge

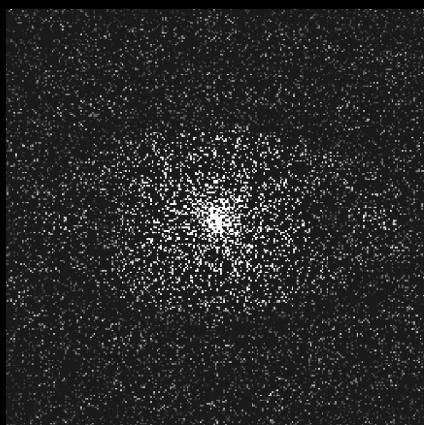
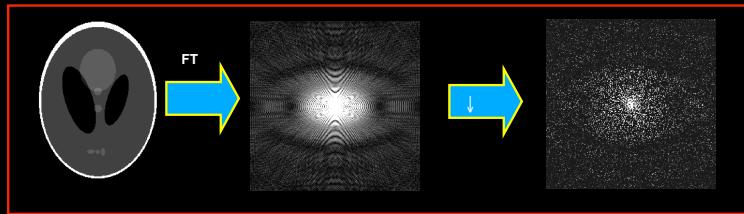


# A Surprising Experiment\*

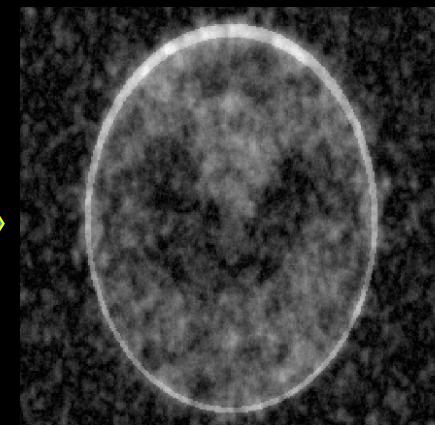


\* E.J. Candes, J. Romberg and T. Tao.

# A Surprising Result\*

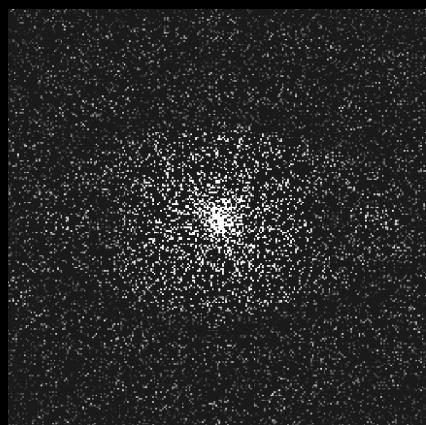
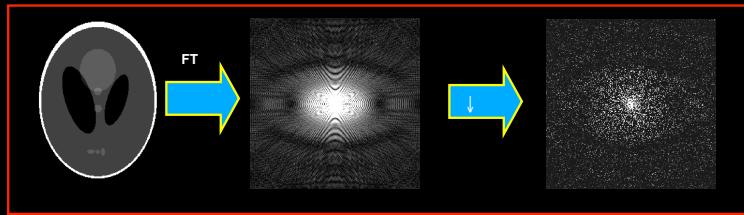


Minimum - norm  
conventional linear  
reconstruction

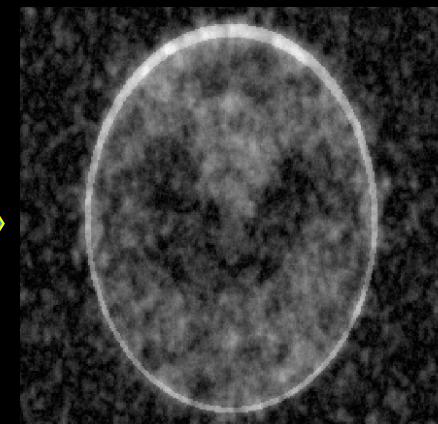


\* E.J. Candes, J. Romberg and T. Tao.

# A Surprising Result\*



Minimum - norm  
conventional linear  
reconstruction



$\ell_1$  minimization



E.J. Candes



# Compressed Sensing

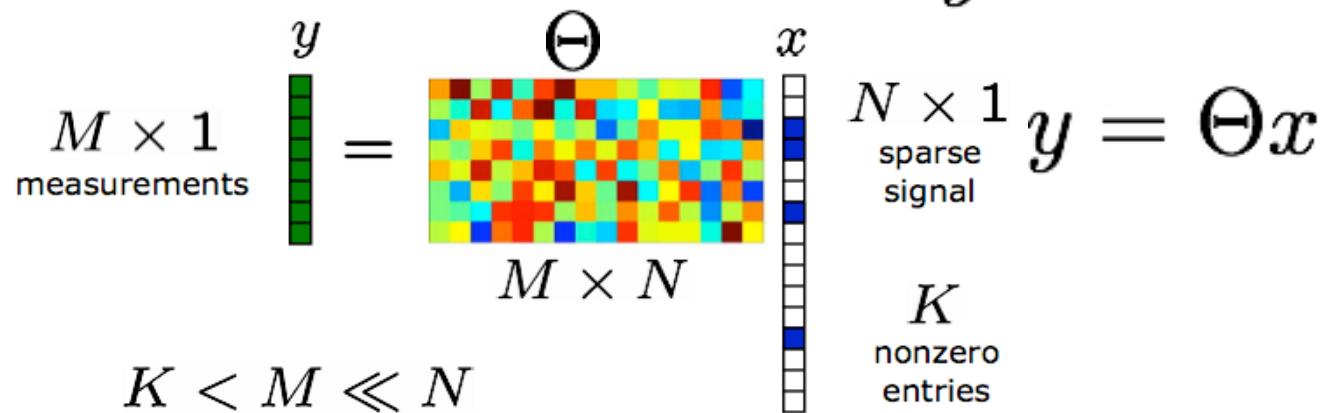


- \* E. Candès and T. Tao, "Near Optimal Signal Recovery From Random Projections: Universal Encoding Strategies?", IEEE Trans. on Information Theory, 52, pp 5406–5425, 2006.
- \* D. Donoho, "Compressed Sensing", IEEE Trans. on Information Theory, 52(4), pp. 1289–1306, April 2006.
- \* E. Candès, J. Romberg and T. Tao, "Robust Uncertainty Principles: Exact Signal Reconstruction from Highly Incomplete Frequency Information", IEEE Trans. on Information Theory, 52(2) pp. 489 – 509, Feb. 2006.

## A non linear sampling theorem

**“Signals with exactly K components different from zero can be recovered perfectly from  $\sim K \log N$  incoherent measurements”**

Replace samples with *few linear projections*  $y = \Theta x$



Reconstruction via non linear processing:

$$\min_x \|x\|_1 \quad \text{s.t.} \quad y = \Theta x$$

⇒ Application: Compression, tomography, ill posed inverse problem.

## Compressed Sensing Reconstruction

Measurements:

$$y_k = \langle x, \theta_k \rangle$$

Reconstruction via non linear processing:

$$\min_x \|x\|_1 \quad \text{s.t.} \quad y = \Theta_\Lambda x$$

In practice,  $x$  is sparse in a given **dictionary**:

$$x = \Phi \alpha$$

and we need to solve:

$$\min_{\alpha} \|\alpha\|_1 \quad \text{s.t.} \quad y = \Theta_\Lambda \Phi \alpha$$

The mutual incoherence is defined as

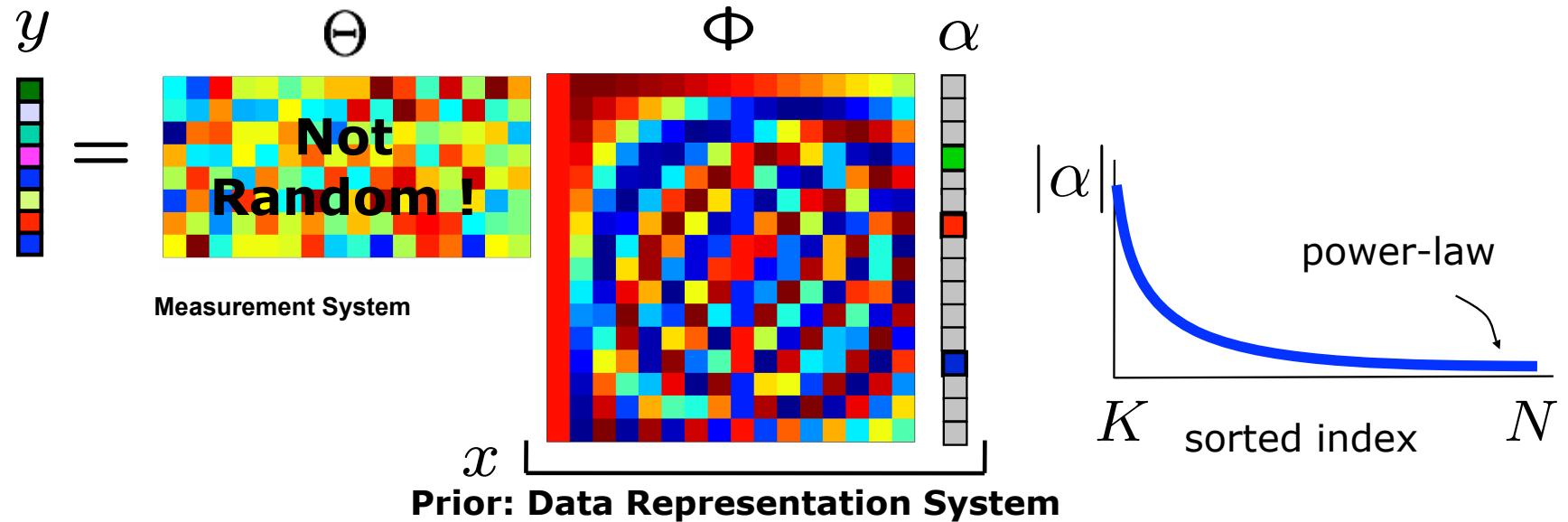
$$\mu_{\Theta, \Phi} = \sqrt{N} \max_{i,k} |\langle \phi_i, \theta_k \rangle|$$

the number of required measurements is :

$$m \geq C \mu_{\Theta, \Phi}^2 K \log n$$

## Soft Compressed Sensing Definition

$$Y = \Theta X = \Theta \Phi \alpha$$



Mutual coherence:

$$\mu_{\Theta, \Phi} = \max_{i, k} |\langle \Theta_i, \Phi_k, \rangle|$$

Mutual coherence the degree of similarity between the sparsity and measurement systems.

Reconstruction via non linear processing:

$$\min_{\alpha} \|\alpha\|_1 \text{ s.t. } y = \Theta \Phi \alpha$$

## How to measure sparsity ?

with  $0^0 = 0$ ,  $\|\alpha\|_0 = \sum_k \alpha_k^0 = \#\{\alpha_k \neq 0\}$

Formally, the sparsest coefficients are obtained by solving the optimization problem:

$$(P0) \text{ Minimize } \|\alpha\|_0 \text{ subject to } S = \phi\alpha$$

It has been proposed (*to relax and*) to replace the  $l_0$  norm by the  $l_1$  norm (Chen, 1995):

$$(P1) \text{ Minimize } \|\alpha\|_1 \text{ subject to } S = \phi\alpha$$

It can be seen as a kind of convexification of (P0).

*It has been shown (Donoho and Huo, 1999) that for certain dictionary, if there exists a highly sparse solution to (P0), then it is identical to the solution of (P1).*

==> Link the sparsity and the sampling through the Compressed Sensing.

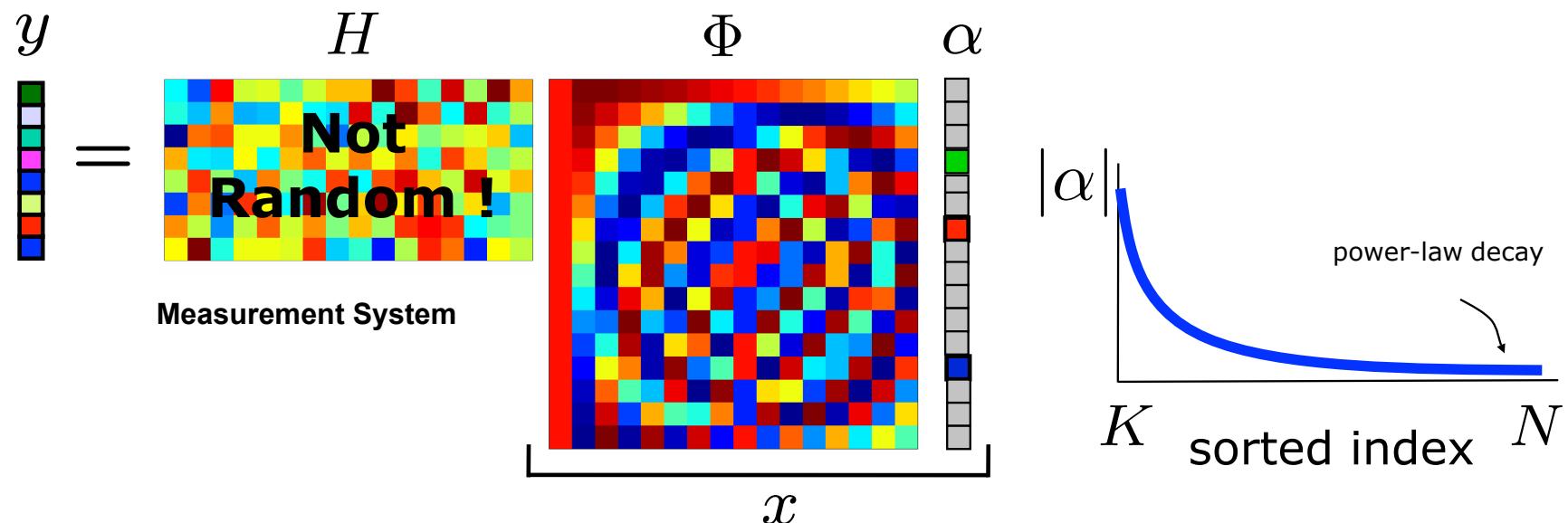
## INVERSE PROBLEM TOUR and SPARSE RECOVERY

$$Y = HX + N$$

$X = \Phi\alpha$ , and  $\alpha$  is sparse

- Denoising
- Deconvolution
- Component Separation
- Inpainting
- Blind Source Separation
- Minimization algorithms
- Compressed Sensing

$$\min_{\alpha} \|\alpha\|_p^p \quad \text{subject to} \quad \|Y - H\Phi\alpha\|^2 \leq \epsilon$$



# Denoising using a sparsity model

$$Y = X + N$$

**Denoising using a sparsity prior on the solution:**

$X$  is sparse in  $\Phi$ , i.e.  $X = \Phi\alpha$  where most of  $\alpha$  are negligible.

$$\tilde{\alpha} \in \arg \min_{\alpha} \frac{1}{2} \| Y - \Phi\alpha \|^2 + t \| \alpha \|_p^p, \quad 0 \leq p \leq 1.$$

**p=0**

$$\tilde{\alpha} \in \arg \min_{\alpha} \frac{1}{2} \| Y - \Phi \alpha \|^2 + \frac{t^2}{2} \| \alpha \|_0$$

$\implies$  Solution via Iterative **Hard Thresholding**

$$\tilde{\alpha}^{(t+1)} = \text{HardThresh}_{\mu t}(\tilde{\alpha}^{(t)} + \mu \Phi^T(Y - \Phi \tilde{\alpha}^{(t)})), \mu = 1/\|\Phi\|^2.$$

$$\tilde{\alpha}_{j,k} = \text{HardThresh}_t(\alpha_{j,k}) = \begin{cases} \alpha_{j,k} & \text{if } |\alpha_{j,k}| \geq t, \\ 0 & \text{otherwise.} \end{cases}$$

1st iteration solution:

$$\tilde{X} = \Phi \text{HardThresh}_t(\Phi^T Y) = \Delta_{\Phi,t}(Y)$$

Exact for  $\Phi$  orthonormal.

**p=1**

$$\tilde{\alpha} = \arg \min_{\alpha} \frac{1}{2} \| Y - \Phi \alpha \|^2 + t \| \alpha \|_1$$

==> Solution via iterative **Soft** Thresholding

$$\tilde{\alpha}^{(t+1)} = \text{SoftThresh}_{\mu t}(\tilde{\alpha}^{(t)} + \mu \Phi^T(Y - \Phi \tilde{\alpha}^{(t)})), \mu \in (0, 2/\|\Phi\|^2).$$

$$\tilde{\alpha}_{j,k} = \text{SoftThresh}_t(\alpha_{j,k}) = \text{sign}(\alpha_{j,k})(| \alpha_{j,k} | - t)_+$$

1st iteration solution:

$$\tilde{X} = \Phi \text{ SoftThresh}_t(\Phi^T Y) = \Delta_{\Phi,t}(Y)$$

Exact for  $\Phi$  orthonormal.

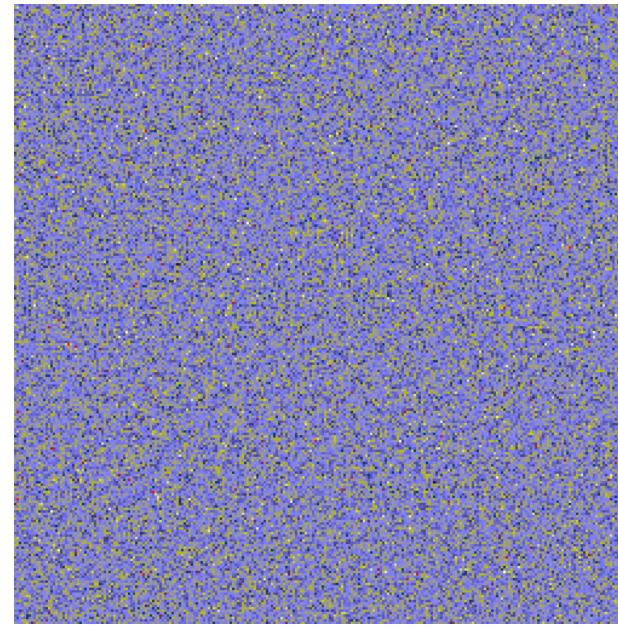
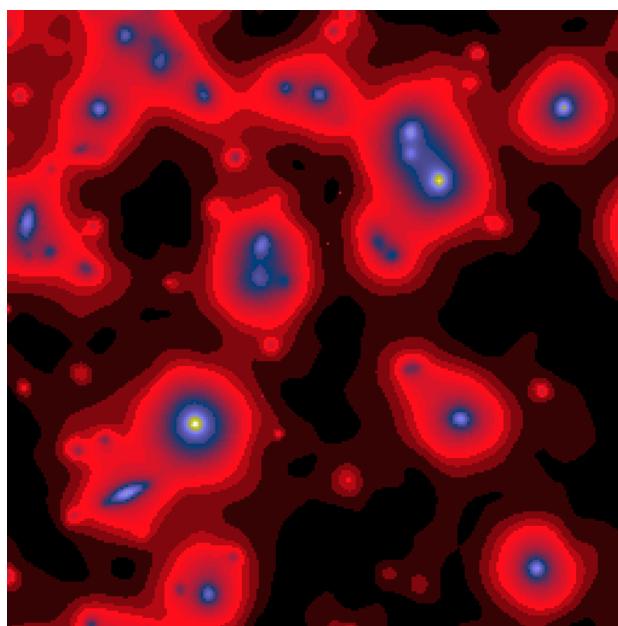
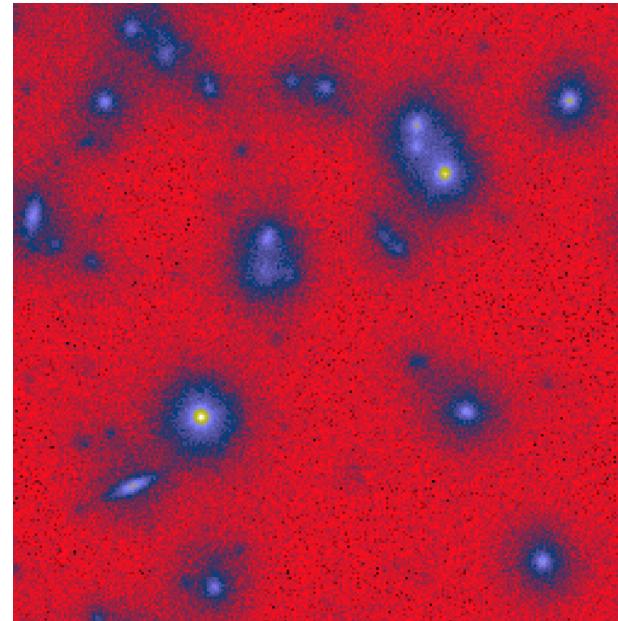
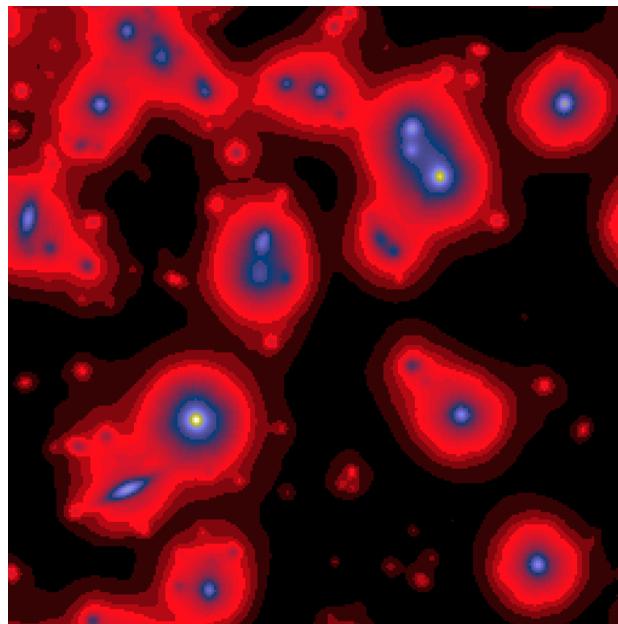
## Inverse Problems and Iterative Thresholding Minimizing Algorithm

Iterative thresholding with a varying threshold was proposed in (Starck et al, 2004; Elad et al, 2005) for sparse signal decomposition in order to accelerate the convergence. The idea consists in using a different threshold  $\lambda^{(n)}$  at each iteration.

For IST: 
$$\alpha^{(n+1)} = \text{HT}_{\lambda^{(n)}} \left( \alpha^{(n)} + \Phi^T A^T (Y - A\Phi\alpha^{(n)}) \right)$$

For IHT: 
$$\alpha^{(n+1)} = \text{ST}_{\lambda^{(n)}} \left( \alpha^{(n)} + \Phi^T A^T (Y - A\Phi\alpha^{(n)}) \right)$$

More Refs: Vonesch et al, 2007; Elad et al 2008; Wright et al., 2008; Nesterov, 2008 and Beck-Teboulle, 2009; Blumensath, 2008; Maleki et Donoho, 2009 ; etc.



## Compressive Sensing Resources

<http://www.dsp.ece.rice.edu/cs/>

More than 200 related papers already!

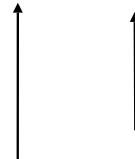
- Compressive Sensing
- Extensions of Compressive Sensing
- Multi-Sensor and Distributed Compressive Sensing
- Compressive Sensing Recovery Algorithms
- Foundations and Connections
- High-Dimensional Geometry
- Ell-1 Norm Minimization
- Statistical Signal Processing
- Machine Learning
- Bayesian Methods
- Finite Rate of Innovation
- Multi-band Signals
- Data Stream Algorithms
- Compressive Imaging
- Medical Imaging
- Analog-to-Information Conversion
- Biosensing
- Geophysical Data Analysis
- Hyperspectral Imaging
- Compressive Radar
- Astronomy
- Communications

+ software available

## Data Representation Tour

- Computational harmonic analysis seeks representations of a signal as linear combinations of basis, frame, dictionary, element :

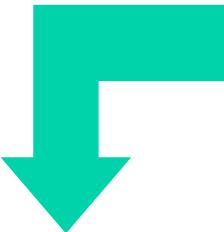
$$s_i = \sum_{k=1}^K \alpha_k \phi_k$$

  
**coefficients      basis, frame**

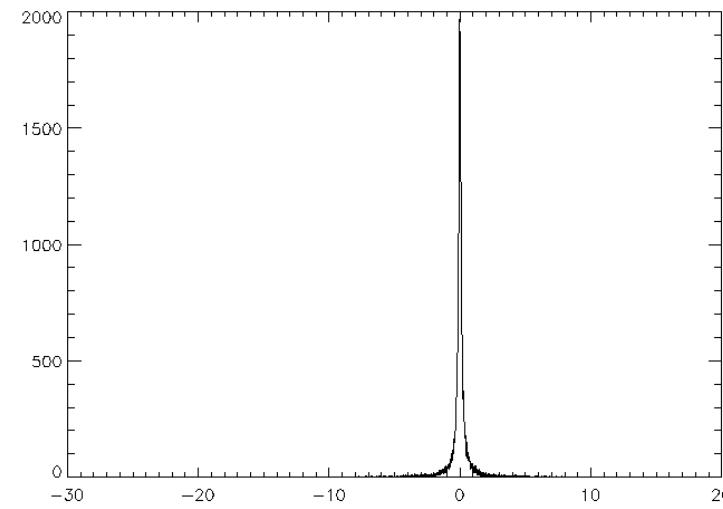
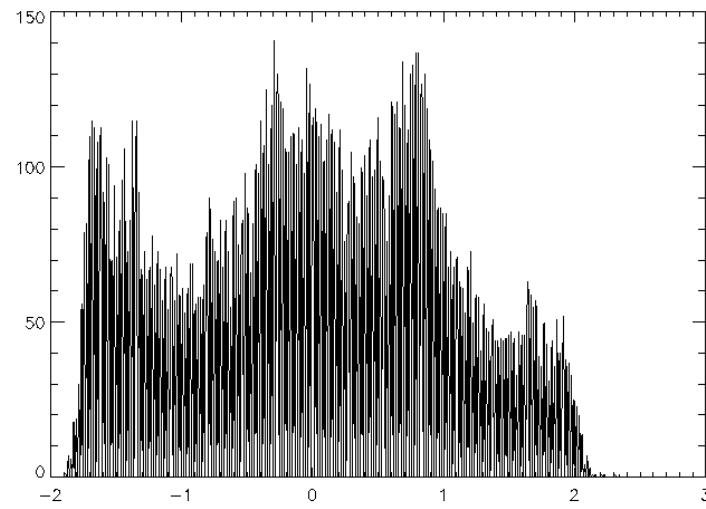
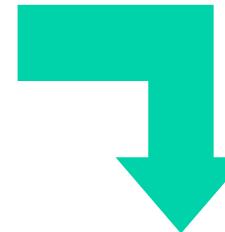
- Fast calculation of the coefficients  $\alpha_k$
- Analyze the signal through the statistical properties of the coefficients

# Representing Barbara

Direct Space



Curvelet Space



# The Great Father Fourier - Fourier Transforms

Any Periodic function can be expressed as linear combination of basic trigonometric functions

(Basis functions used are sine and cosine)



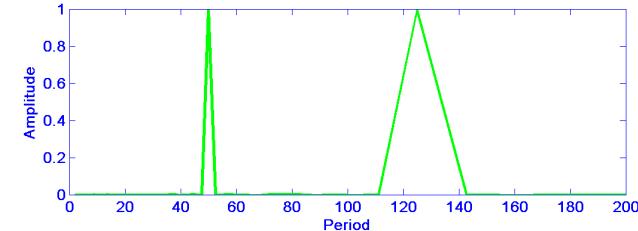
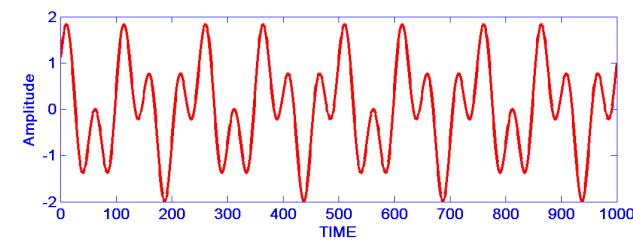
Jean-Baptiste-Joseph Fourier  
(1768-1830)

$$X(f) = \int_{-\infty}^{\infty} x(t)e^{-2\pi ift} dt$$

$$x(t) = \int_{-\infty}^{\infty} X(f)e^{2\pi ift} df$$

Time domain

Frequency domain



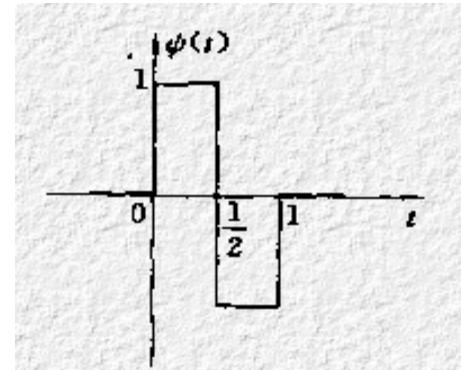
## ● Alfred Haar Wavelet (1909):

The first mention of wavelets appeared in an appendix to the thesis of Haar

- With *compact support*, vanishes outside of a finite interval
- Not continuously differentiable
- Wavelets are functions defined over a finite interval and having an average value of zero.

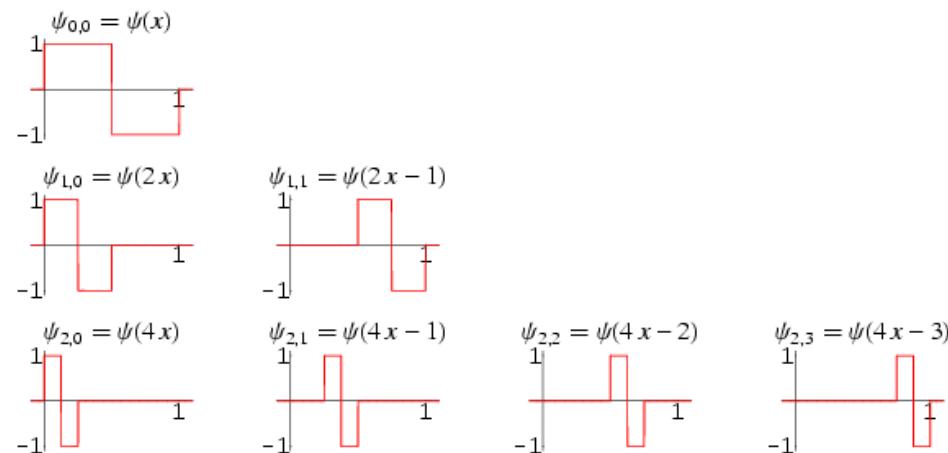


$$f(x) = c_0 + \sum_{j=0}^{\infty} \sum_{k=0}^{2^j-1} c_{jk} \psi_{jk}(x).$$



$$\Psi(x) = \begin{cases} 1 & 0 \leq x \leq \frac{1}{2} \\ -1 & \frac{1}{2} < x \leq 1 \\ 0 & \text{otherwise} \end{cases}$$

Haar wavelet



**==> What kind of  $\psi(t)$  could be useful?**

- . Impulse Function (Haar): Best time resolution
- . Sinusoids (Fourier): Best frequency resolution

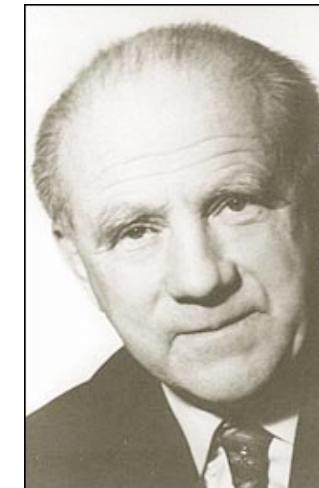
**==> We want both of the best resolutions**

**==> Heisenberg, 1930**

**Uncertainty Principle**

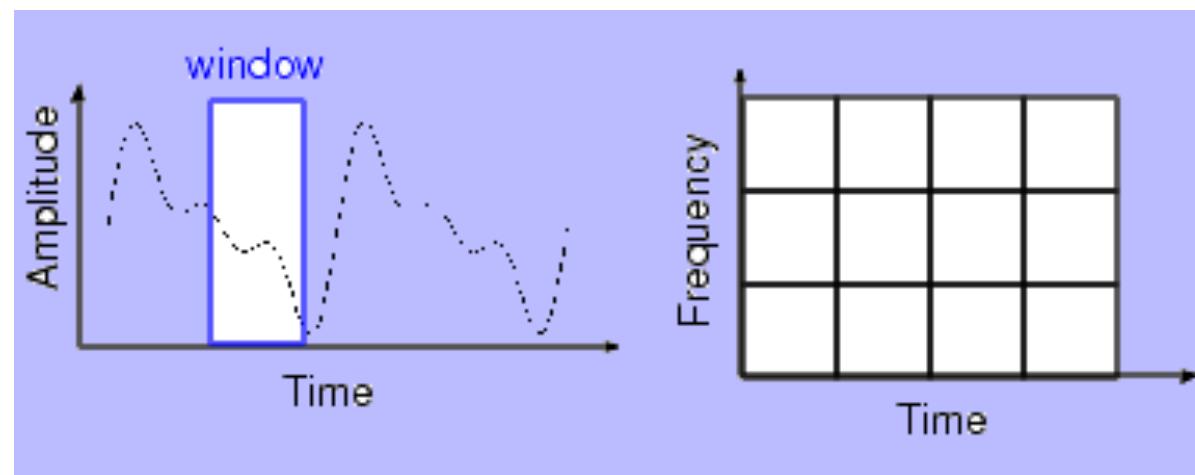
**There is a lower bound for**

$$\Delta t \cdot \Delta\omega$$

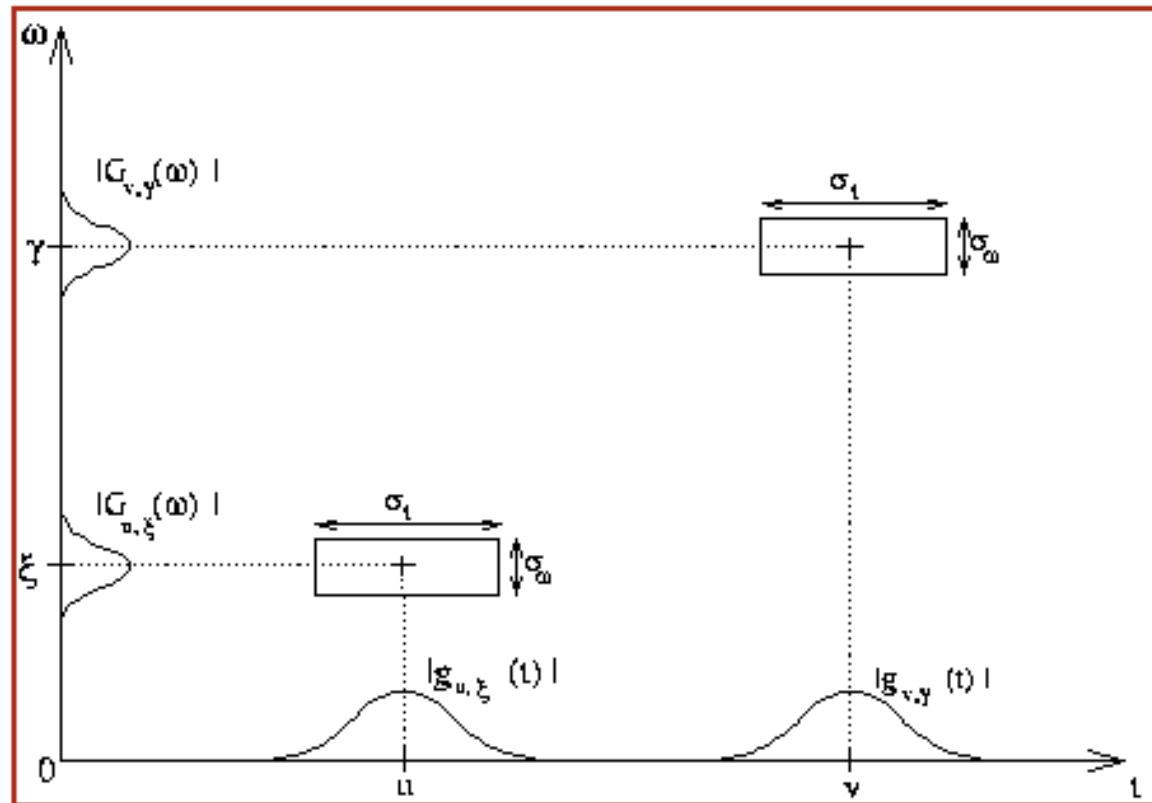


## SHORT TIME FOURIER TRANSFORM (STFT)

- Dennis Gabor (1946) Used STF  
To analyze only a small section of the signal at a time --  
a technique called *Windowing the Signal*.
- The Segment of Signal is Assumed Stationary



## Heisenberg Box



$$\sigma_t^2 \sigma_\omega^2 \geq \frac{1}{4}.$$



Yves Meyer



## A Major Breakthrough

**Daubechies, 1988 and Mallat, 1989**

**Daubechies:**

**Compactly Supported Orthogonal and Bi-Orthogonal Wavelets**

**Mallat:**

**Theory of Multiresolution Signal Decomposition**

**Fast Algorithm for the Computation of Wavelet Transform Coefficients  
using Filter Banks**

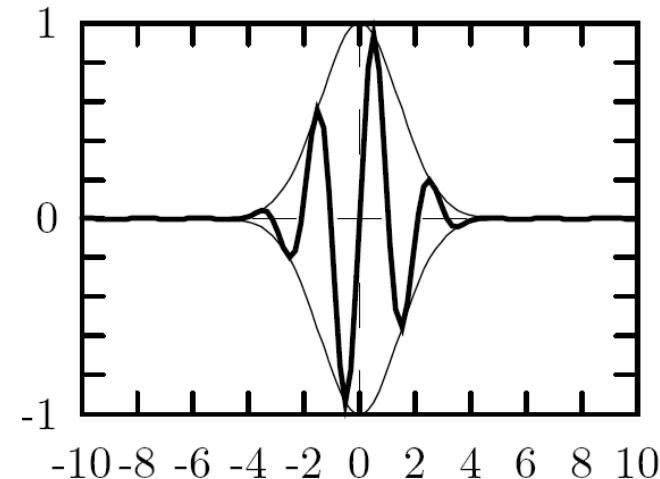
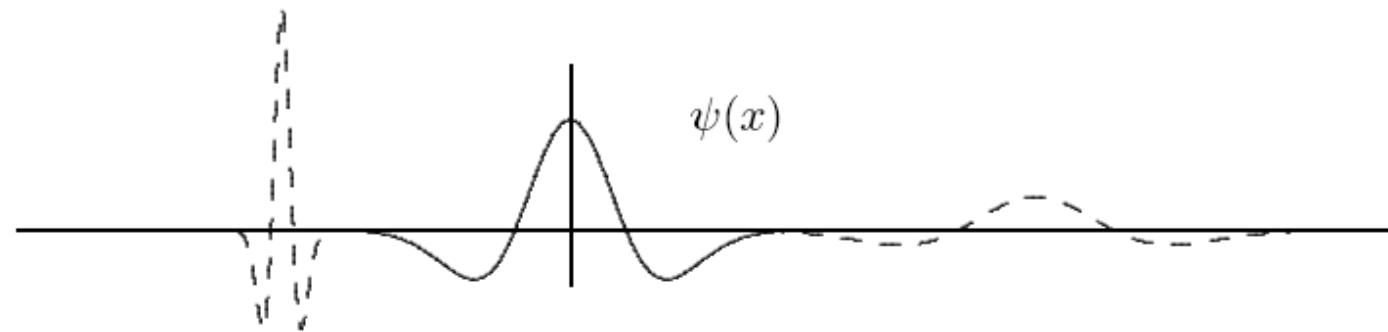
## Candidate analyzing functions for piecewise smooth signals

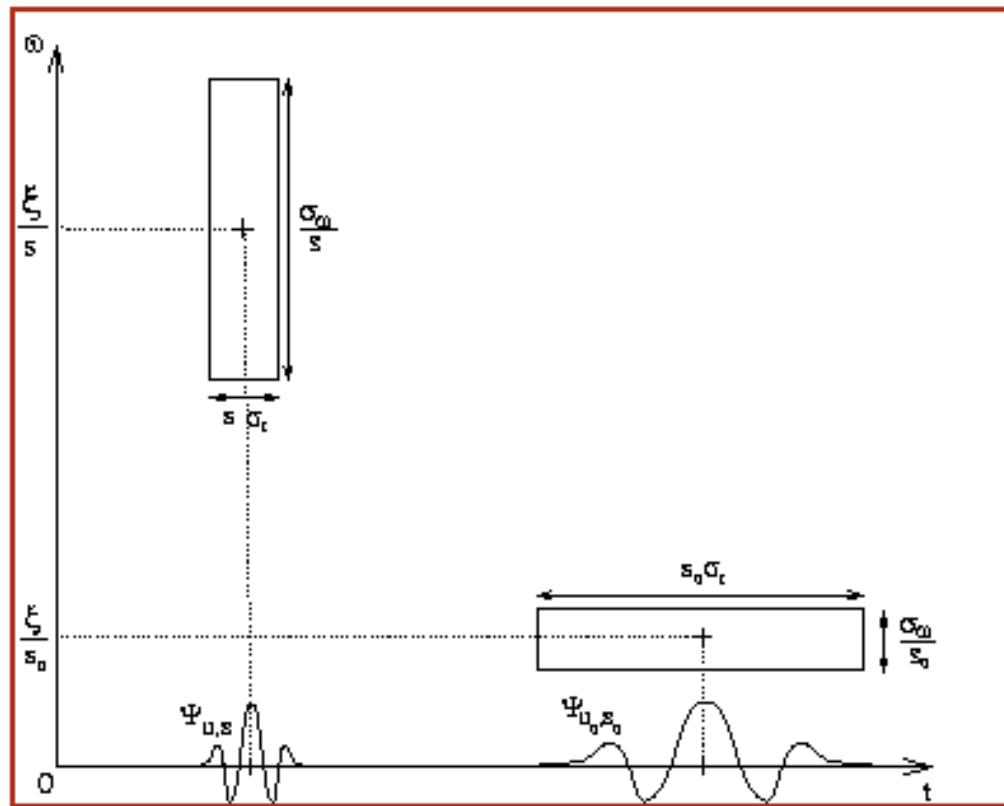
- Windowed fourier transform or Gaborlets :

$$\psi_{\omega,b}(t) = g(t-b)e^{i\omega t}$$

- Wavelets :

$$\psi_{a,b}(t) = \frac{1}{\sqrt{b}}\psi\left(\frac{t-a}{b}\right)$$

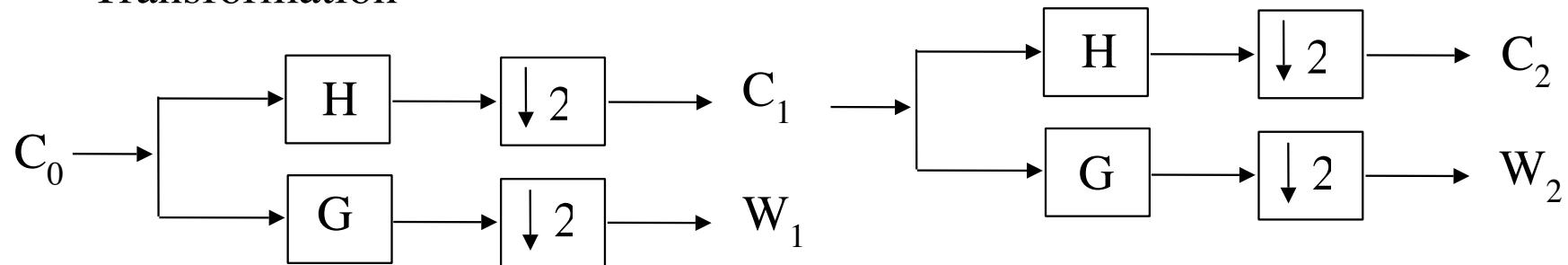




## The Orthogonal Wavelet Transform (OWT)

$$s_l = \sum_k c_{J,k} \phi_{J,l}(k) + \sum_k \sum_{j=1}^J \psi_{j,l}(k) w_{j,k}$$

Transformation



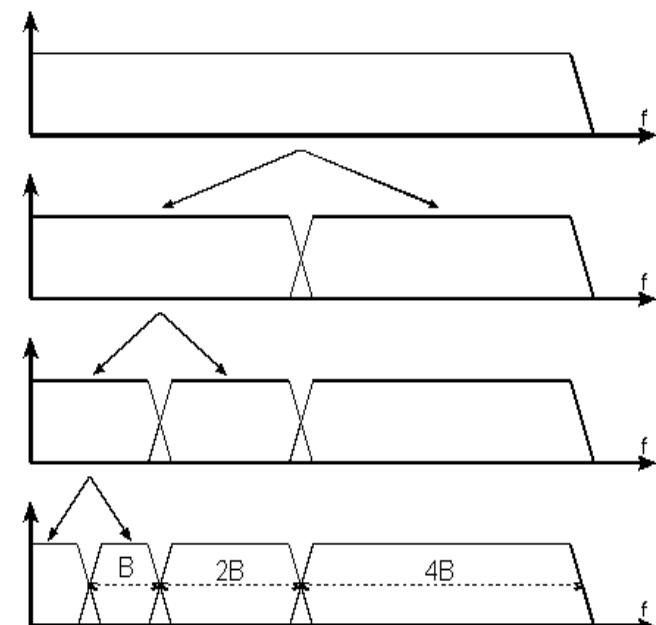
$$c_{j+1,l} = \sum_h h_{k-2l} c_{j,k} = (\bar{h} * c_j)_{2l}$$

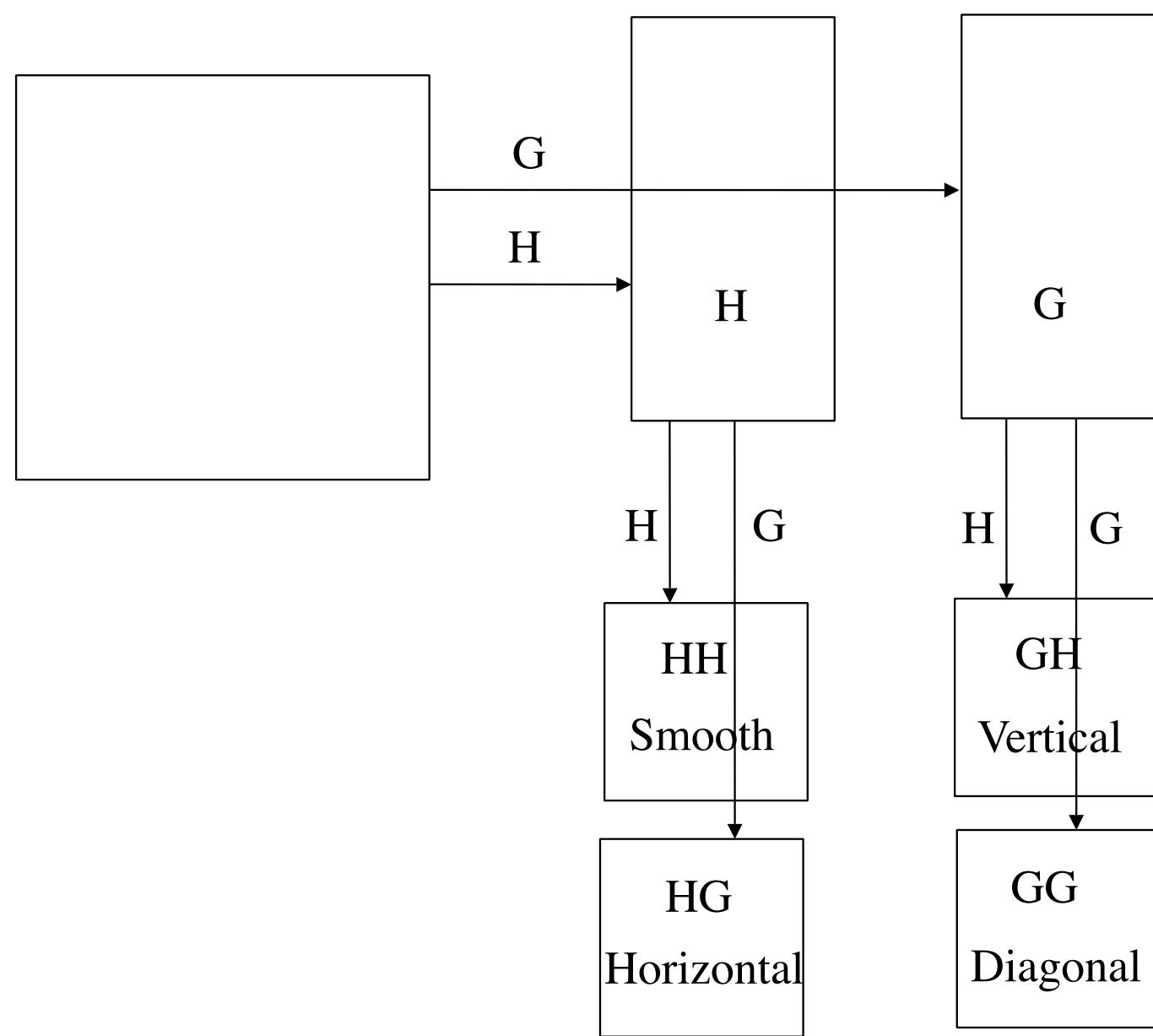
$$w_{j+1,l} = \sum_h g_{k-2l} c_{j,k} = (\bar{g} * c_j)_{2l}$$

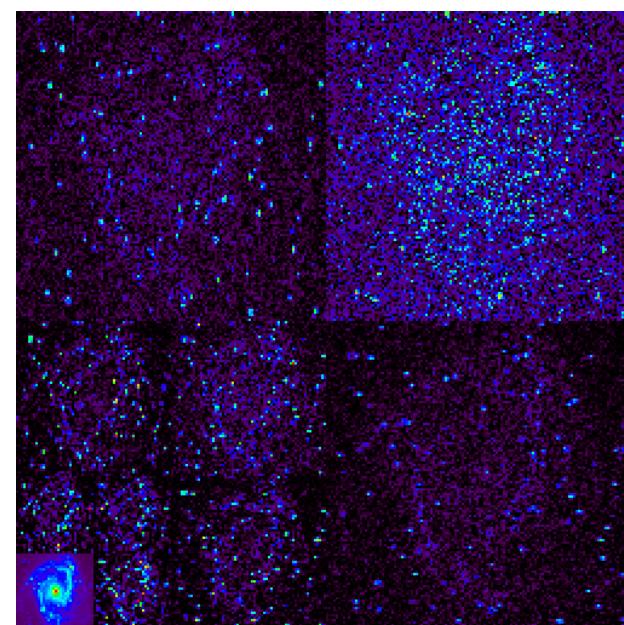
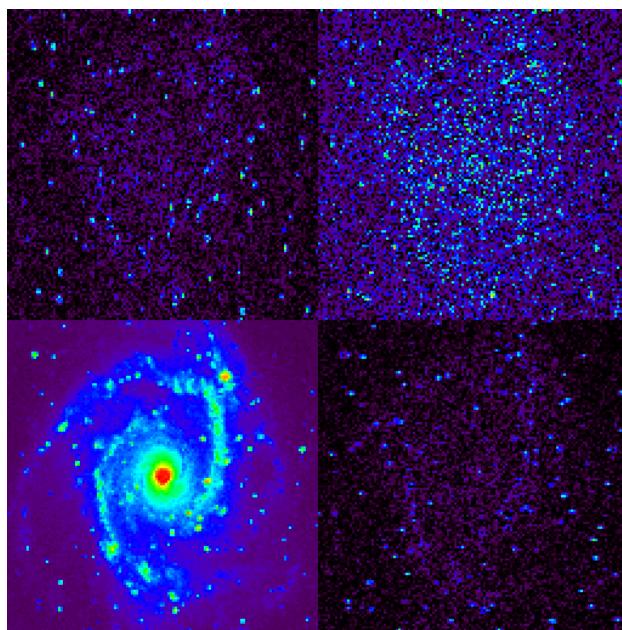
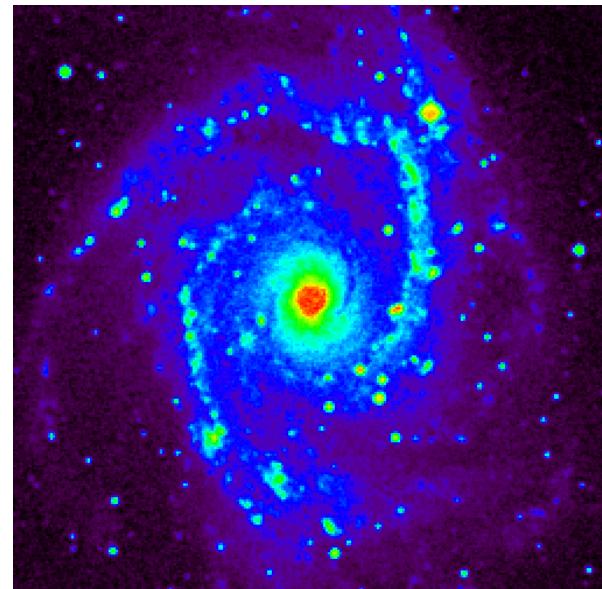
Reconstruction:

$$c_{j,l} = \sum_k \tilde{h}_{k+2l} c_{j+1,k} + \tilde{g}_{k+2l} w_{j+1,k} = \tilde{h} * \tilde{c}_{j+1} + \tilde{g} * \tilde{w}_{j+1}$$

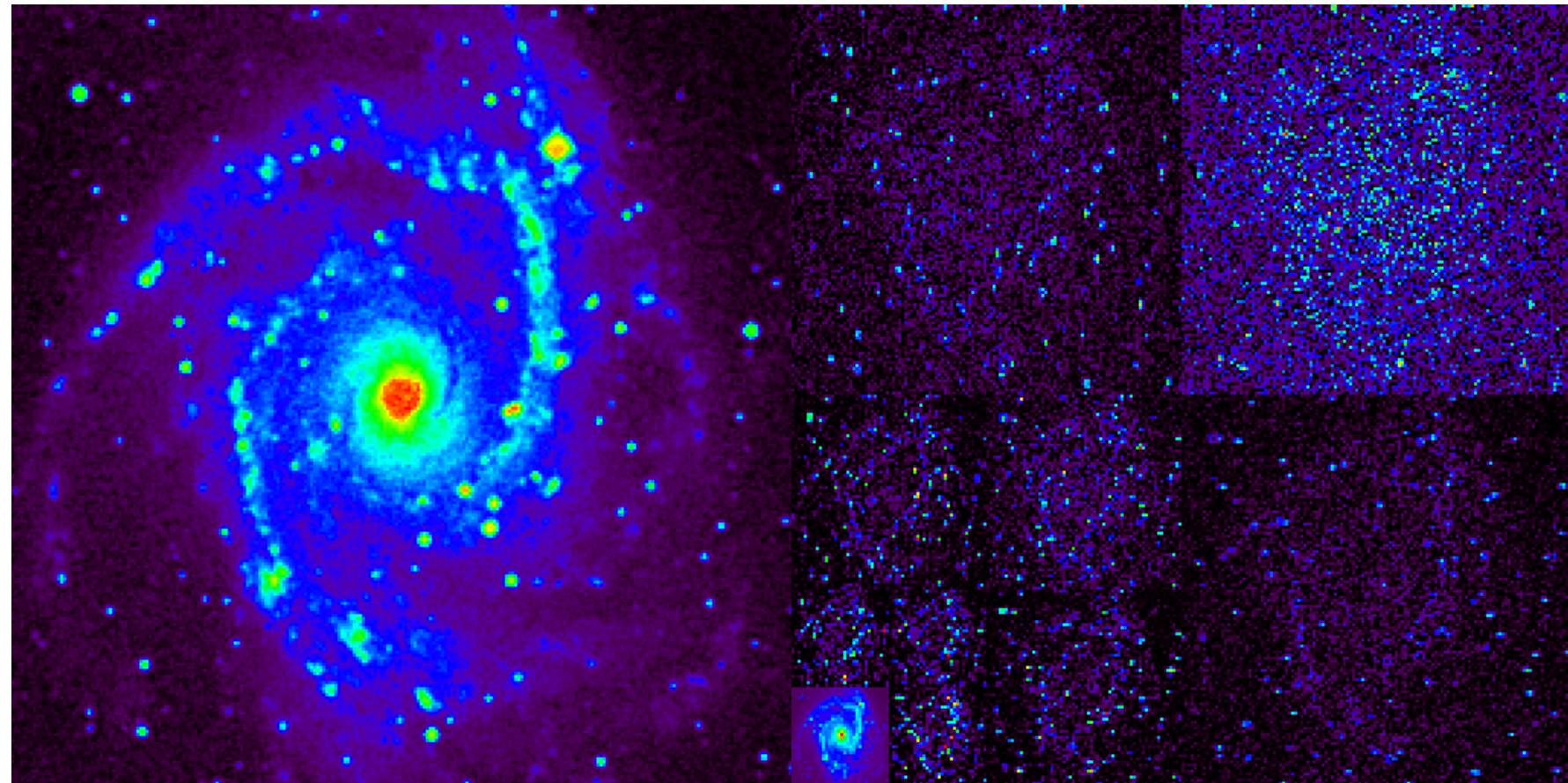
$$\tilde{x} = (x_1, 0, x_2, 0, x_3, \dots, 0, x_j, 0, \dots, x_{n-1}, 0, x_n)$$







NGC2997



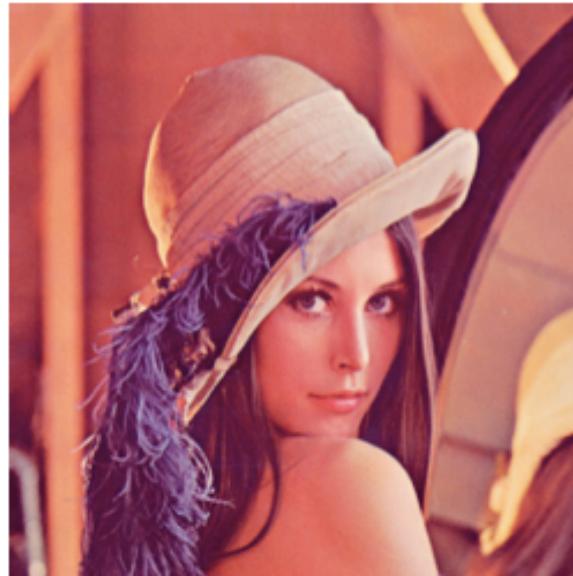
NGC2997 WT

# JPEG/JPEG 2000

Original BMP

300x300x24

270056 bytes



JPEG 1:68

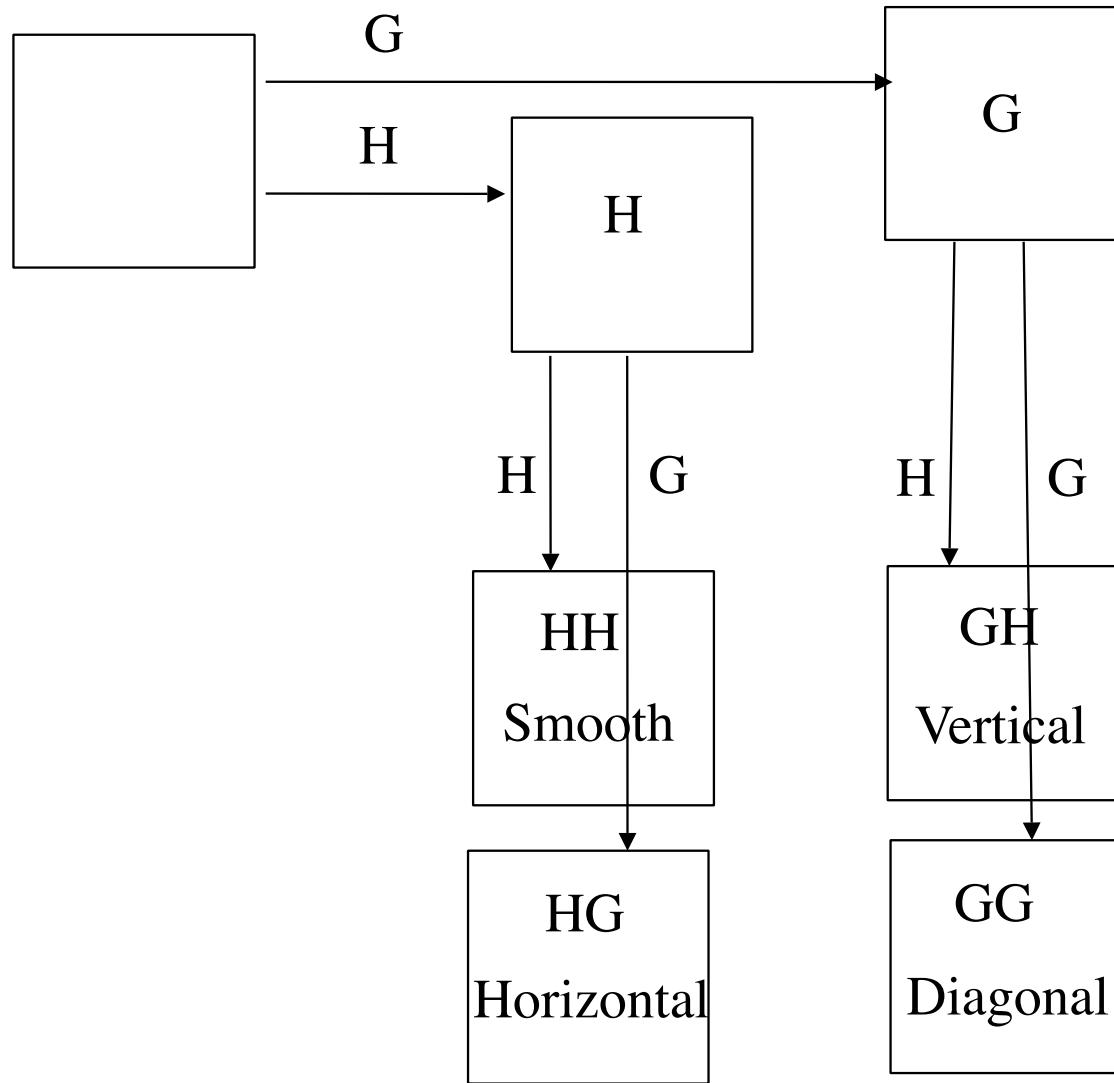
3983 bytes

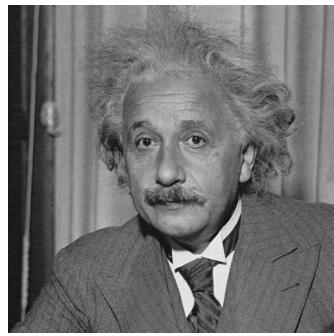


JPEG2000 1:70

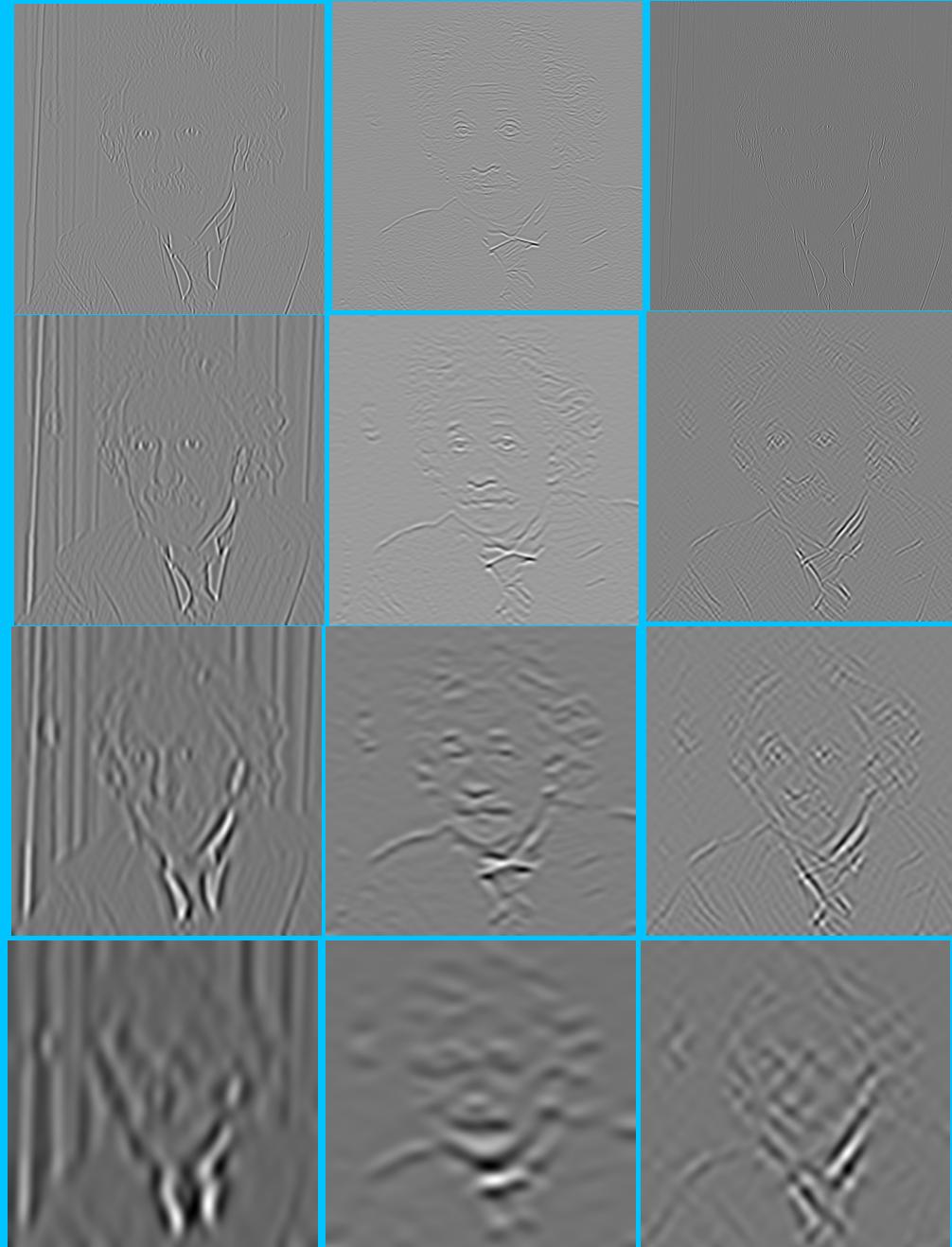
3876 bytes

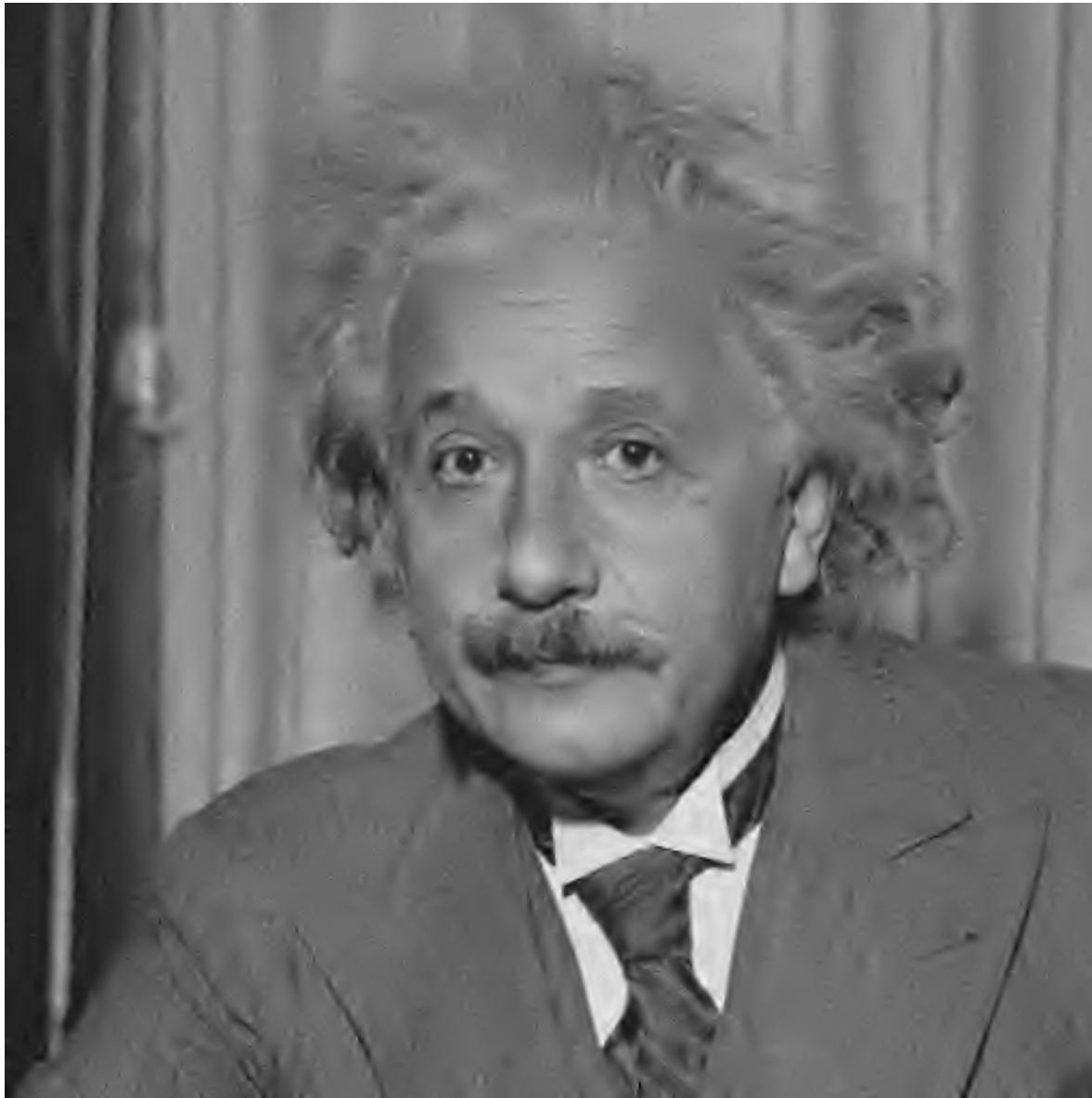






## Undecimated Wavelet Transform

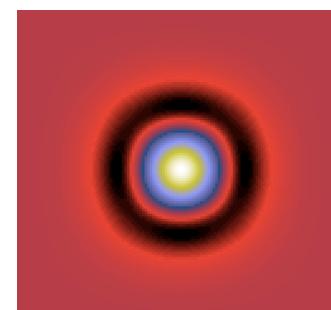
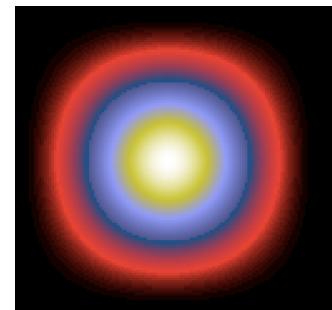
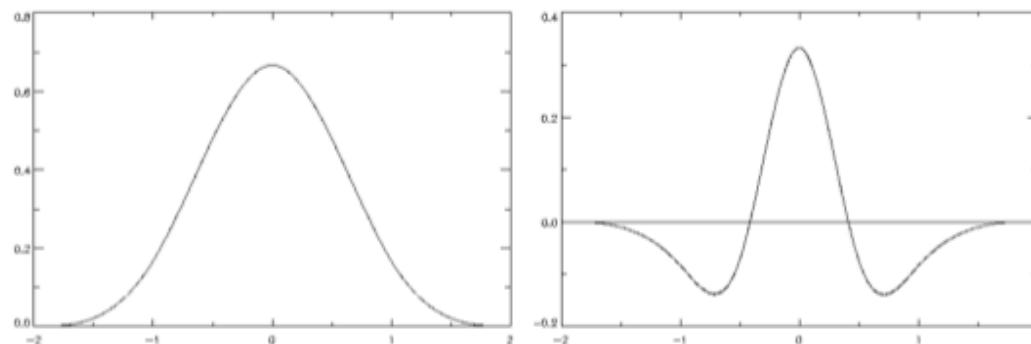




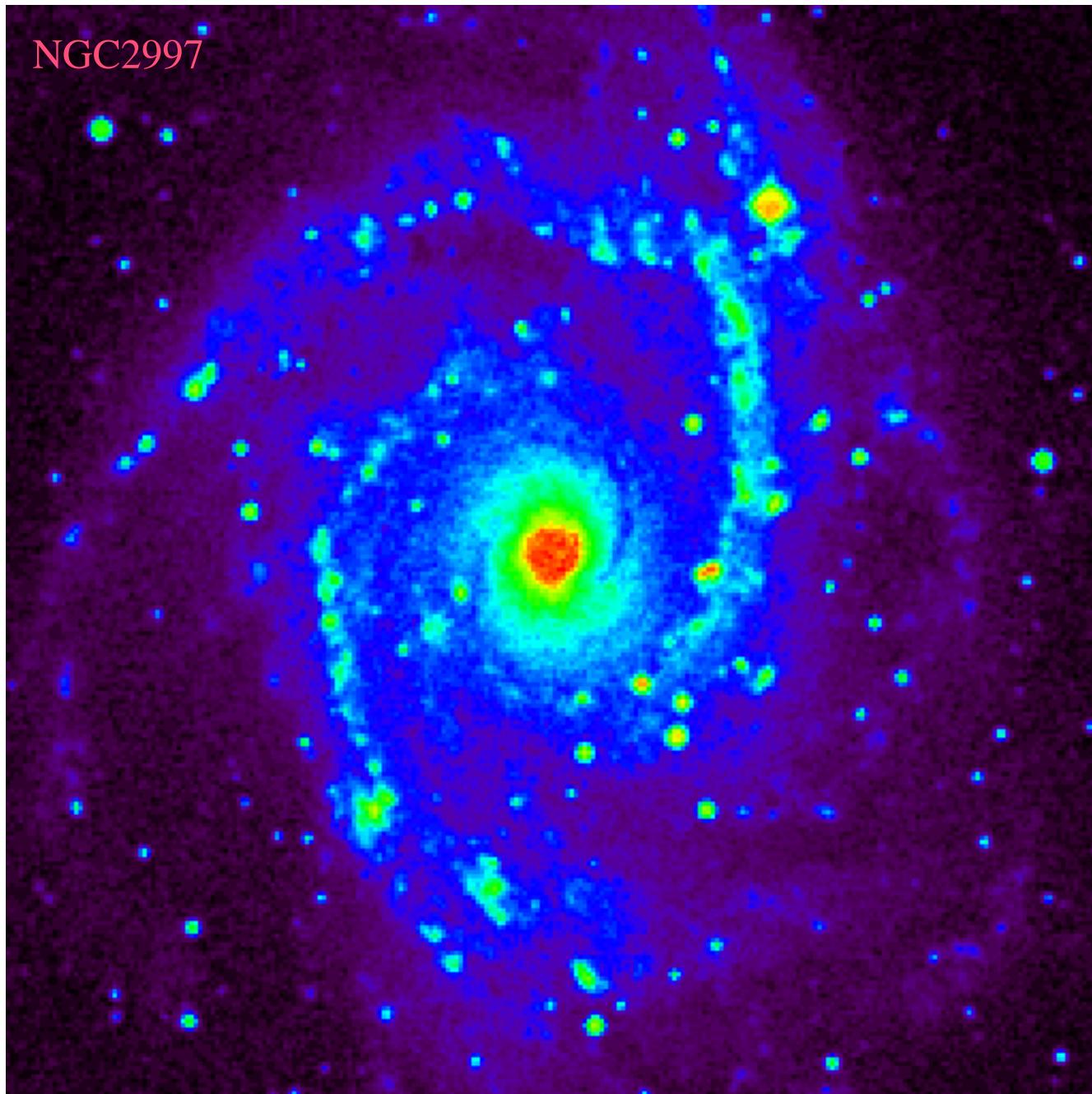
# Wavelet Transform in Astronomy

## The Isotropic Wavelet and Scaling Functions

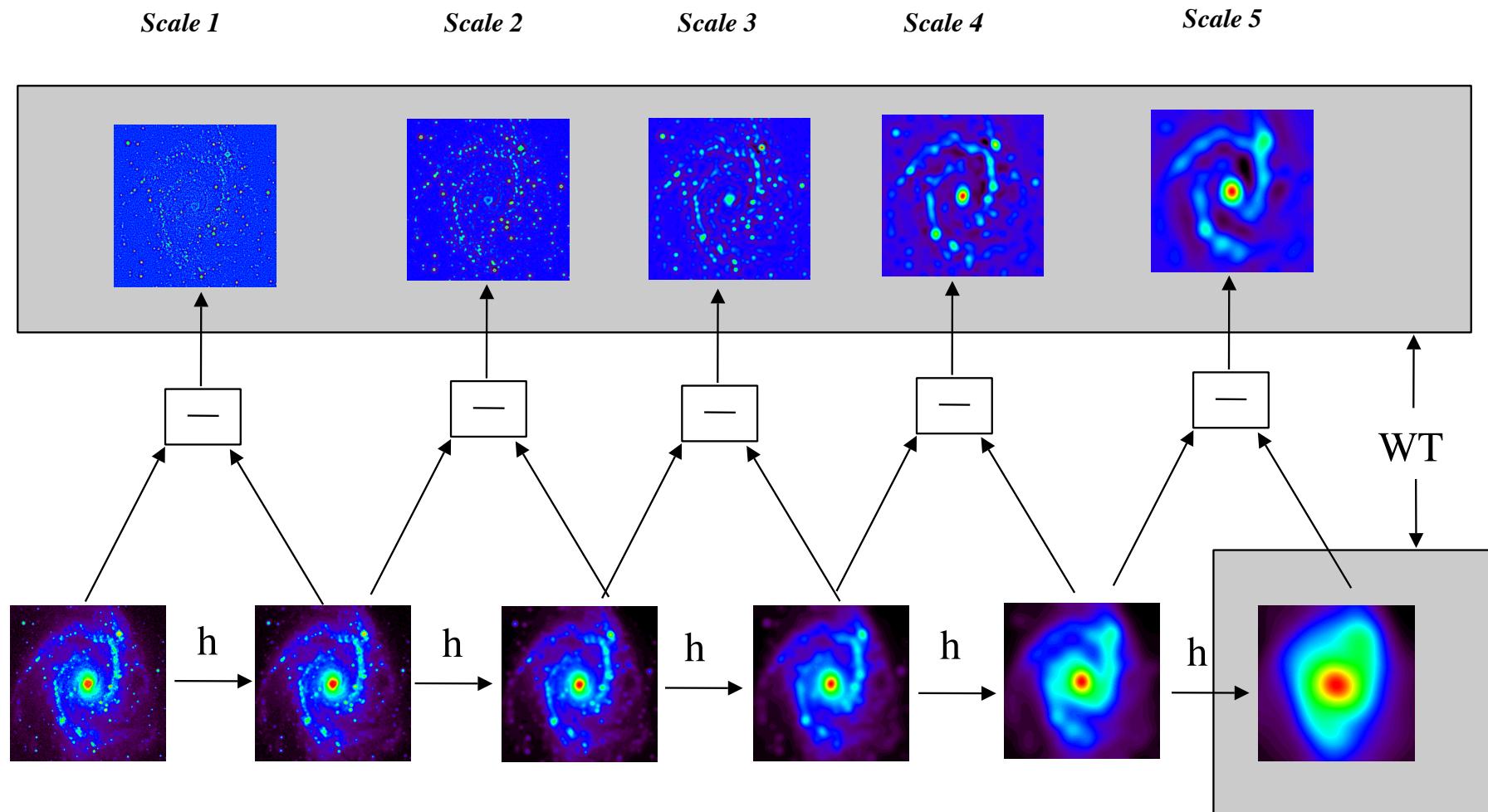
$$\begin{aligned}B_3(x) &= \frac{1}{12}(|x-2|^3 - 4|x-1|^3 + 6|x|^3 - 4|x+1|^3 + |x+2|^3) \\ \psi(x, y) &= B_3(x)B_3(y) \\ \frac{1}{4}\psi\left(\frac{x}{2}, \frac{y}{2}\right) &= \phi(x, y) - \frac{1}{4}\phi\left(\frac{x}{2}, \frac{y}{2}\right)\end{aligned}$$



NGC2997



# ISOTROPIC UNDECIMATED WAVELET TRANSFORM



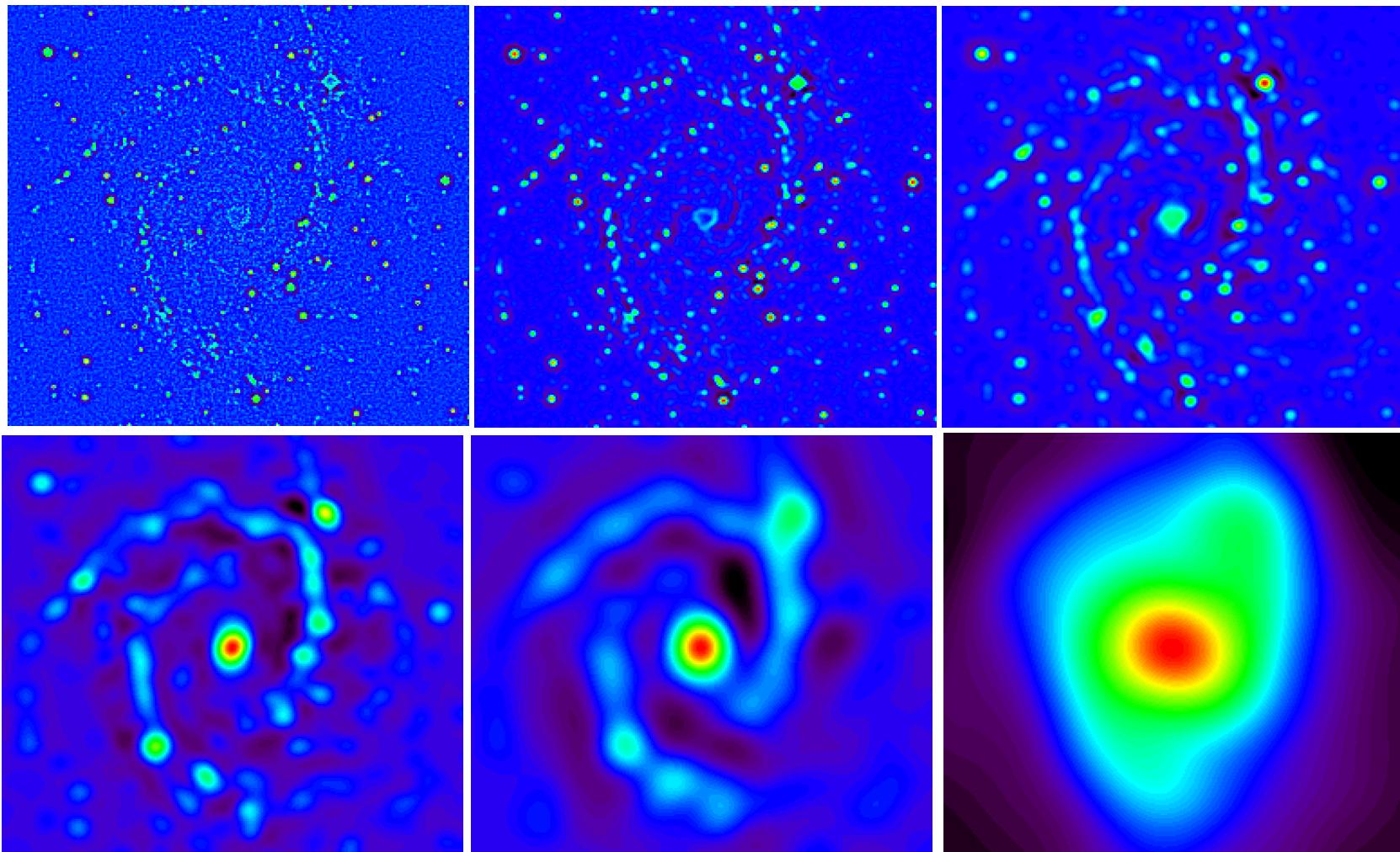
# The STARLET Transform

## Isotropic Undecimated Wavelet Transform (a trous algorithm)

$$\varphi = B_3 - \text{spline}, \quad \frac{1}{2}\psi\left(\frac{x}{2}\right) = \frac{1}{2}\varphi\left(\frac{x}{2}\right) - \varphi(x)$$

$$h = [1, 4, 6, 4, 1]/16, \quad g = \delta - h, \quad \tilde{h} = \tilde{g} = \delta$$

$$I(k, l) = c_{J, k, l} + \sum_{j=1}^J w_{j, k, l}$$

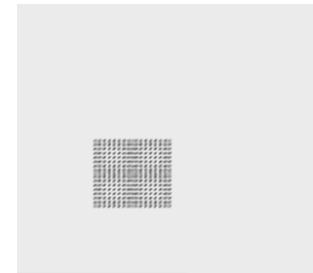


# Looking for adapted representations

## Local DCT

Stationary textures

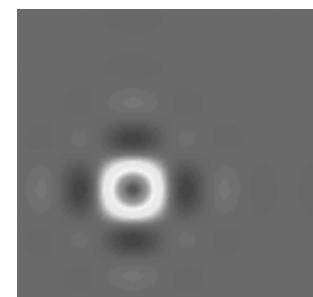
Locally oscillatory



## Wavelet transform

Piecewise smooth

Isotropic structures

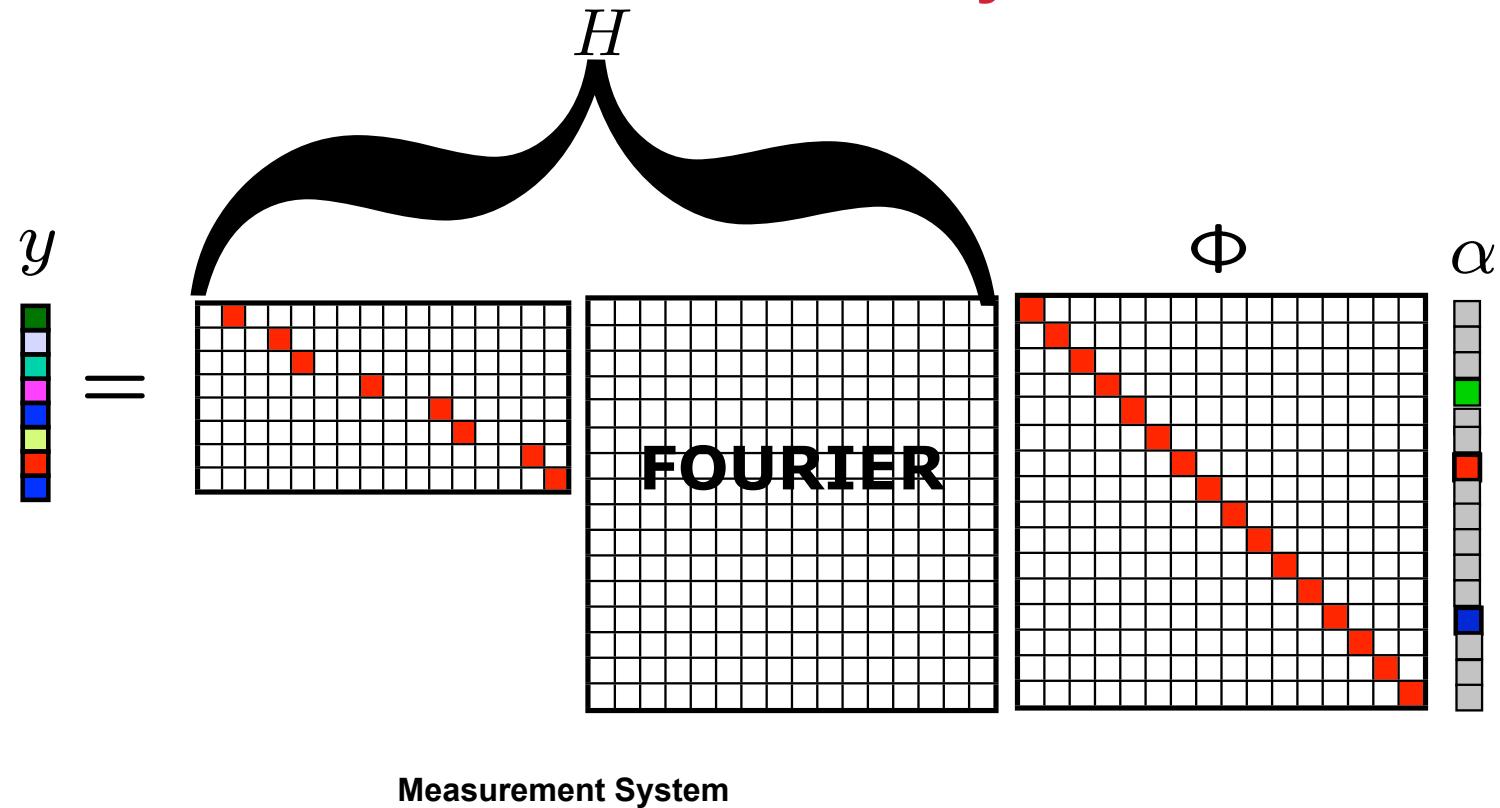


## Curvelet transform

Piecewise smooth,  
edge



# Radio-Interferometry



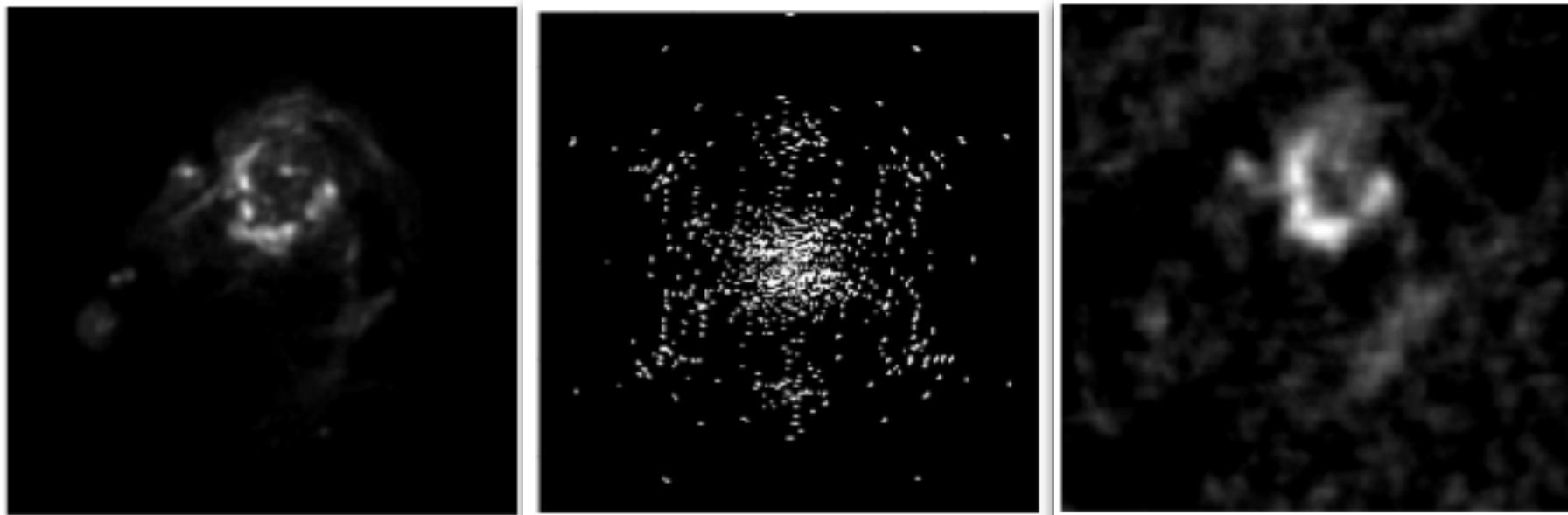
==> See (McEwen et al, 2011; Wenger et al, 2010; Wiaux et al, 2009; Cornwell et al, 2009; Suskimo, 2009; Feng et al, 2011).

# CS-Radio Astronomy

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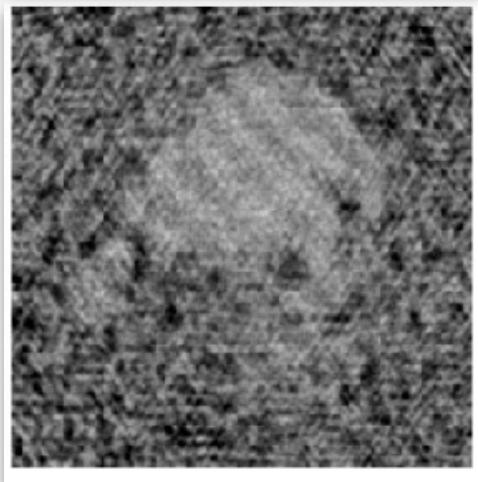
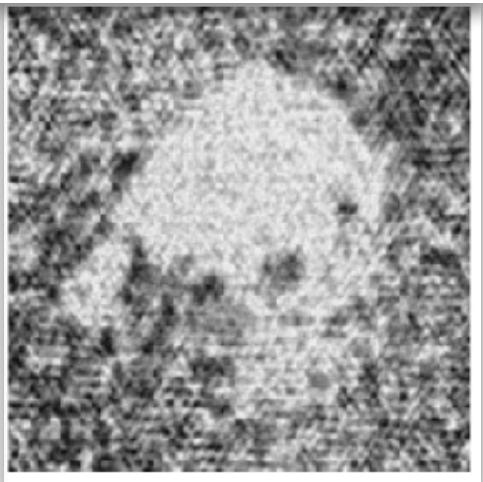
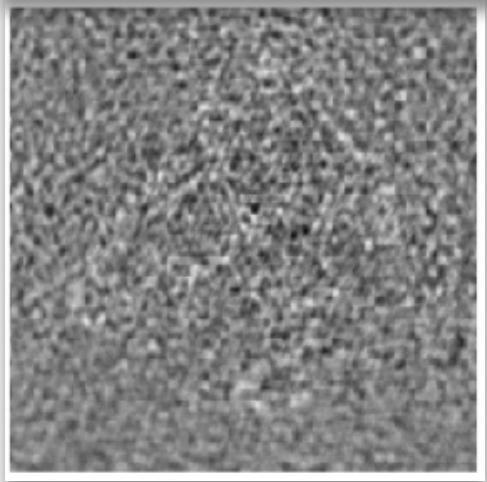
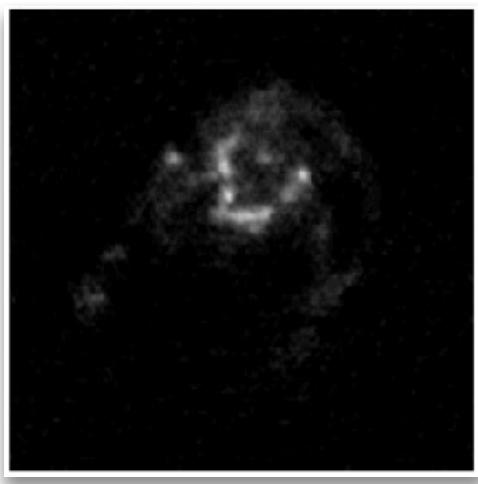
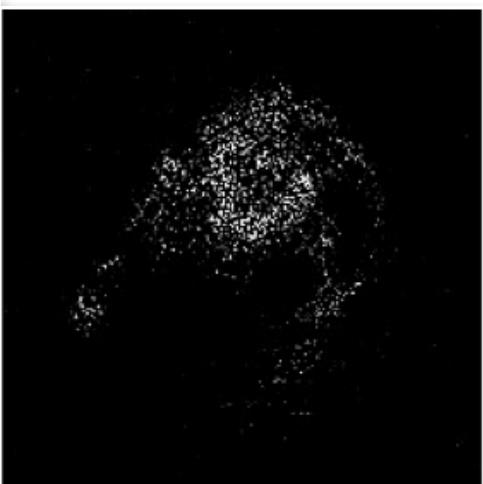
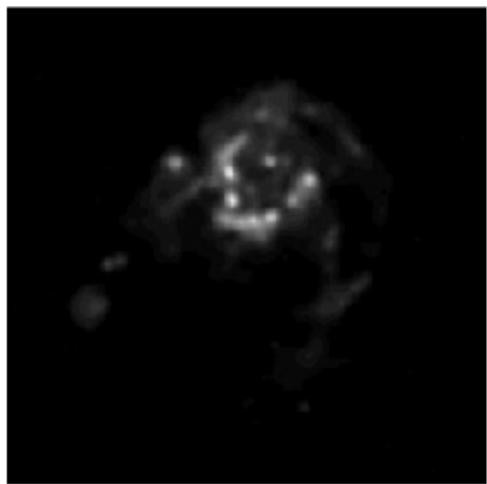
The Applications of Compressive Sensing to Radio Astronomy: I Deconvolution

Feng Li, Tim J. Cornwell and Frank De hoog, ArXiv:1106.1711, Volume 528, A31,2011.



Australian Square Kilometer Array Pathfinder (ASKAP) radio telescope.

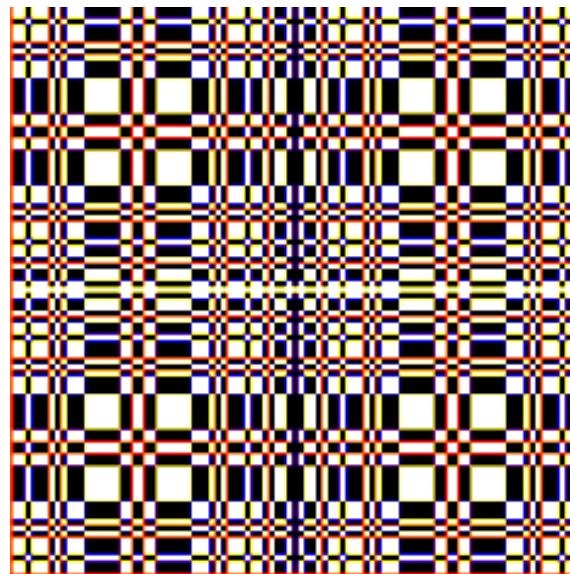
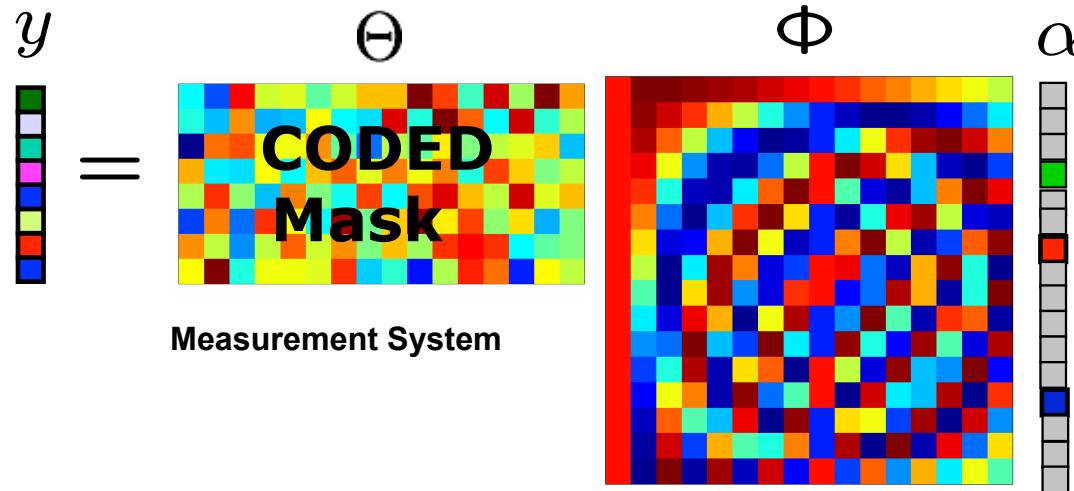
# CS-Radio Astronomy



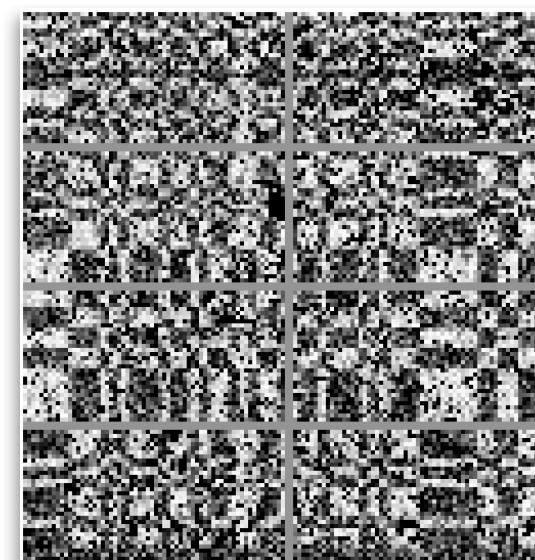
Hogbom CLEAN

MEM residual

## Gamma Ray Instruments (Integral) - Acquisition with coded masks



INTEGRAL/IBIS Coded Mask



Crab Nebula Integral Observation

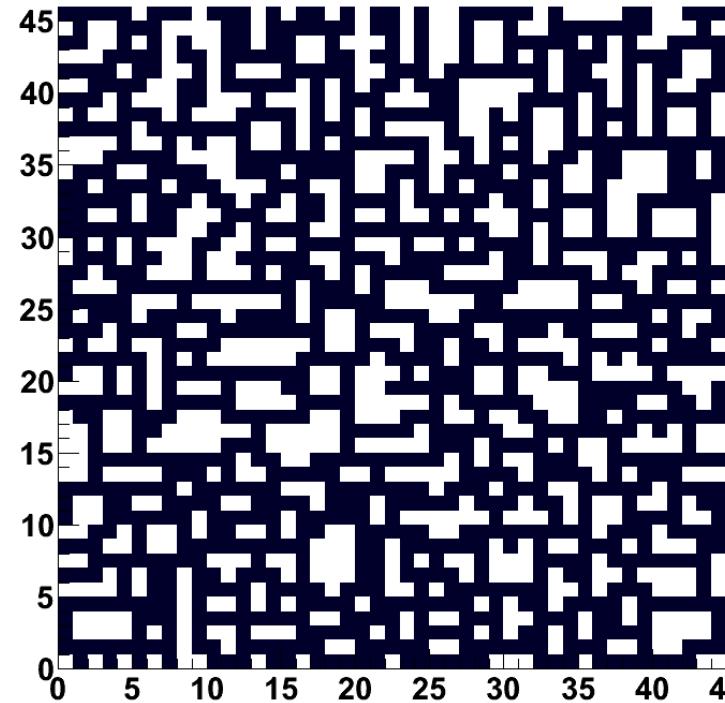
Courtesy I. Caballero, J. Rodriguez (AIM/Saclay)

# SVOM (*future French-Chinese Gamma-Ray Burst mission*)

saclay  
irfu

- *ECLAIRs france-chinese satellite ‘SVOM’ (launch in 2014-2015)*  
*Gamma-ray detection in energy range 4 - 120 keV*  
*Coded mask imaging (at 460 mm of the detector plane)*

**Physical mask pattern**  
(46 x 46 pixels of 11.7 mm)



**ECLAIR could become the first CS-Designed Astronomical Instrument**

# Problems related to the WT

1) Edges representation:

if the WT performs better than the FFT to represent edges in an image, it is still not optimal.

2) There is only a fixed number of directional elements independent of scales.

3) Limitation of existing scale concepts:  
there is no highly anisotropic elements.

# Multiscale Transforms

## Critical Sampling

(bi-) Orthogonal WT  
Lifting scheme construction  
Wavelet Packets  
Mirror Basis

## Redundant Transforms

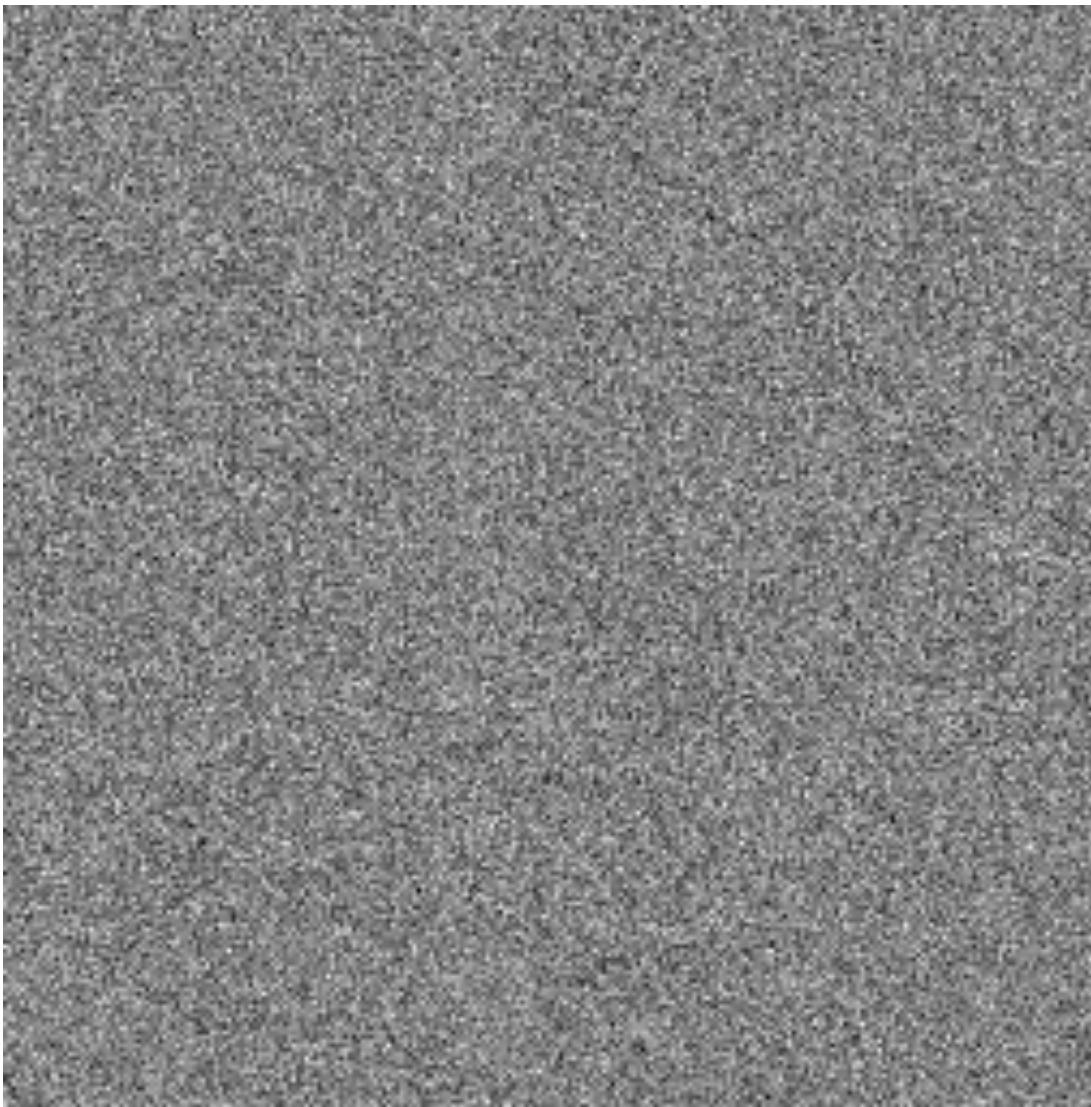
Pyramidal decomposition (Burt and Adelson)  
**Undecimated Wavelet Transform**  
**Isotropic Undecimated Wavelet Transform**  
Complex Wavelet Transform  
Steerable Wavelet Transform  
Dyadic Wavelet Transform  
Nonlinear Pyramidal decomposition (Median)

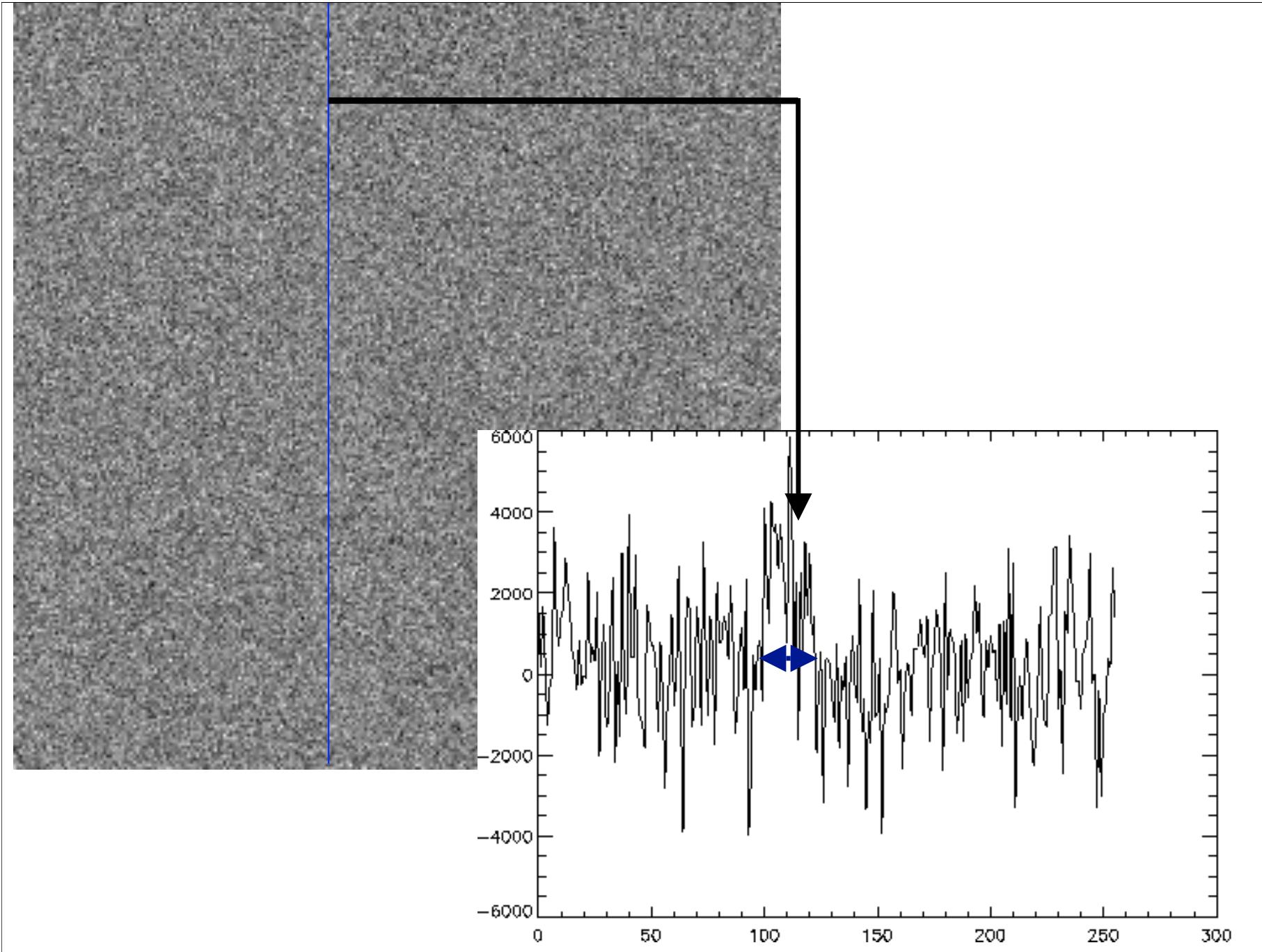
## New Multiscale Construction

Contourlet  
Bandelet  
Finite Ridgelet Transform  
Platelet  
(W-)Edgelet  
Adaptive Wavelet

**Ridgelet**  
**Curvelet** (Several implementations)  
Wave Atom

**SNR = 0.1**

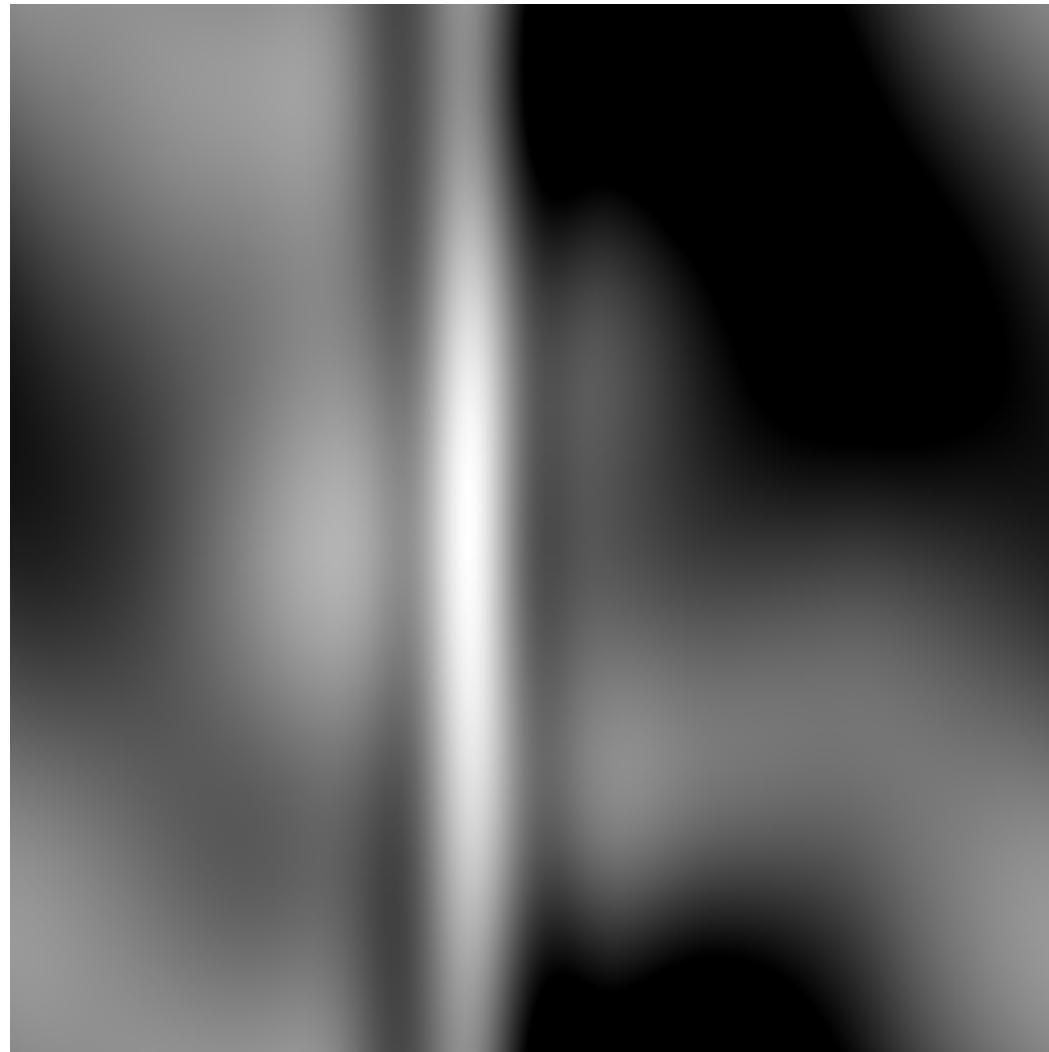




## Undecimated Wavelet Filtering (3 sigma)



## Ridgelet Filtering (5sigma)



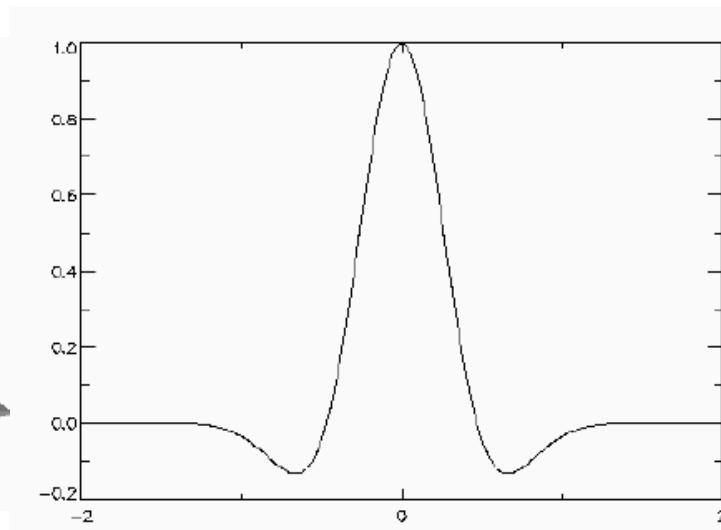
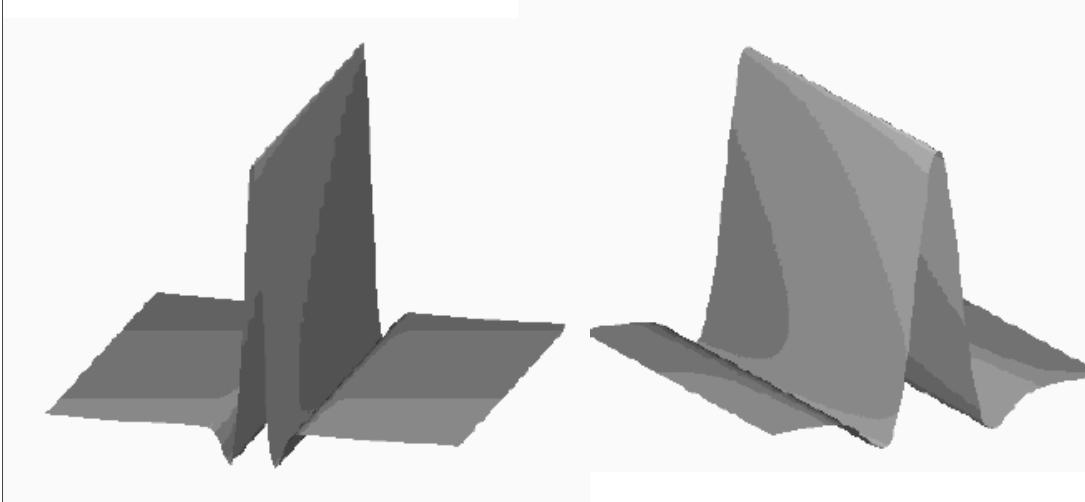


# Continuous Ridgelet Transform

Ridgelet Transform (Candes, 1998):  $R_f(a,b,\theta) = \int \psi_{a,b,\theta}(x) f(x) dx$

Ridgelet function:  $\psi_{a,b,\theta}(x) = a^{\frac{1}{2}} \psi\left(\frac{x_1 \cos(\theta) + x_2 \sin(\theta) - b}{a}\right)$

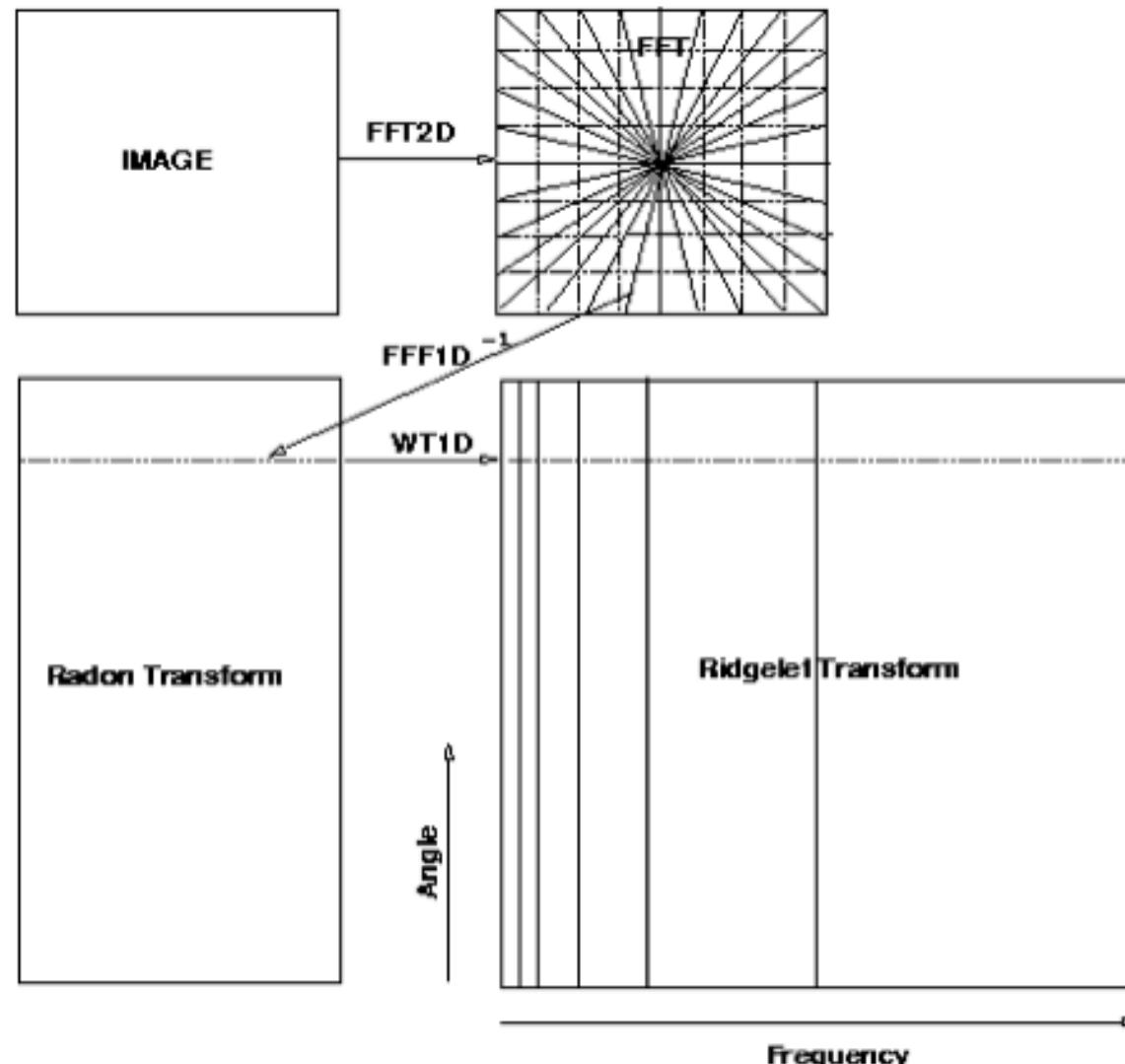
The function is constant along lines. Transverse to these ridges, it is a wavelet.



The ridgelet coefficients of an object  $f$  are given by analysis

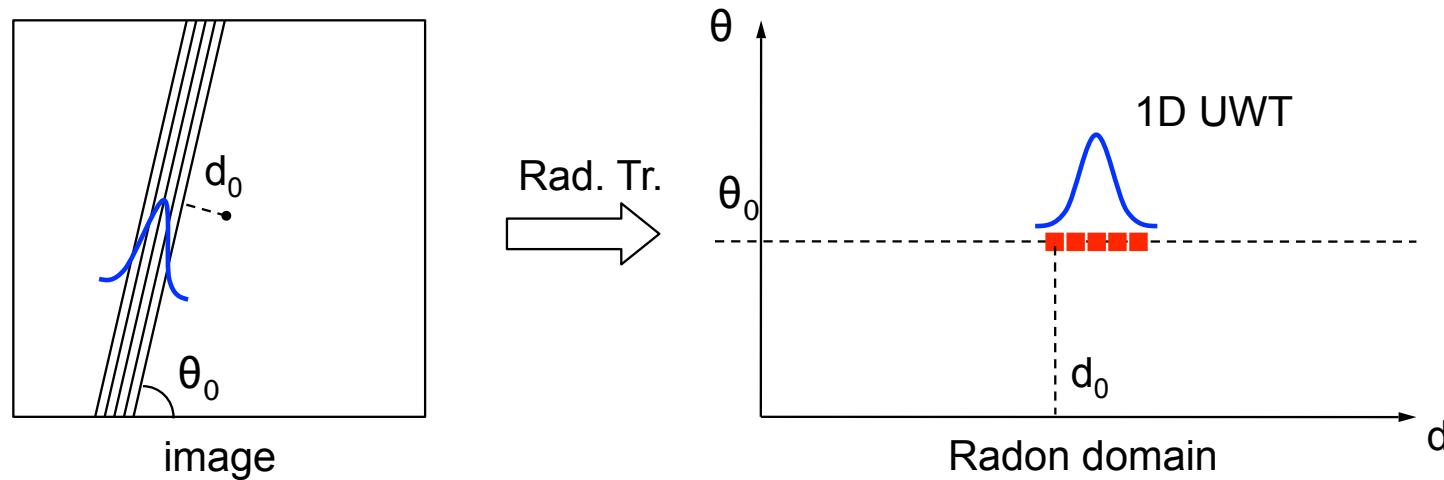
of the Radon transform via:

$$R_f(a,b,\theta) = \int Rf(\theta,t)\psi\left(\frac{t-b}{a}\right)dt$$



## Ridgelet Denoising

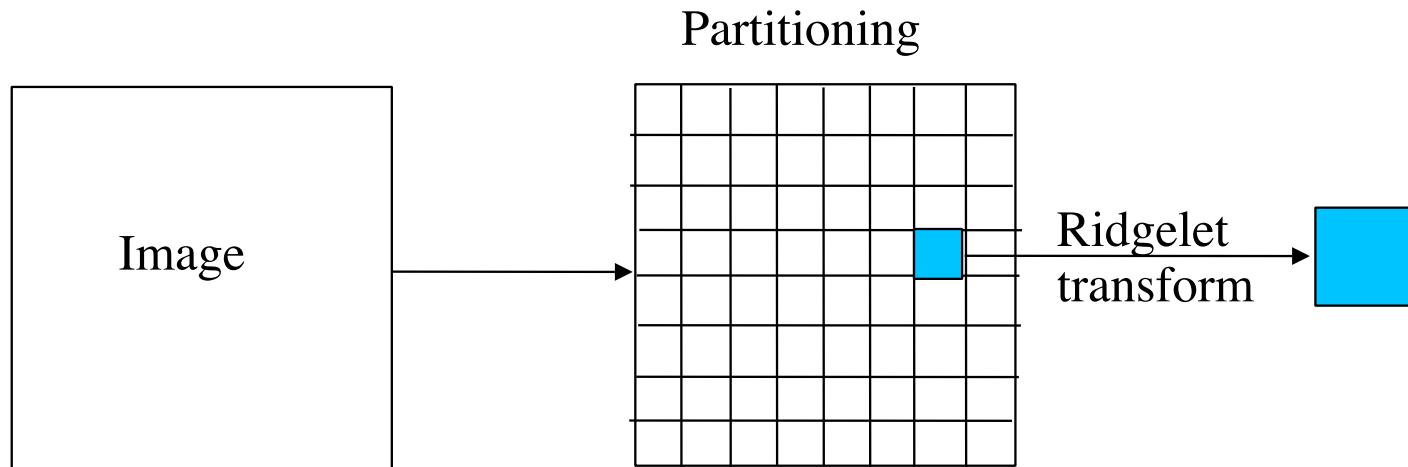
- Ridgelet transform: Radon + 1D Wavelet



1. Rad. Tr.
2. For each line, apply the same denoising scheme as before
3. Rad. Tr.<sup>-1</sup>

# Local Ridgelet Transform

The ridgelet transform is optimal to find only lines of the size of the image. To detect line segments, a partitioning must be introduced. The image is decomposed into blocks, and the ridgelet transform is applied on each block.

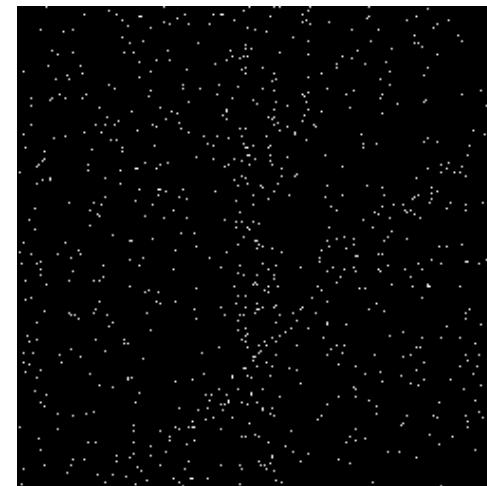


## Poisson Noise and Line-Like Sources Restoration (MS-VST + Ridgelet)

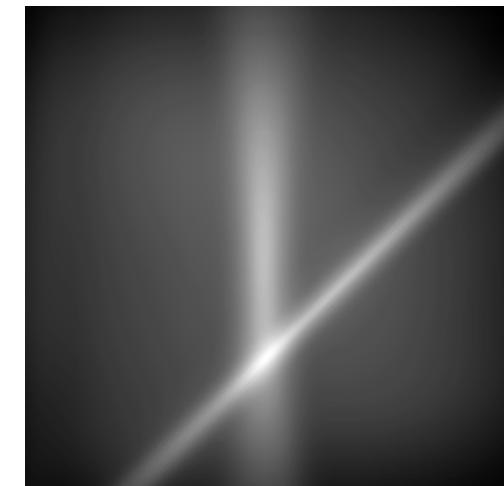
B. Zhang, M.J. Fadili and J.-L. Starck, "Wavelets, Ridgelets and Curvelets for Poisson Noise Removal" ,ITIP, 2008.



underlying intensity image



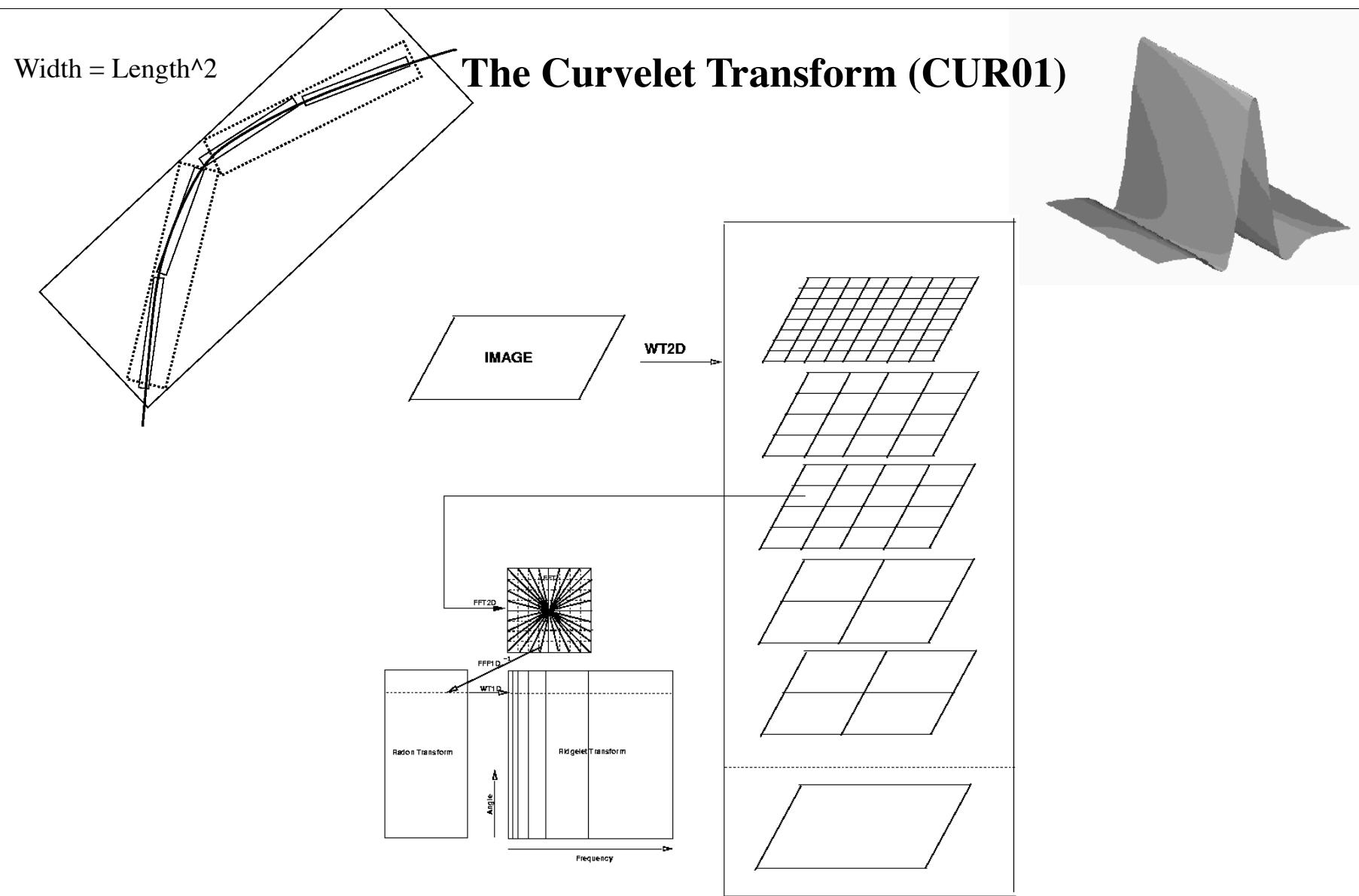
simulated image of counts



restored image  
from the left image of counts

**Max Intensity**  
background = 0.01  
vertical bar = 0.03  
inclined bar = 0.04

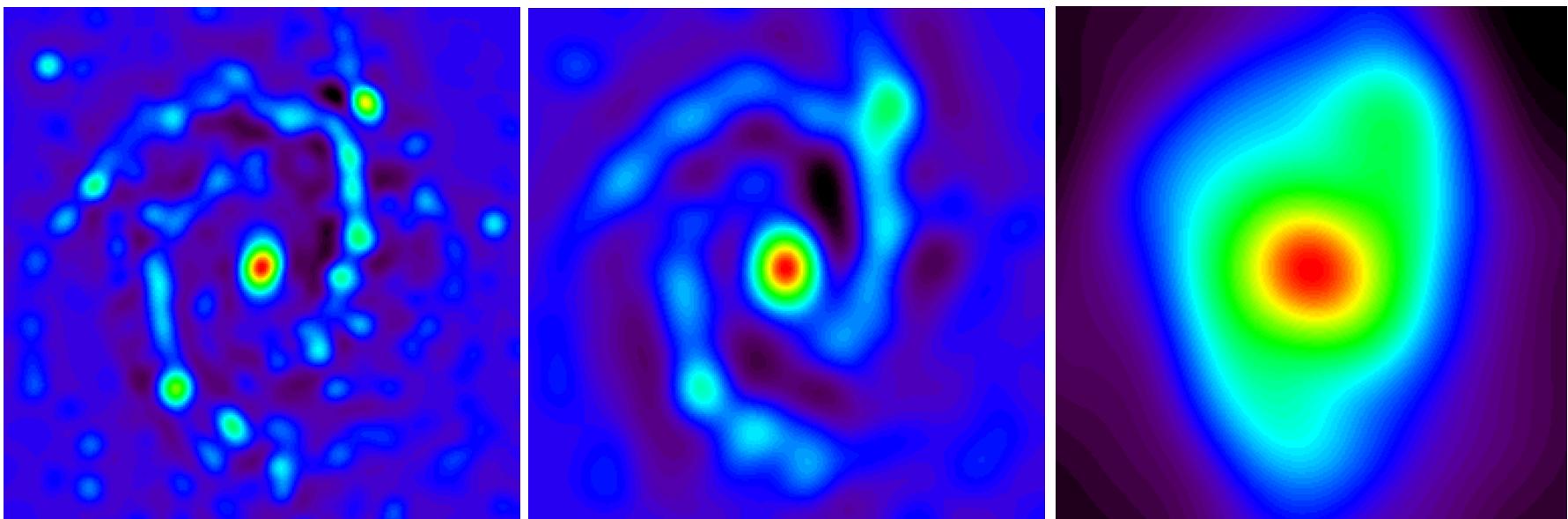
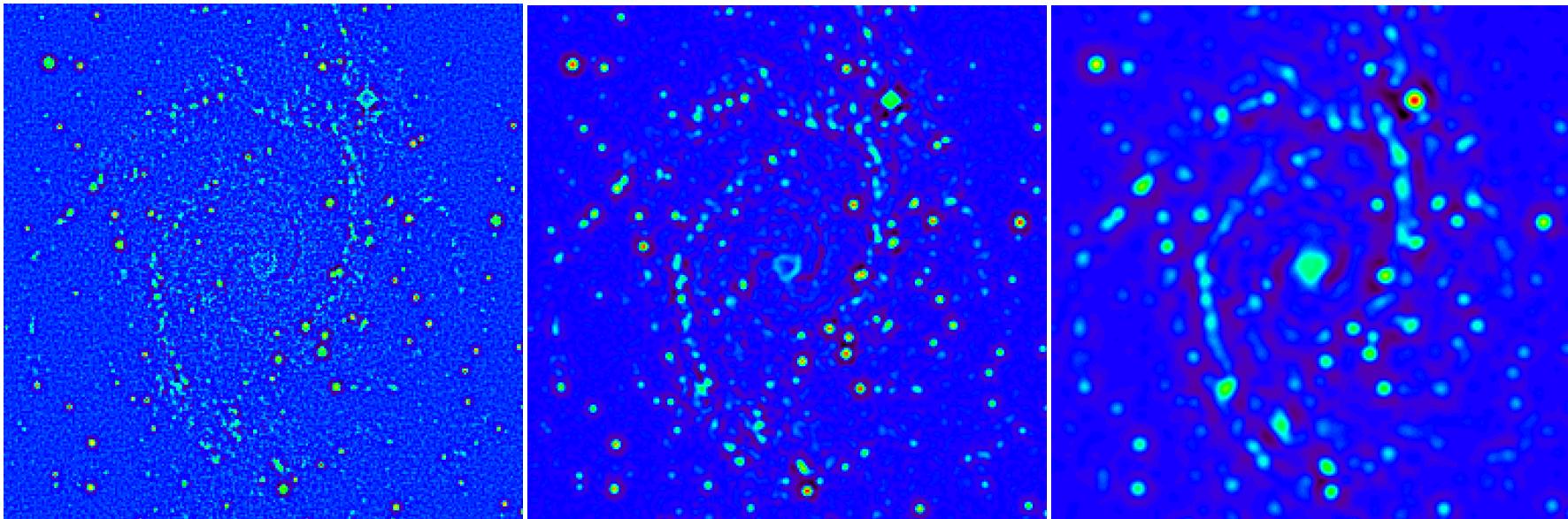
# The Curvelet Transform (CUR01)



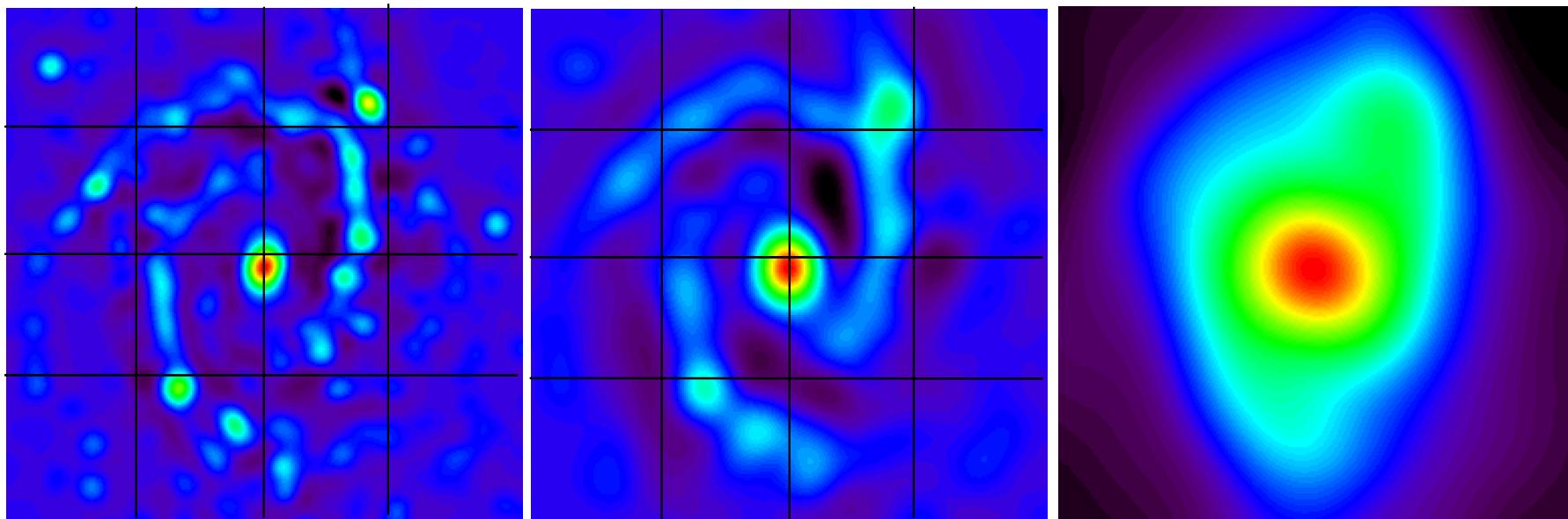
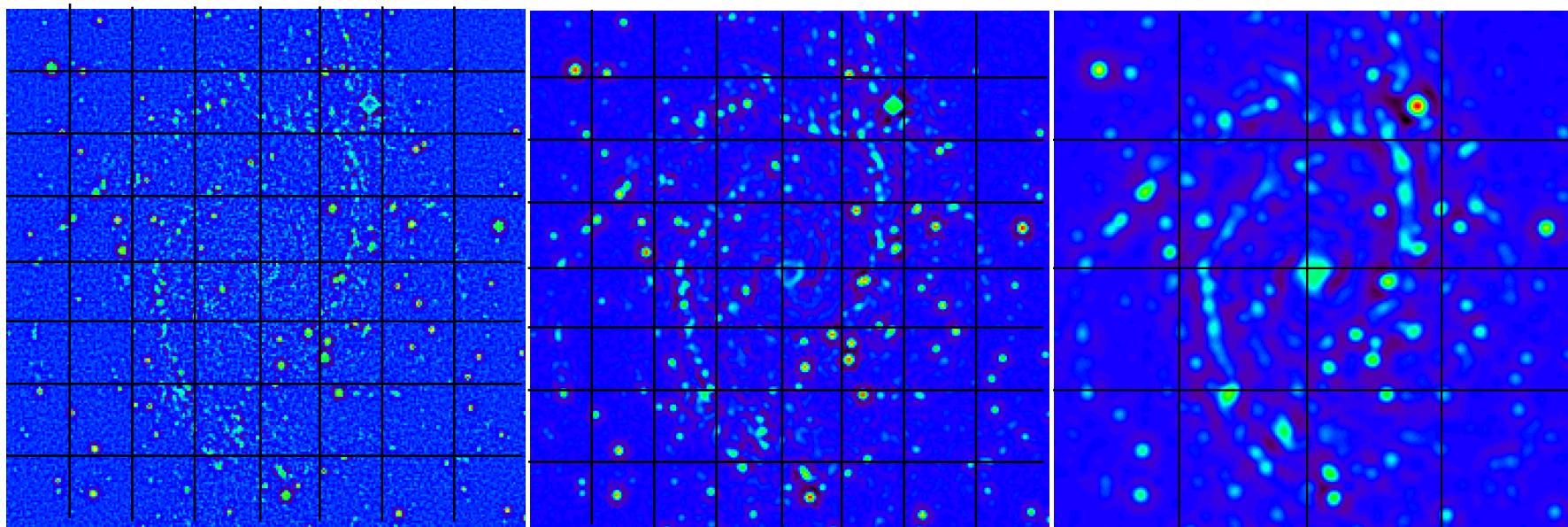
J.-L. Starck, E. Candes, D.L. Donoho **The Curvelet Transform for Image Denoising**, IEEE Transaction on Image Processing, 11, 6, 2002.

**Undecimated Isotropic WT:**

$$I(k, l) = c_{J, k, l} + \sum_{j=1}^J w_{j, k, l}$$



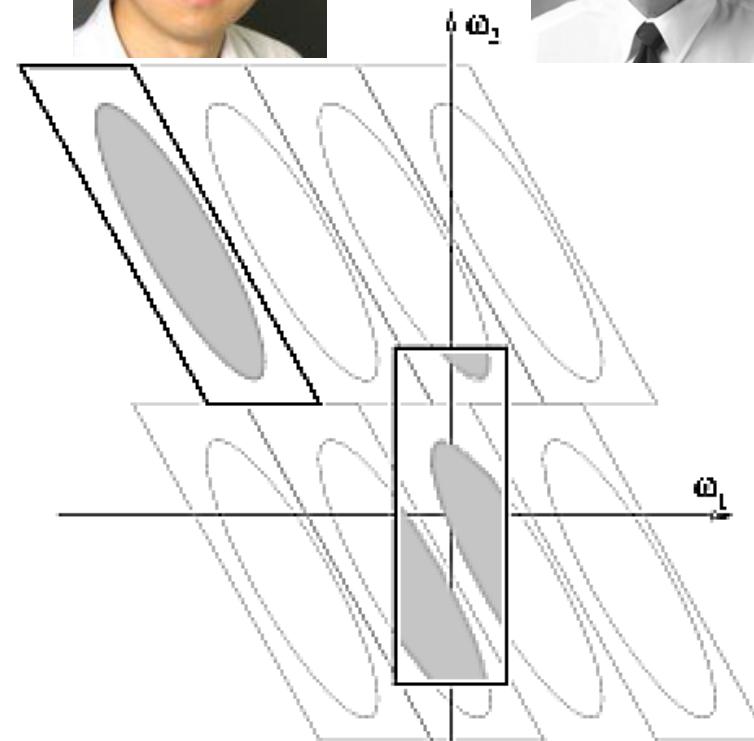
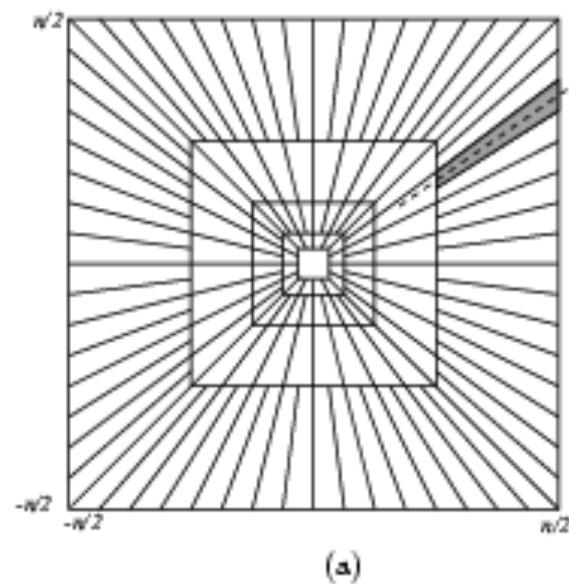
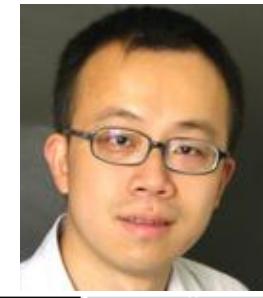
## PARTITIONING



## The Fast Curvelet Transform, Candes et al, 2005

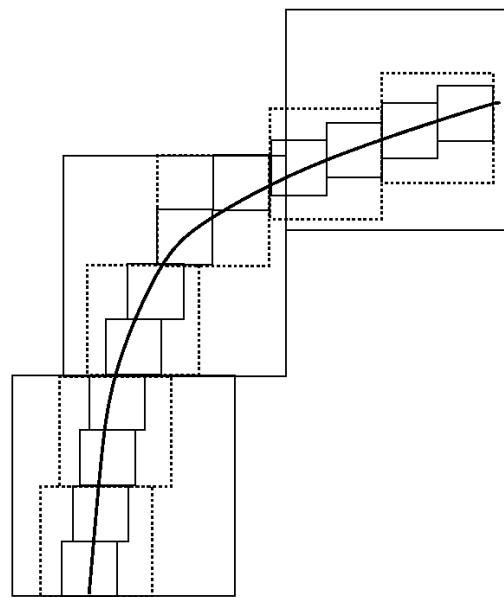
CUR03 - Fast Curvelet Transform using the USFFT

CUR04 - Fast Curvelet Transform using the Wrapping and 2DFFT

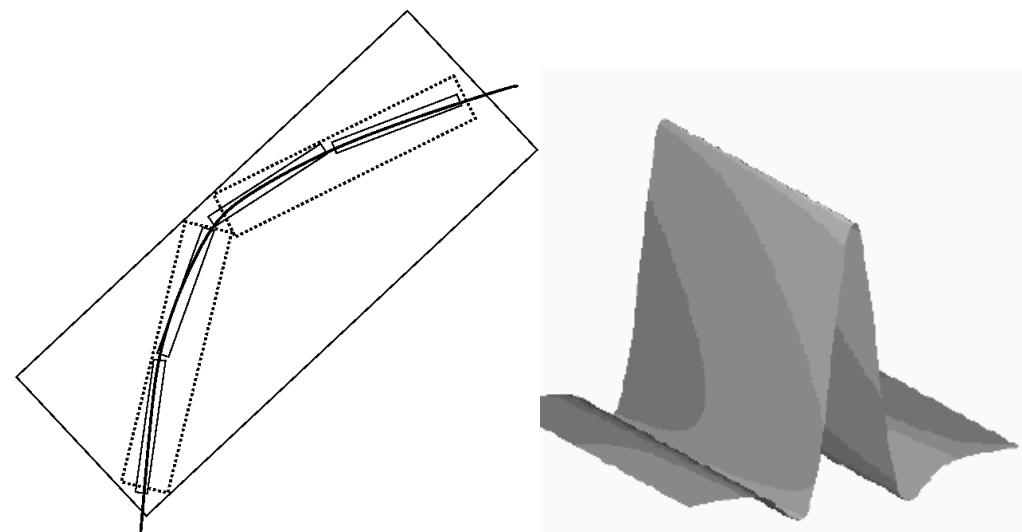


## Wavelets and edges

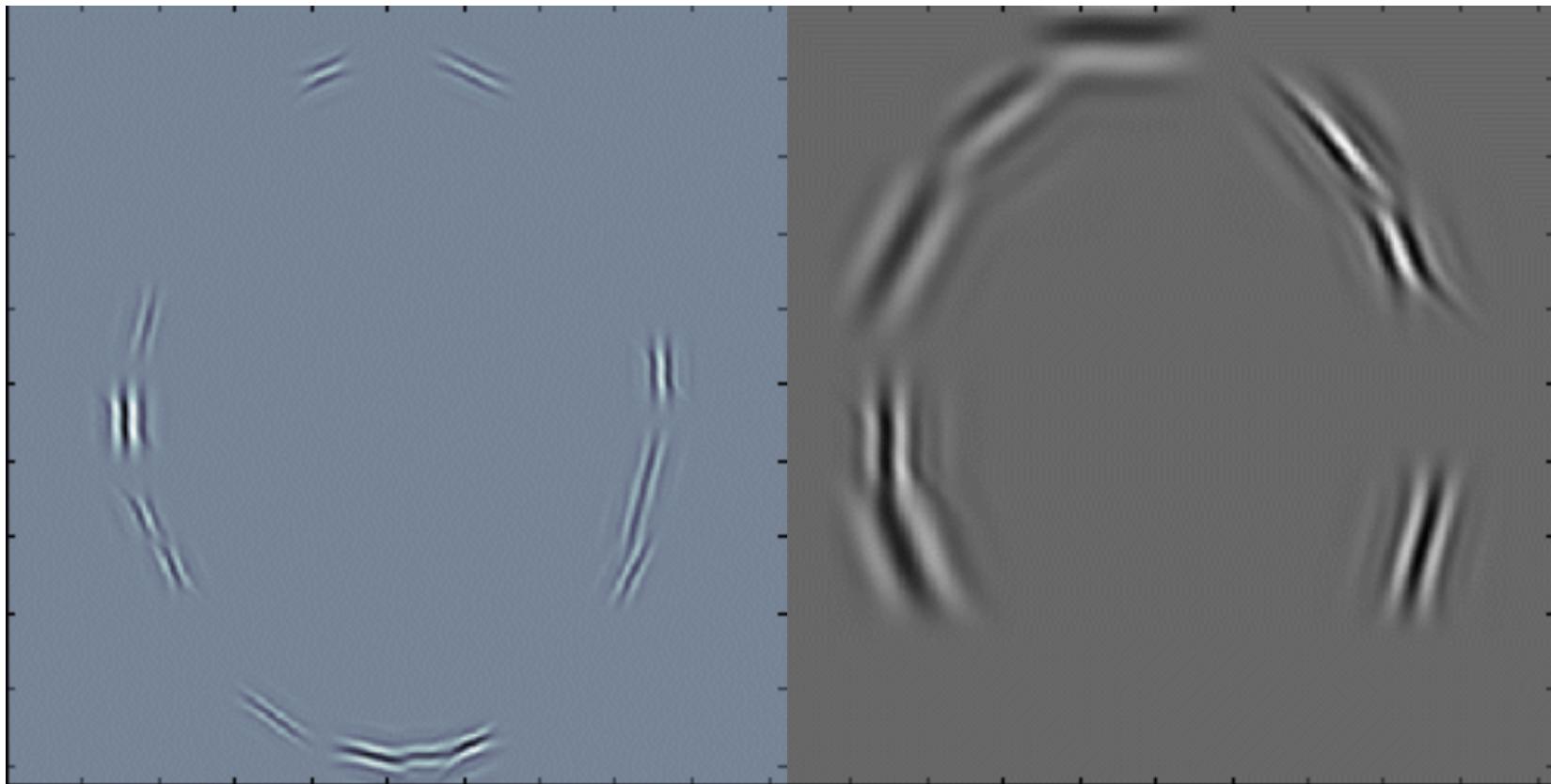
- many wavelet coefficients are needed to account for edges i.e. singularities along lines or curves :



- need dictionaries of strongly anisotropic atoms :



ridgelets, curvelets, contourlets, bandelettes, etc.



- J.L. Starck, E. Candes, and D.L. Donoho, "**The Curvelet Transform for Image Denoising**", IEEE Transactions on Image Processing , 11, 6, pp 670 –684, 2002.
- J.-L. Starck, M.K. Nguyen and F. Murtagh, "**Wavelets and Curvelets for Image Deconvolution: a Combined Approach**", Signal Processing, 83, 10, pp 2279–2283, 2003.
- J.-L. Starck, E. Candes, and D.L. Donoho, "**Astronomical Image Representation by the Curvelet Transform**", Astronomy and Astrophysics, 398, 785–800, 2003.
- J.-L. Starck, F. Murtagh, E. Candes, and D.L. Donoho, "**Gray and Color Image Contrast Enhancement by the Curvelet Transform**", IEEE Transaction on Image Processing, 12, 6, pp 706–717, 2003.

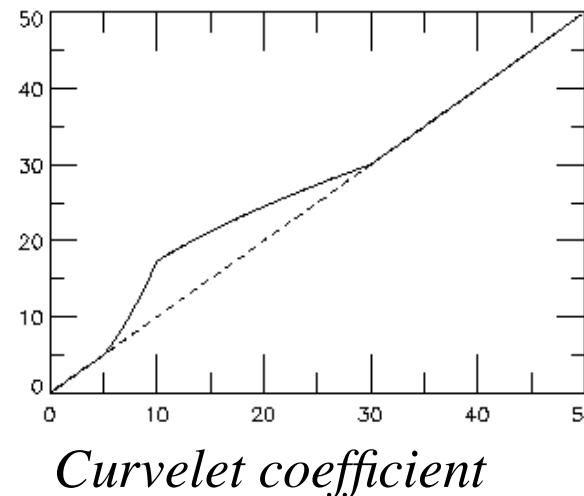
# CONTRAST ENHANCEMENT USING THE CURVELET TRANSFORM

J.-L Starck, F. Murtagh, E. Candes and D.L. Donoho, “Gray and Color Image Contrast Enhancement by the Curvelet Transform”,

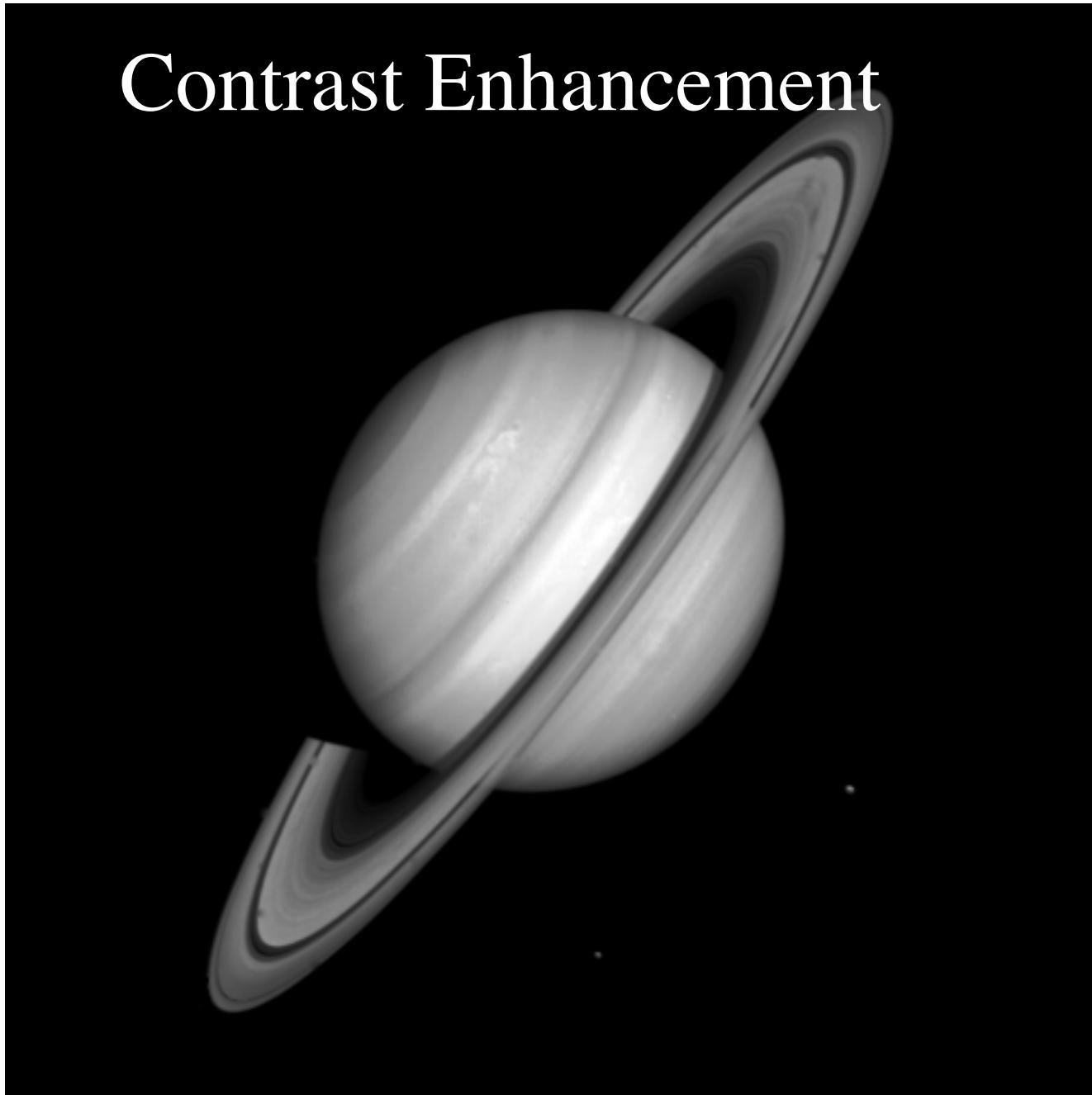
IEEE Transaction on Image Processing, 12, 6, 2003.

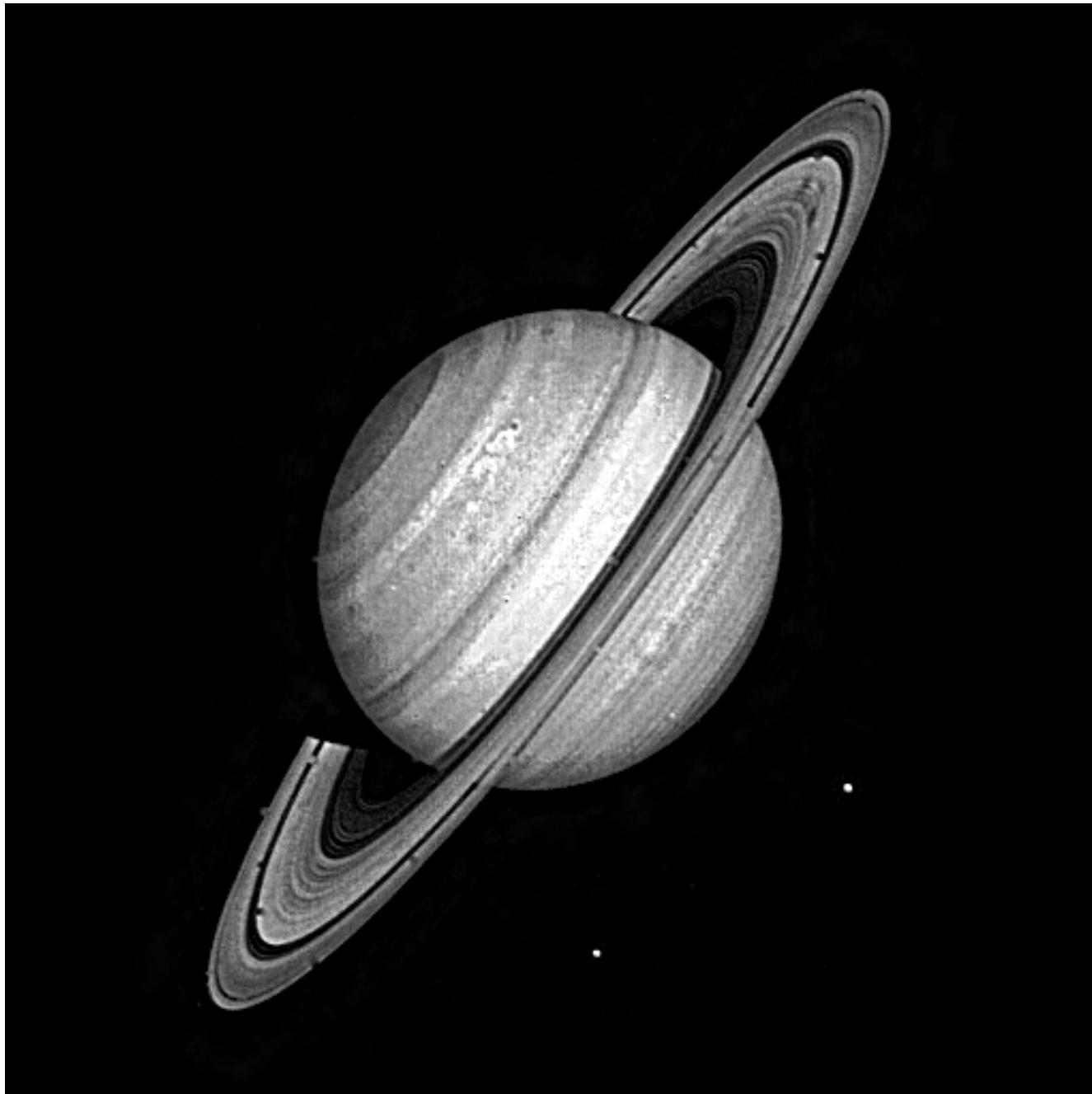
$$\tilde{I} = C_R(y_c(C_T I)) \quad \left\{ \begin{array}{ll} y_c(x, \sigma) = 1 & \text{if } x < c\sigma \\ y_c(x, \sigma) = \frac{x - c\sigma}{c\sigma} \left( \frac{m}{c\sigma} \right)^p + \frac{2c\sigma - x}{c\sigma} & \text{if } x < 2c\sigma \\ y_c(x, \sigma) = \left( \frac{m}{x} \right)^p & \text{if } 2c\sigma \leq x < m \\ y_c(x, \sigma) = \left( \frac{m}{x} \right)^s & \text{if } x > m \end{array} \right.$$

*Modified  
curvelet  
coefficient*



# Contrast Enhancement





comet Tempel 1 on July 4, 2005

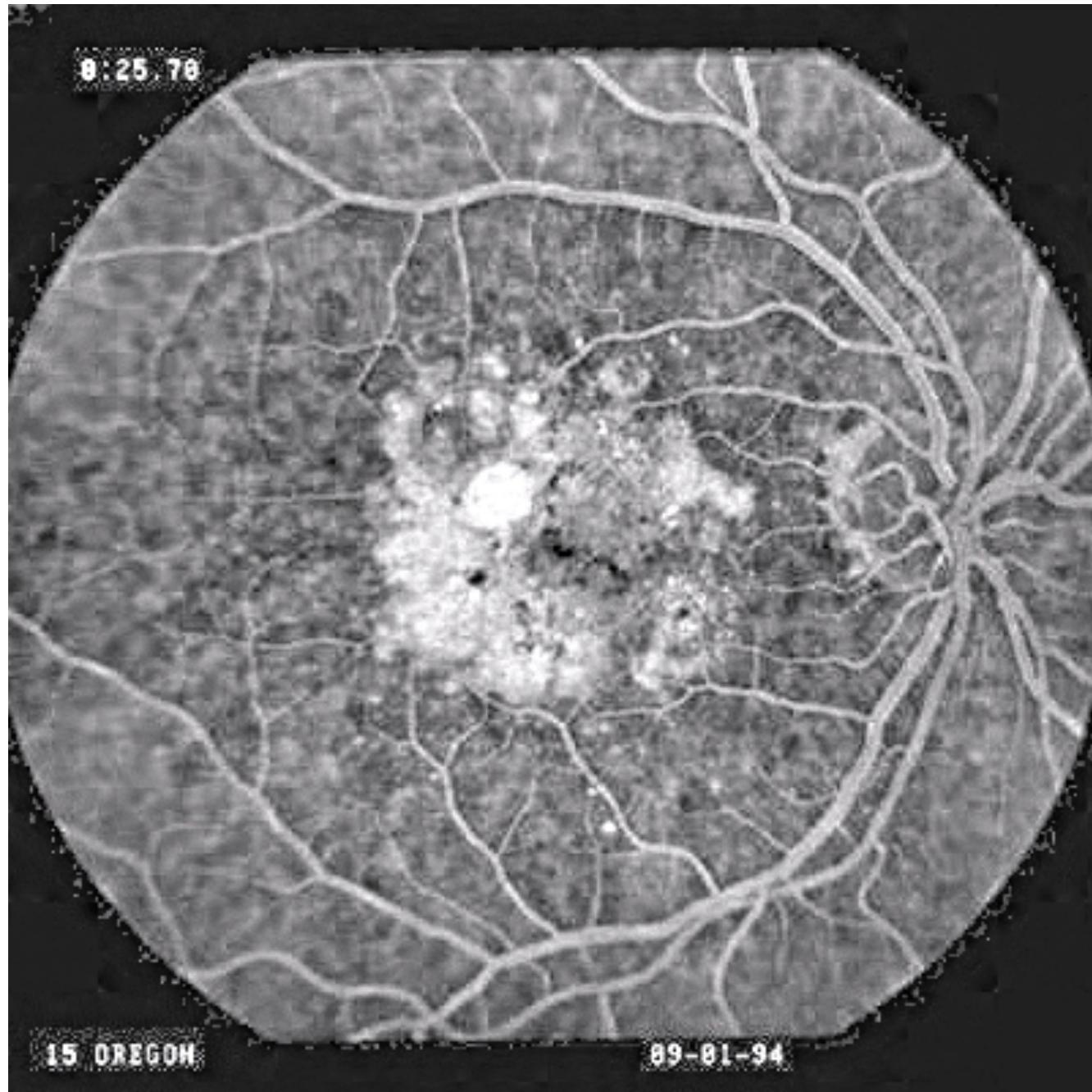


0:25.70



15 OREGON

09-01-94



8.25.78

15 OREGON

89-01-94





## INVERSE PROBLEMS

$$Y = HX + N$$

PB 1: find X knowing Y, H and the statistical properties of the noise N

Ex: Astronomical image deconvolution

Weak lensing

PB 2: find X and H knowing Y and the statistical properties of the noise N

Ex: Blind deconvolution

Multichannel Data (PCA, ICA, etc)

Ill posed problem, i.e. not an unique and stable solution ==> Regularization

$$\|Y - HX\|^2 \quad \text{with some constraints on } X$$

==> Sparsity constraint (i.e.  $\|X\|_0$ )

# DENOISING

## NOISE MODELING

For a positive coefficient:  $P = \text{Prob}(w > w_{j,x,y})$

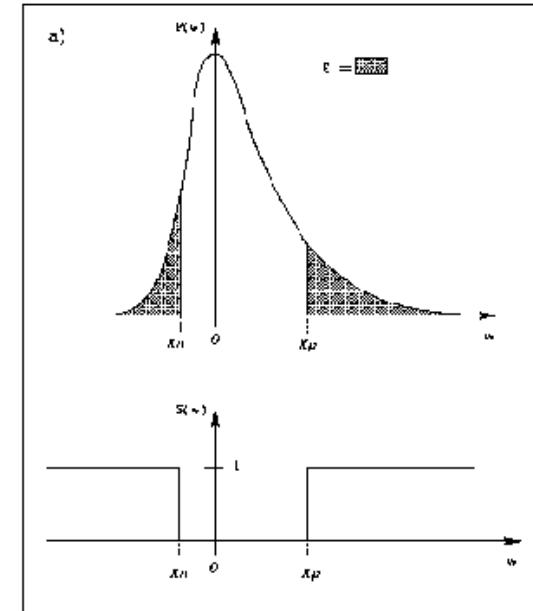
For a negative coefficient:  $P = \text{Prob}(w < w_{j,x,y})$

Given a threshold  $t$ :

if  $P > t$ , the coefficient could be due to the noise.  
 if  $P < t$ , the coefficient cannot be due to the noise,  
 and a **significant coefficient** is detected.

$$\begin{aligned} \text{Hard Thresholding: } \delta(c) &= c && \text{if } |c| \geq t \\ &= 0 && \text{if } |c| < t \end{aligned}$$

$$\text{Soft Thresholding: } \delta(c) = \text{sgn}(c)(|c| - t)_+$$

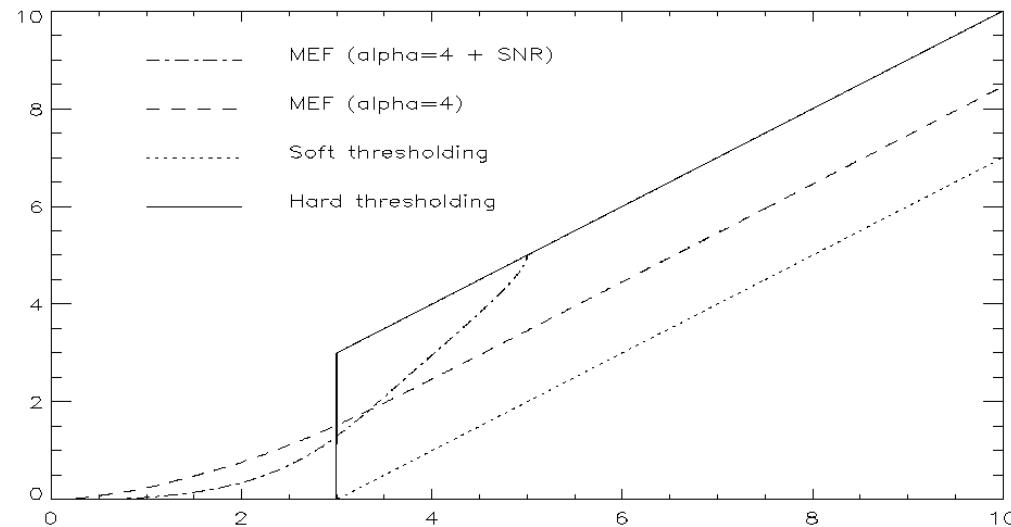


### DENOISING ALGORITHM

- Take the wavelet transform of the data.
- For each wavelet scale  $j$ 
  - Set to zero all coefficients with an absolute value lower than  $T_j$  ( $T_j$  is derived from the noise modeling).
- Apply the inverse wavelet transform to the thresholded coefficients.

$$\left. \right\} \tilde{y} = W_R[\delta(W_T y)]$$

## Filtered wavelet coefficients versus wavelet coefficients



## Threshold estimation: Gaussian case

1. k-sigma:  $T_j = k\sigma_j$
2. Universal Threshold:  $T_j = \sqrt{2 \log n} \sigma_j$
3. False Discovery Rate (FDR): compute the p-values for each wavelet coefficient  $w_{j,l}$  at scale j and position l using the noise level  $\sigma_j$ . The user parameter  $\alpha$  determines the number of false detections as a percentage of the number of true detections. The FDR fixes the threshold.

# CURVELET FILTERING

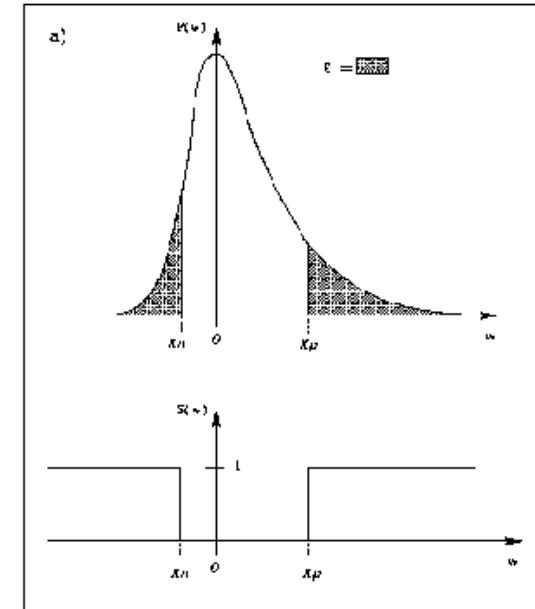
## NOISE MODELING

For a positive coefficient:  $P = \text{Prob}\{W \dots w\}$

For a negative coefficient  $P = \text{Prob}\{W \text{,, } w\}$

Given a threshold  $t$ :

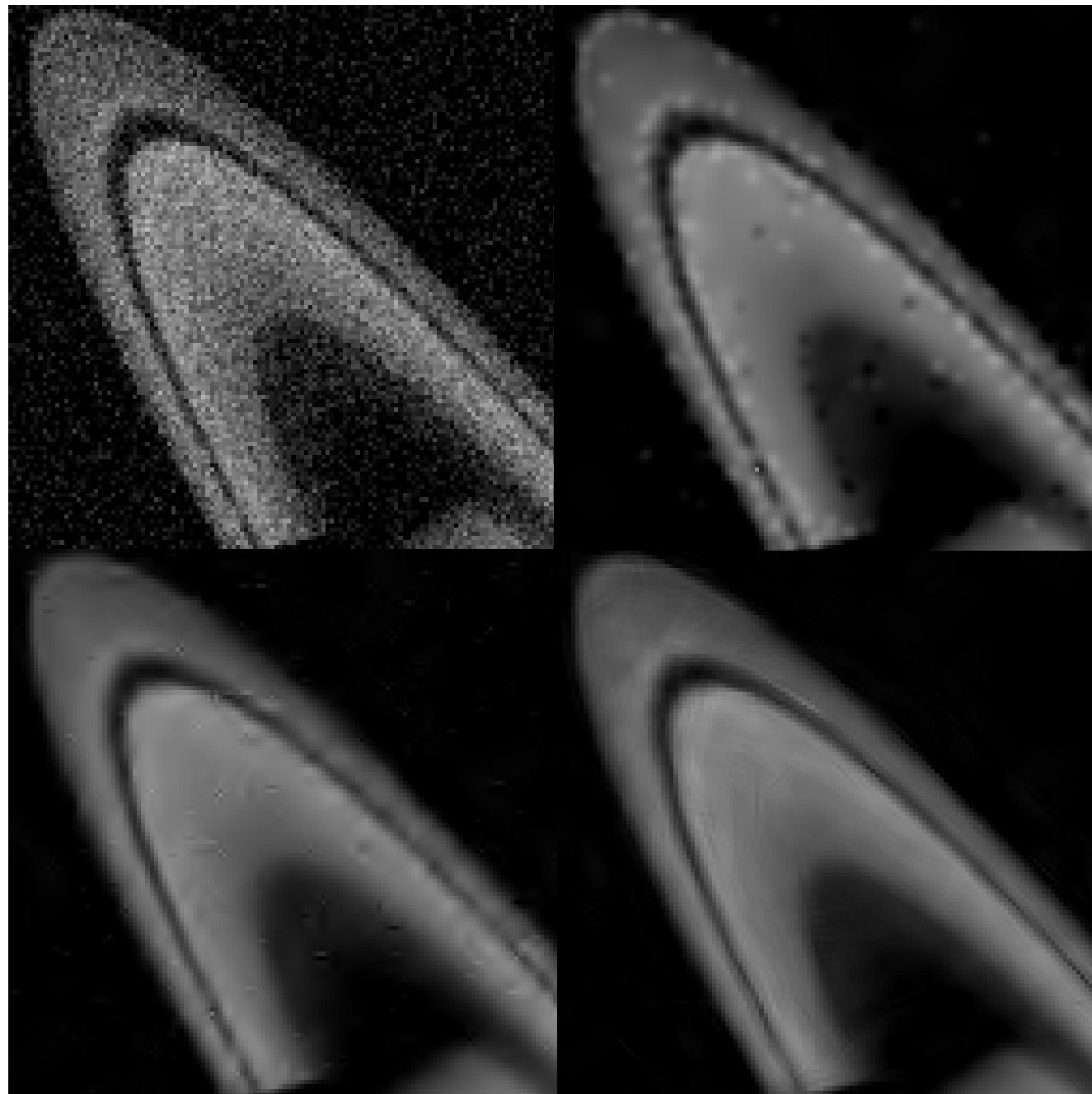
if  $P > t$ , the coefficient could be due to the noise.  
if  $P < t$ , the coefficient cannot be due to the noise,  
and a **significant coefficient** is detected.



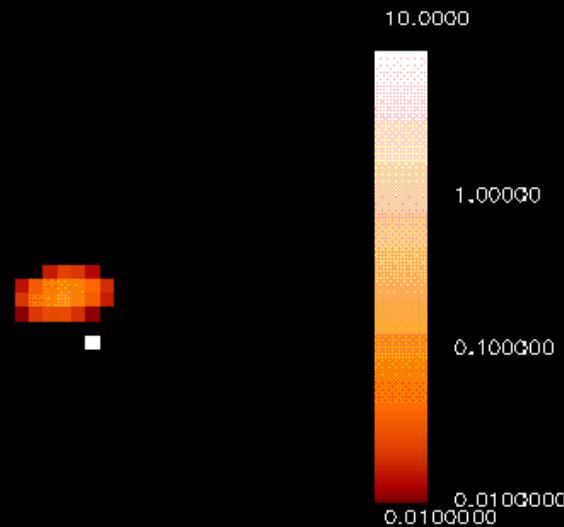
$$\tilde{y} = C_R[\delta(C_T y)]$$

Hard Thresholding:

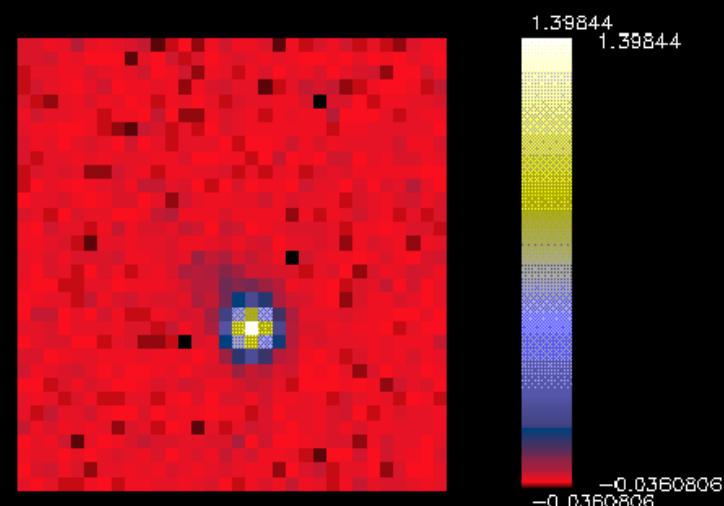
$$\begin{aligned}\delta(c) &= c && \text{if } |c| \geq t \\ &= 0 && \text{if } |c| < t\end{aligned}$$



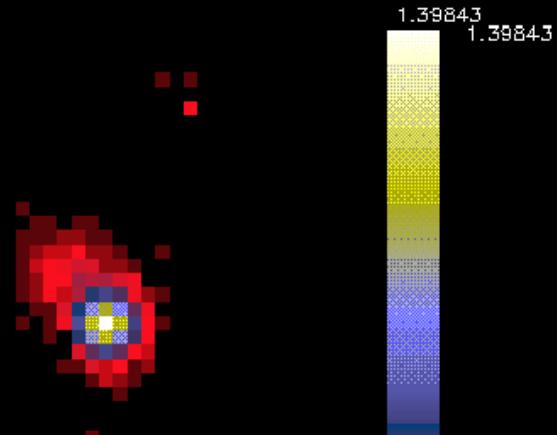
Simulation : faint galaxy nearby a bright star : original



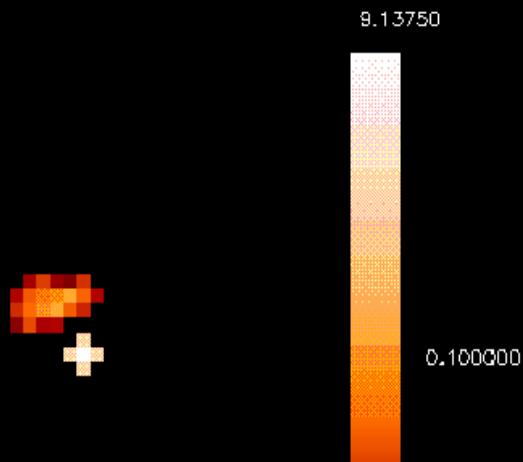
Simulation:weak galax. near a bright \*, convolv. with ISOCAM Psf,noise



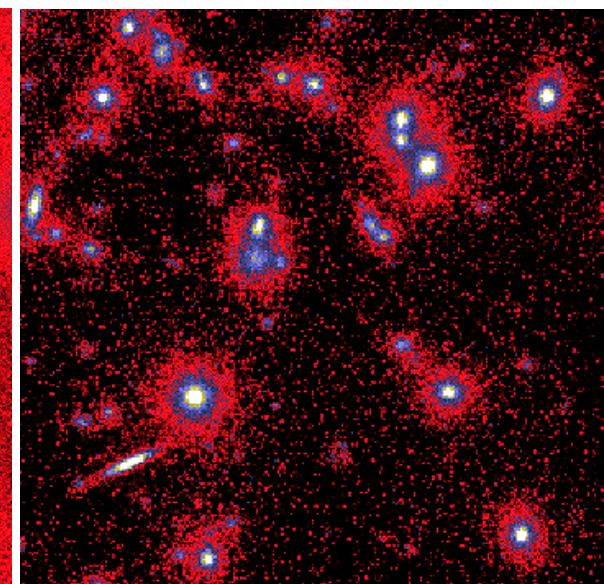
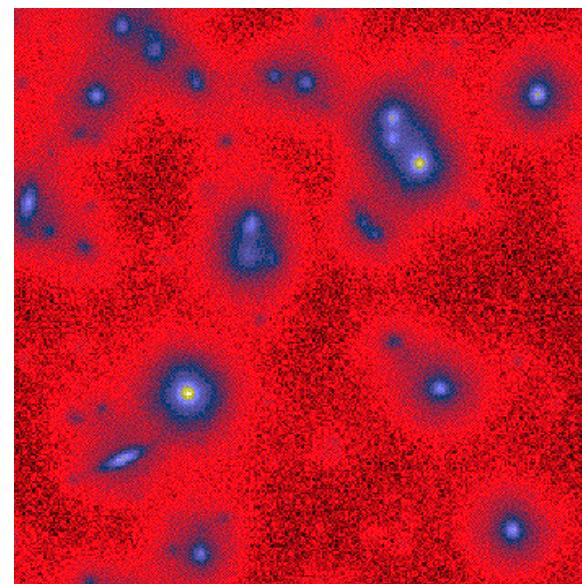
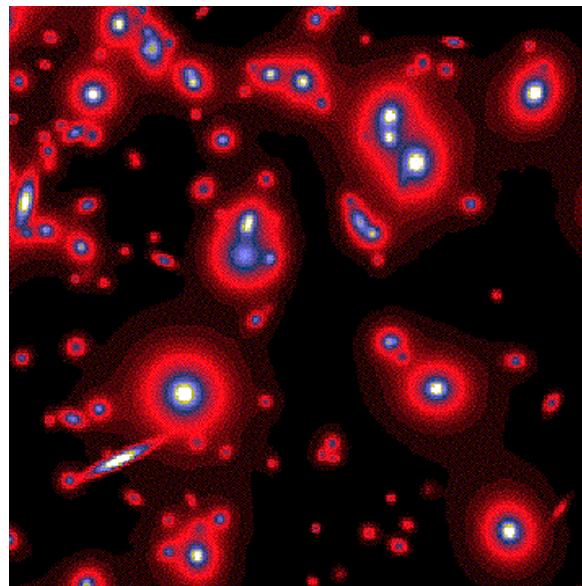
Simulation:weak galax. near a bright \* : after filtering



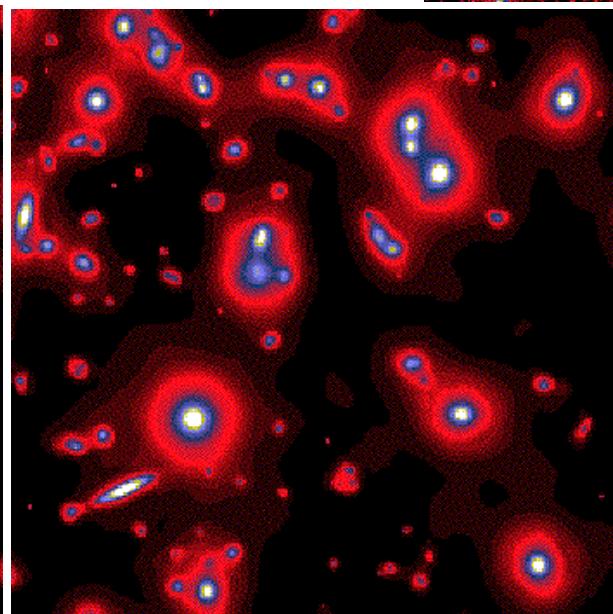
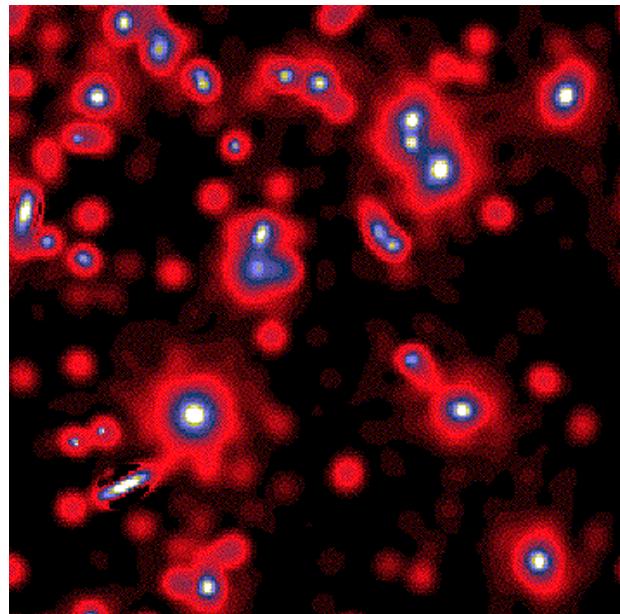
Simulation : faint galaxy nearby a bright star : after deconvolution



## DECONVOLUTION SIMULATION



PIXON

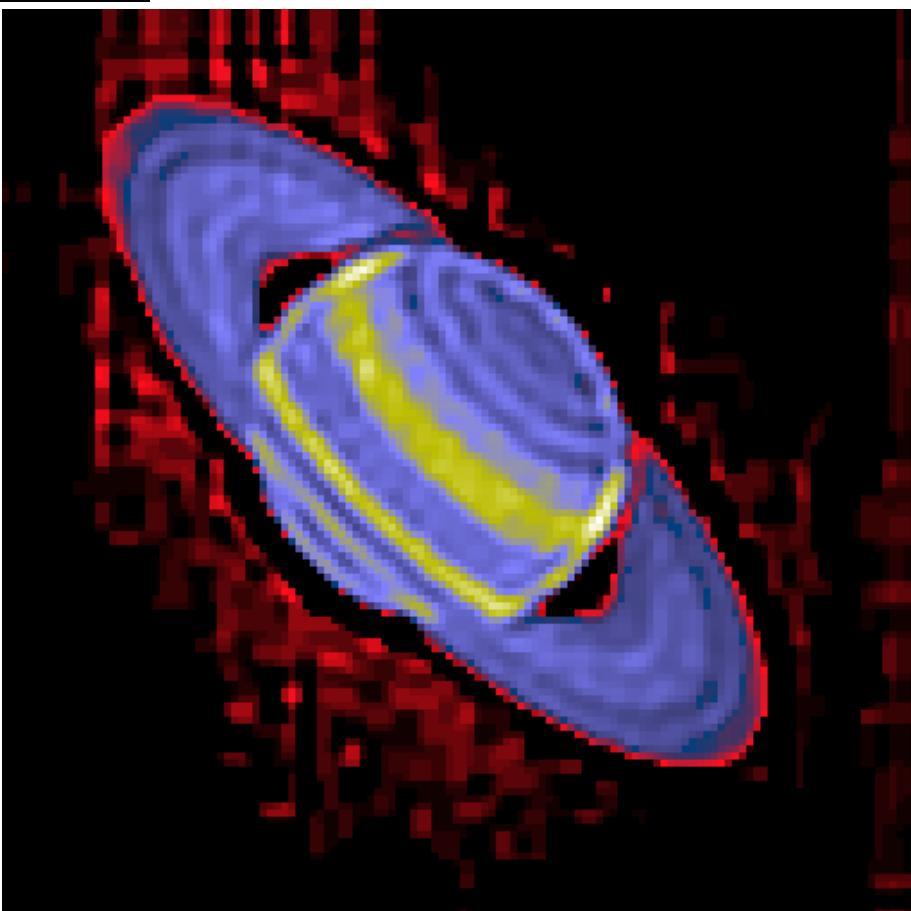
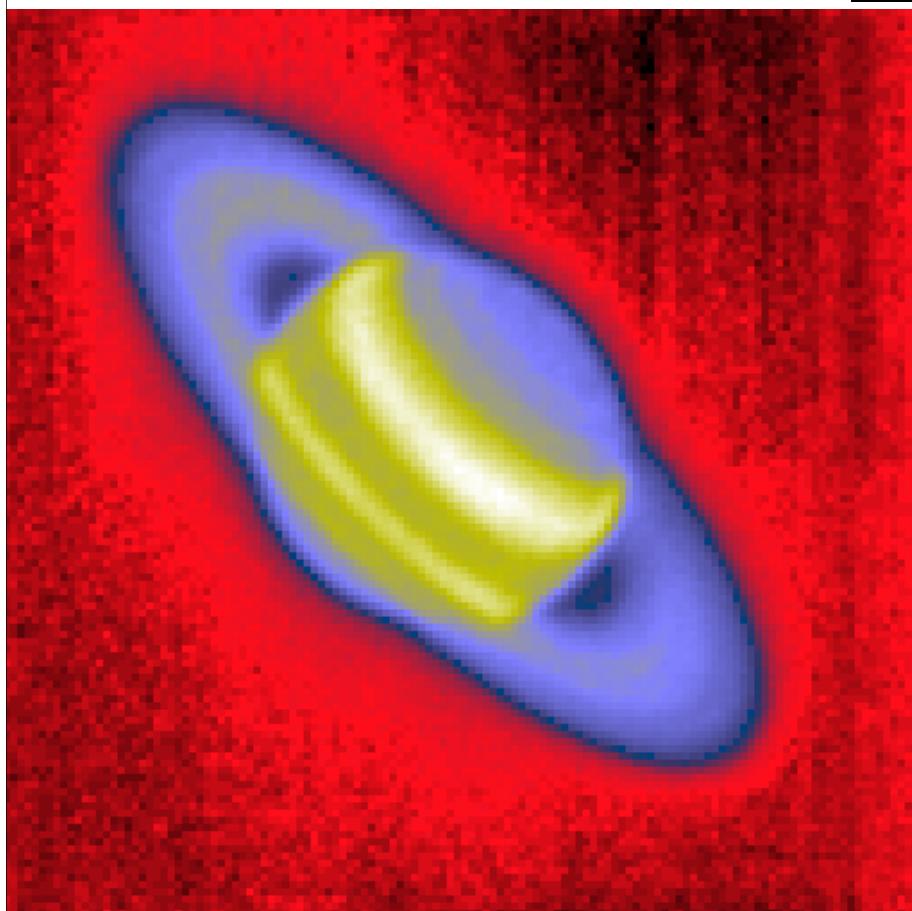
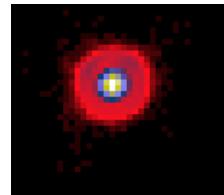


LUCY

← Wavelet

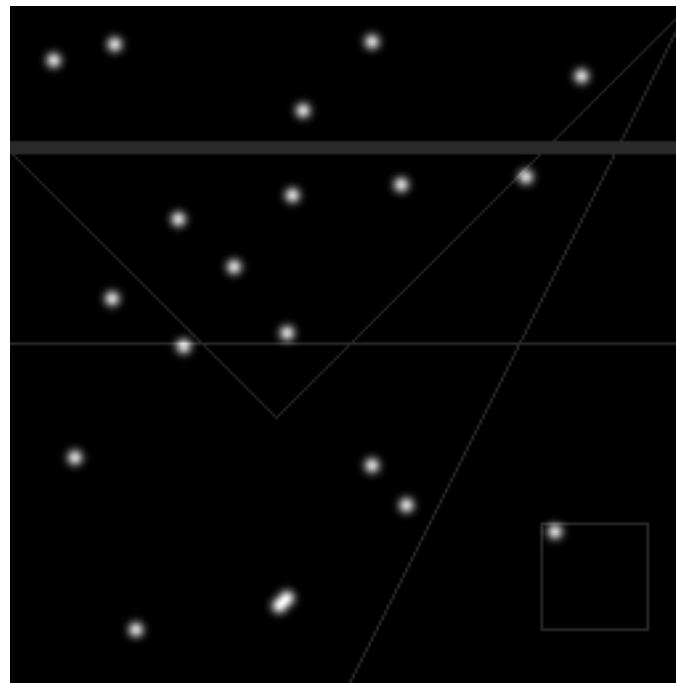
## DECONVOLUTION

- E. Pantin, J.-L. Starck, and F. Murtagh, "Deconvolution and Blind Deconvolution in Astronomy", in *Blind image deconvolution: theory and applications*, pp 277--317, 2007.
- J.-L. Starck, F. Murtagh, and M. Bertero, "The Starlet Transform in Astronomical Data Processing: Application to Source Detection and Image Deconvolution", Springer, *Handbook of Mathematical Methods in Imaging*, in press, 2010.

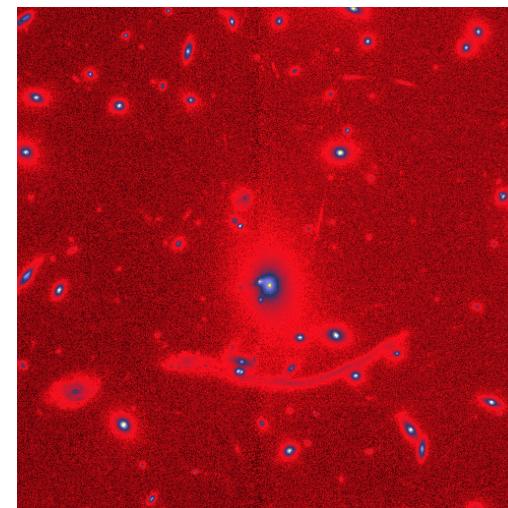
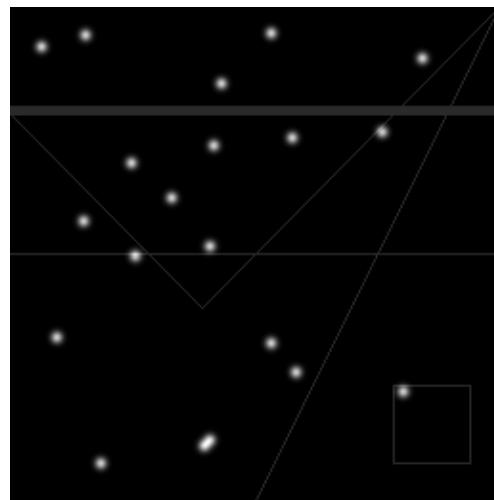


## A difficult issue

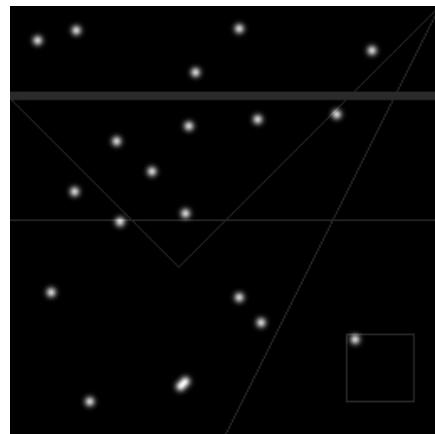
Is there any representation that well represents the following image ?



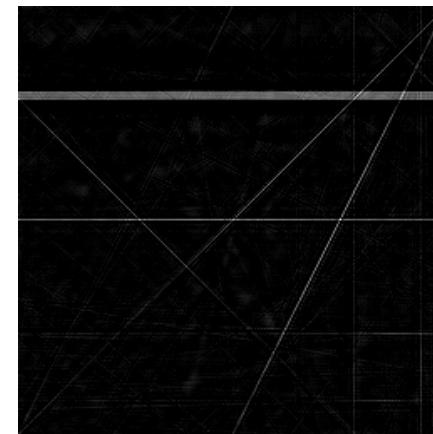
**PB:** a given transform does not necessary provide a good dictionary for all features contained in the data.



## Going further



=



+



Lines

Gaussians



Curvelets



Wavelets

**REDUNDANT REPRESENTATIONS**

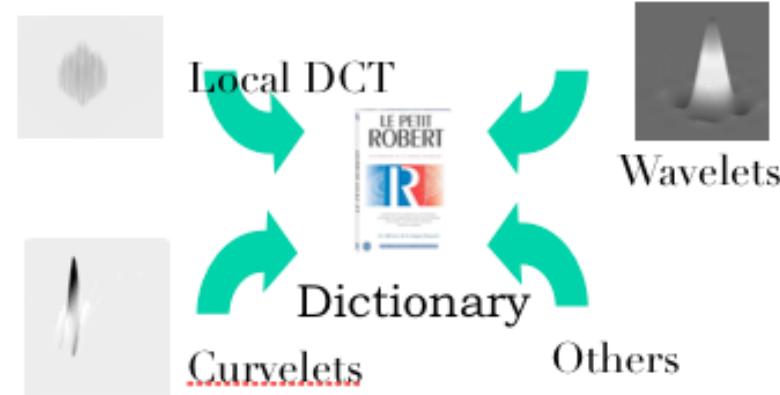
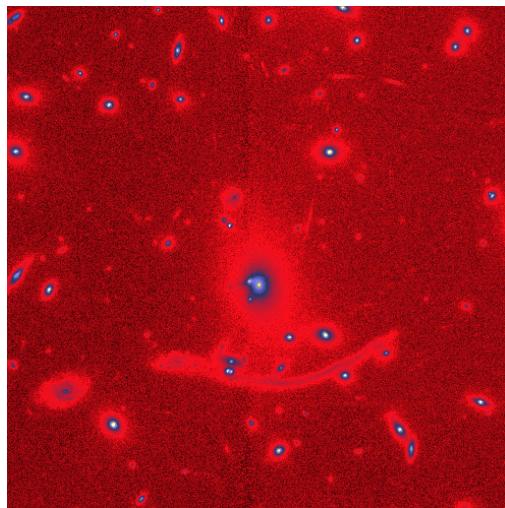


# Morphological Diversity

•J.-L. Starck, M. Elad, and D.L. Donoho, *Redundant Multiscale Transforms and their Application for Morphological Component Analysis*, *Advances in Imaging and Electron Physics*, 132, 2004.

•J.-L. Starck, M. Elad, and D.L. Donoho, *Image Decomposition Via the Combination of Sparse Representation and a Variational Approach*, *IEEE Trans. on Image Proces.*, 14, 10, pp 1570--1582, 2005.

•J.Bobin et al, *Morphological Component Analysis: an adaptive thresholding strategy*, *IEEE Trans. on Image Processing*, Vol 16, No 11, pp 2675--2681, 2007.



$$\phi = [\phi_1, \dots, \phi_L], \quad \alpha = \{\alpha_1, \dots, \alpha_L\}, \quad s = \phi\alpha = \sum_{k=1}^L \phi_k \alpha_k$$

**Sparsity Model 2:** we consider a signal as a sum of K components  $s_k$ ,  $s = \sum_{k=1}^K s_k$  each of them being sparse in a given dictionary :

$$s_k = \Phi_k \alpha_k$$

$$s = \sum_{k=1}^K s_k = \sum_{k=1}^K \Phi_k \alpha_k = \Phi \alpha$$





# New Perspectives



## Morphological Component Analysis (MCA)

- *Redundant Multiscale Transforms and their Application for Morphological Component Analysis*, Advances in Imaging and Electron Physics, 132, 2004.
- *Image Decomposition Via the Combination of Sparse Representation and a Variational Approach*, IEEE Trans. on Image Proces., 14, 10, pp 1570--1582, 2005.
- *Morphological Component Analysis: an adaptive thresholding strategy*, IEEE Trans. on Image Processing, Vol 16, No 11, pp 2675--2681, 2007.

$$J(s_1, \dots, s_L) = \left\| s - \sum_{k=1}^L s_k \right\|_2^2 + \lambda \sum_{k=1}^L \|T_k s_k\|_p$$

# Morphological Component Analysis (MCA)

$$J(s_1, \dots, s_L) = \left\| s - \sum_{k=1}^L s_k \right\|_2^2 + \lambda \sum_{k=1}^L \|T_k s_k\|_p$$

- . Initialize all  $s_k$  to zero
- . Iterate  $j=1, \dots, N_{\text{iter}}$ 
  - Iterate  $k=1, \dots, L$

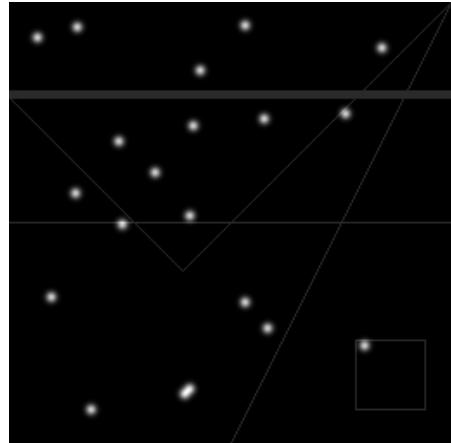
Update the  $k$ th part of the current solution by fixing all other parts and minimizing:

$$J(s_k) = \left\| s - \sum_{i=1, i \neq k}^L s_i - s_k \right\|_2^2 + \lambda^{(j)} \|T_k s_k\|_p$$

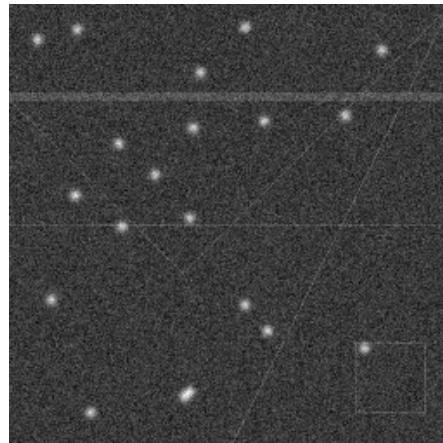
Which is obtained by a simple **hard**/soft thresholding of :  $s_r = s - \sum_{i=1, i \neq k}^L s_i$

- Decrease the threshold  $\lambda^{(j)}$

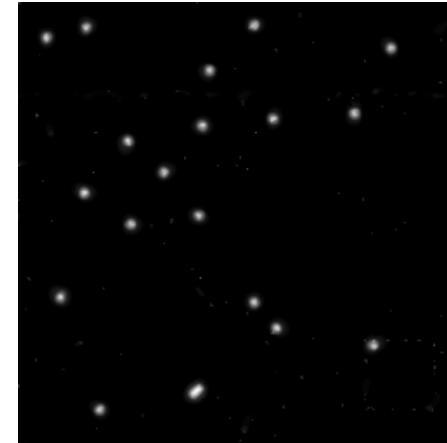
$$MIN_{s_1, s_2} (\|W s_1\|_p + \|C s_2\|_p) \text{ subject to } \|s - (s_1 + s_2)\|_2^2 < \varepsilon$$



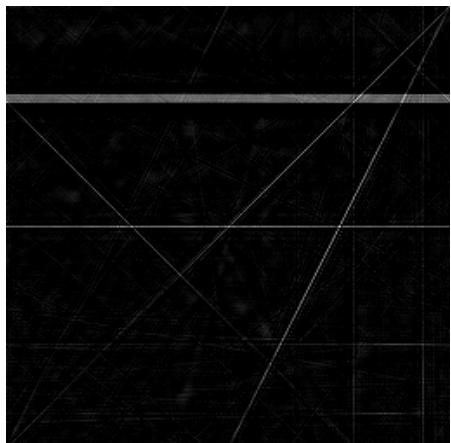
a) Simulated image (gaussians+lines)



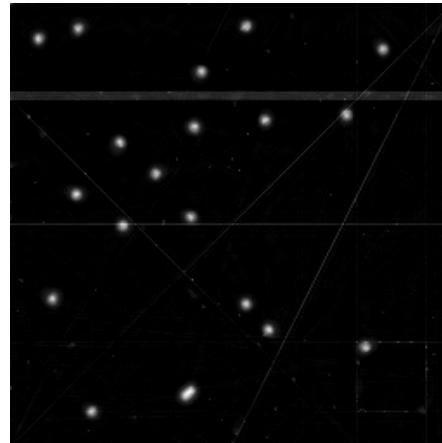
b) Simulated image + noise



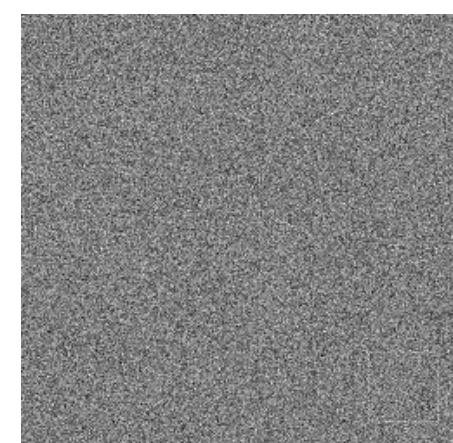
c) A trous algorithm



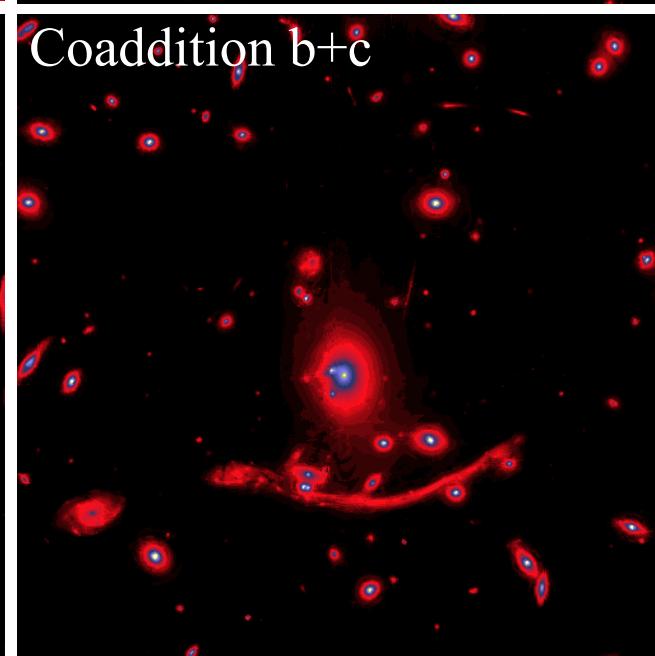
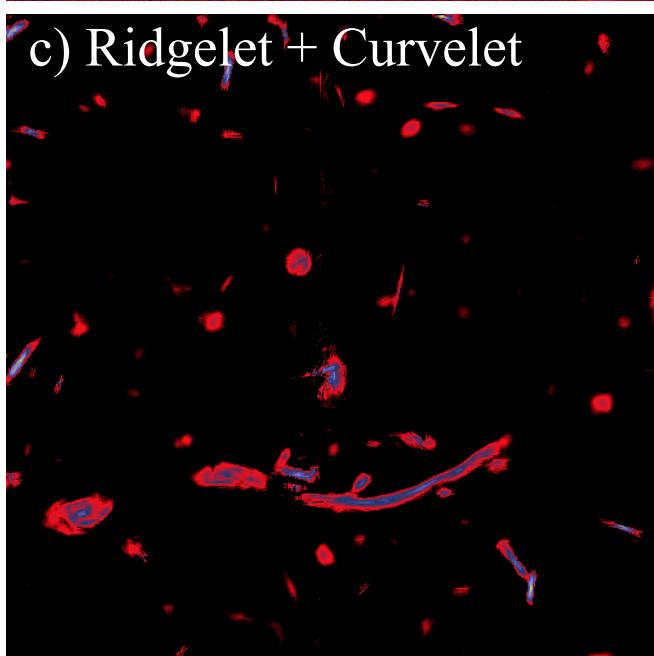
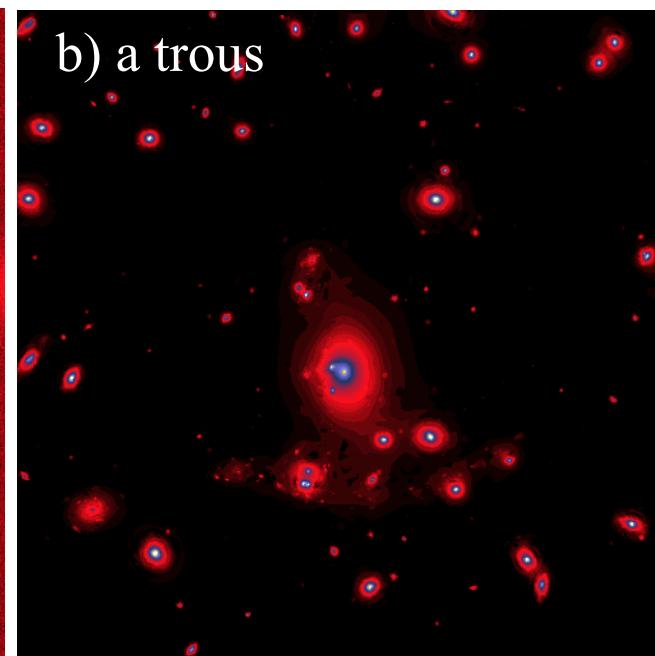
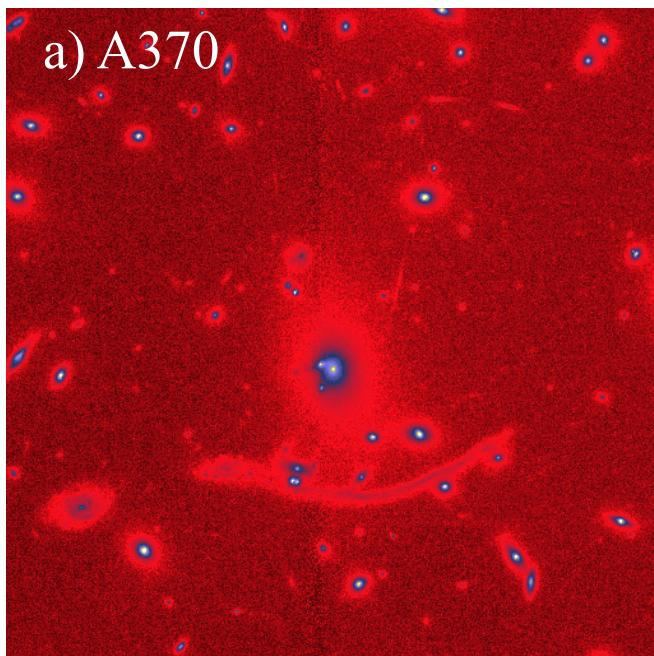
d) Curvelet transform

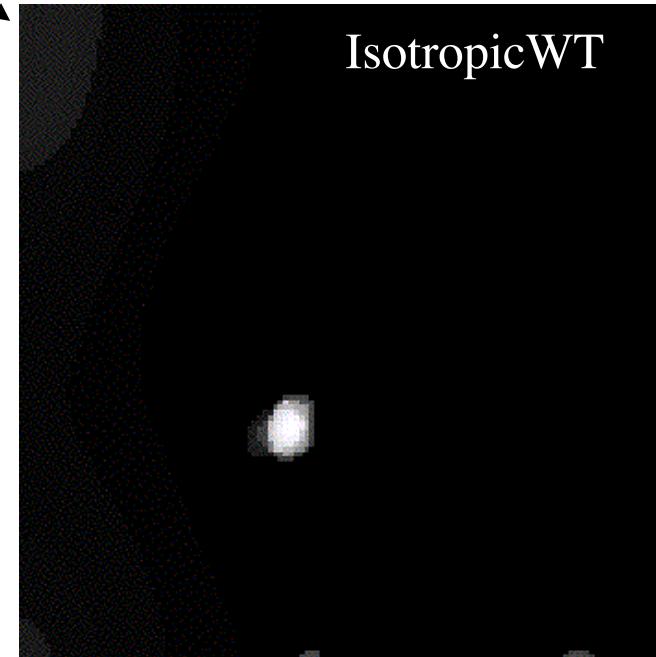
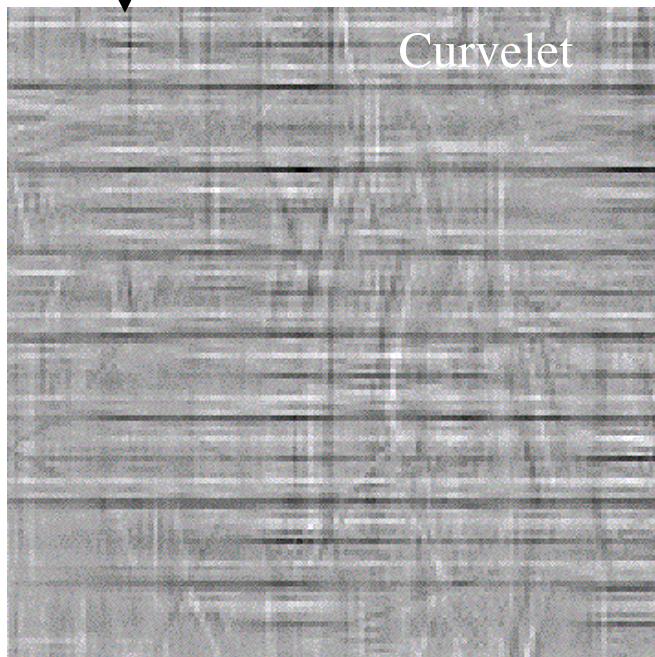
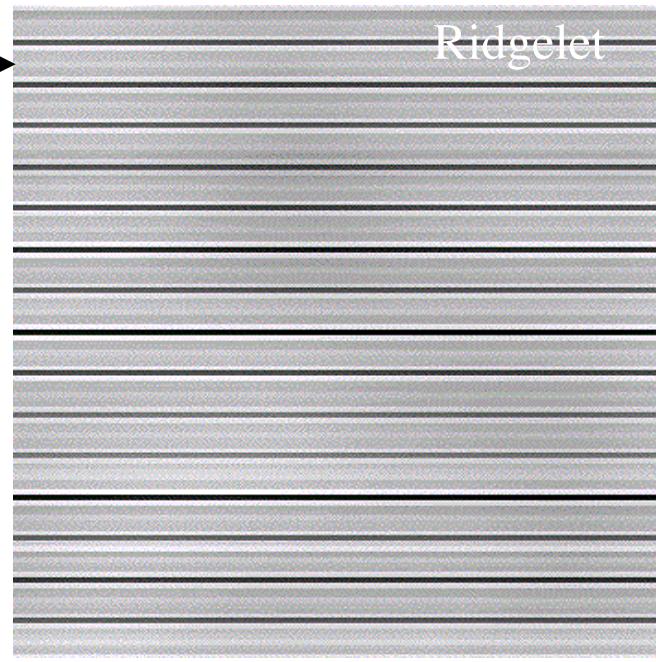
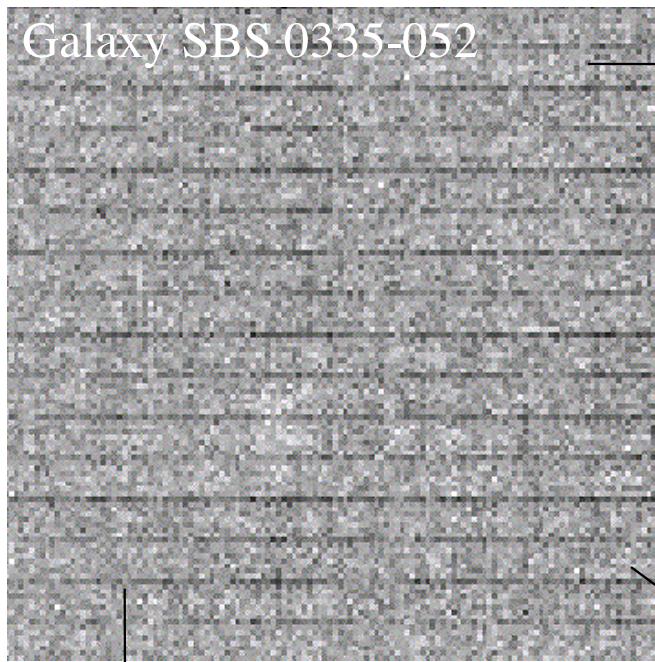


e) coaddition c+d

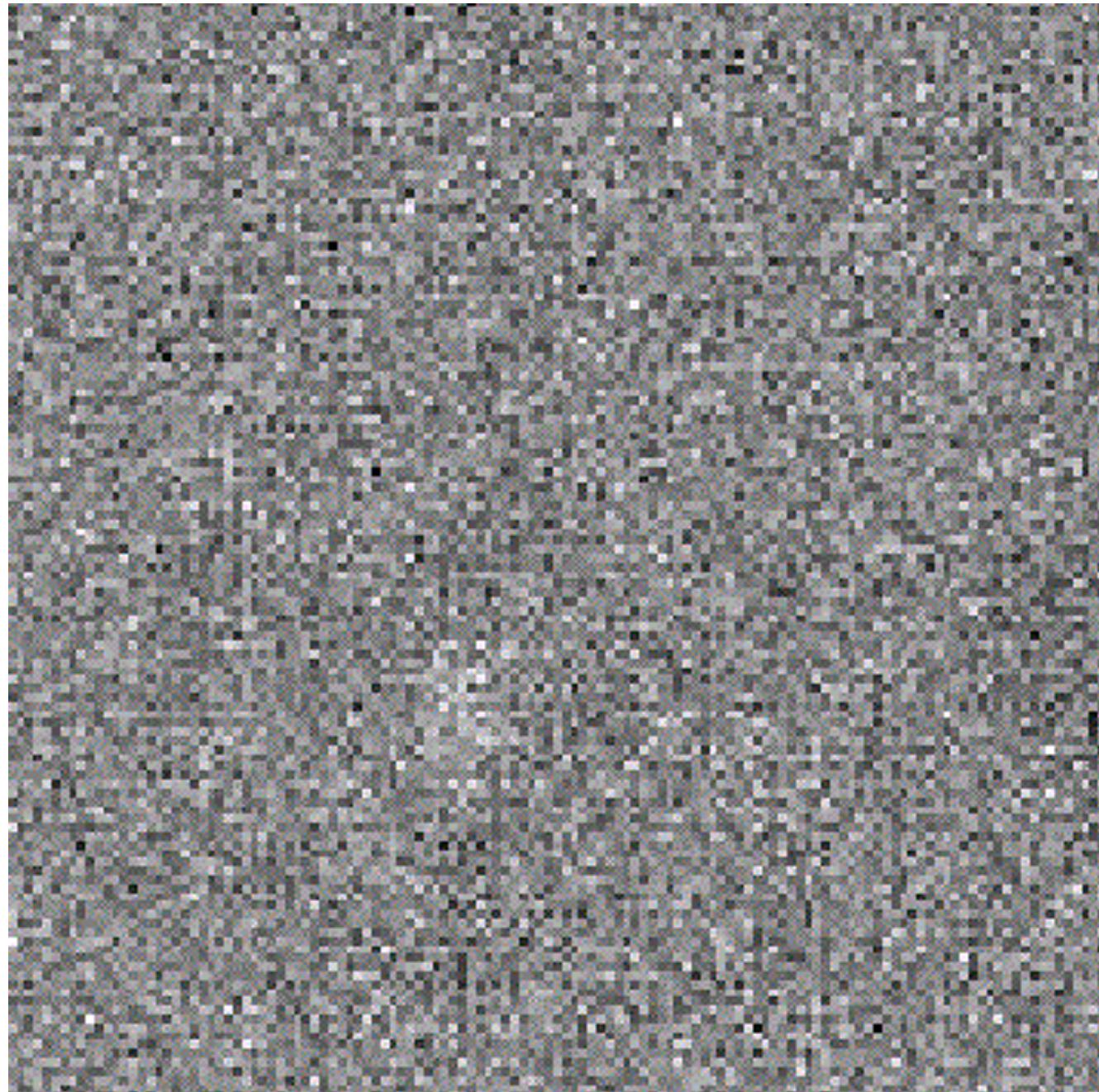


f) residual = e-b



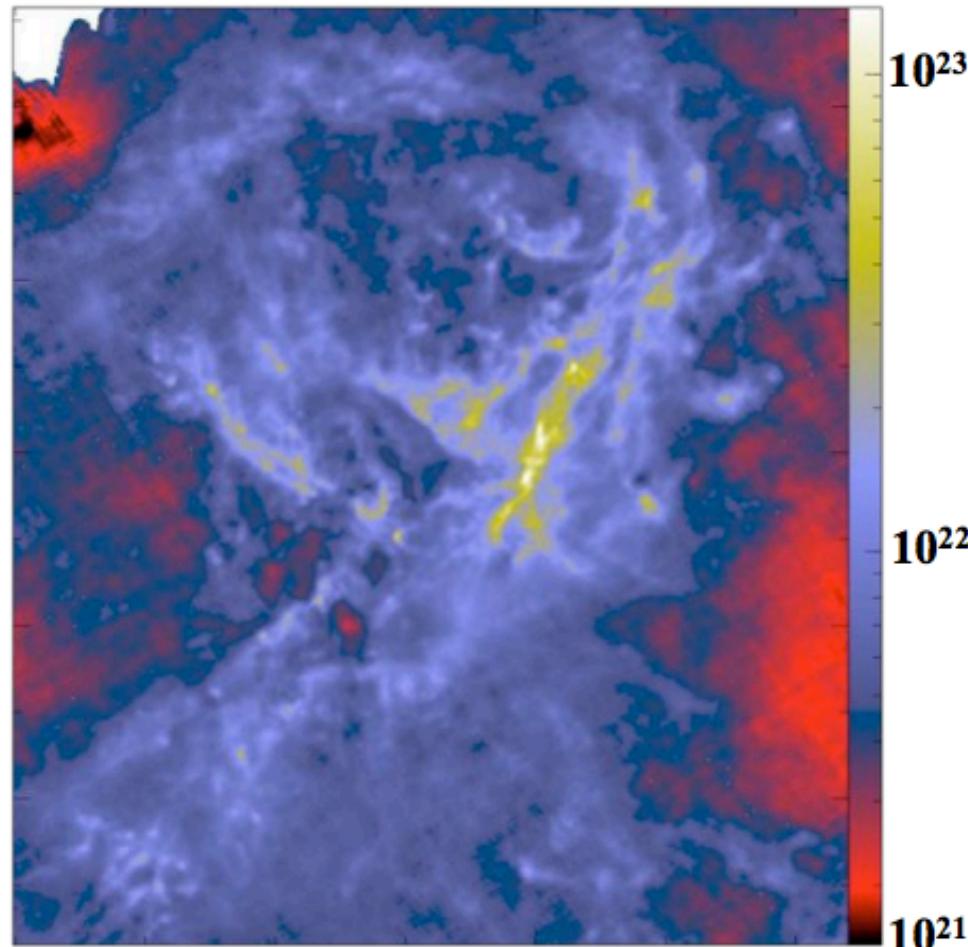


**Galaxy SBS 0335-052**  
**10 micron**  
**GEMINI-OSCIR**



Revealing the structure of one of the nearest infrared dark clouds (Aquila Main:  $d \sim 260$  pc)

**Herschel (SPIRE+PACS)**  
**Column density map ( $\text{H}_2/\text{cm}^2$ )**



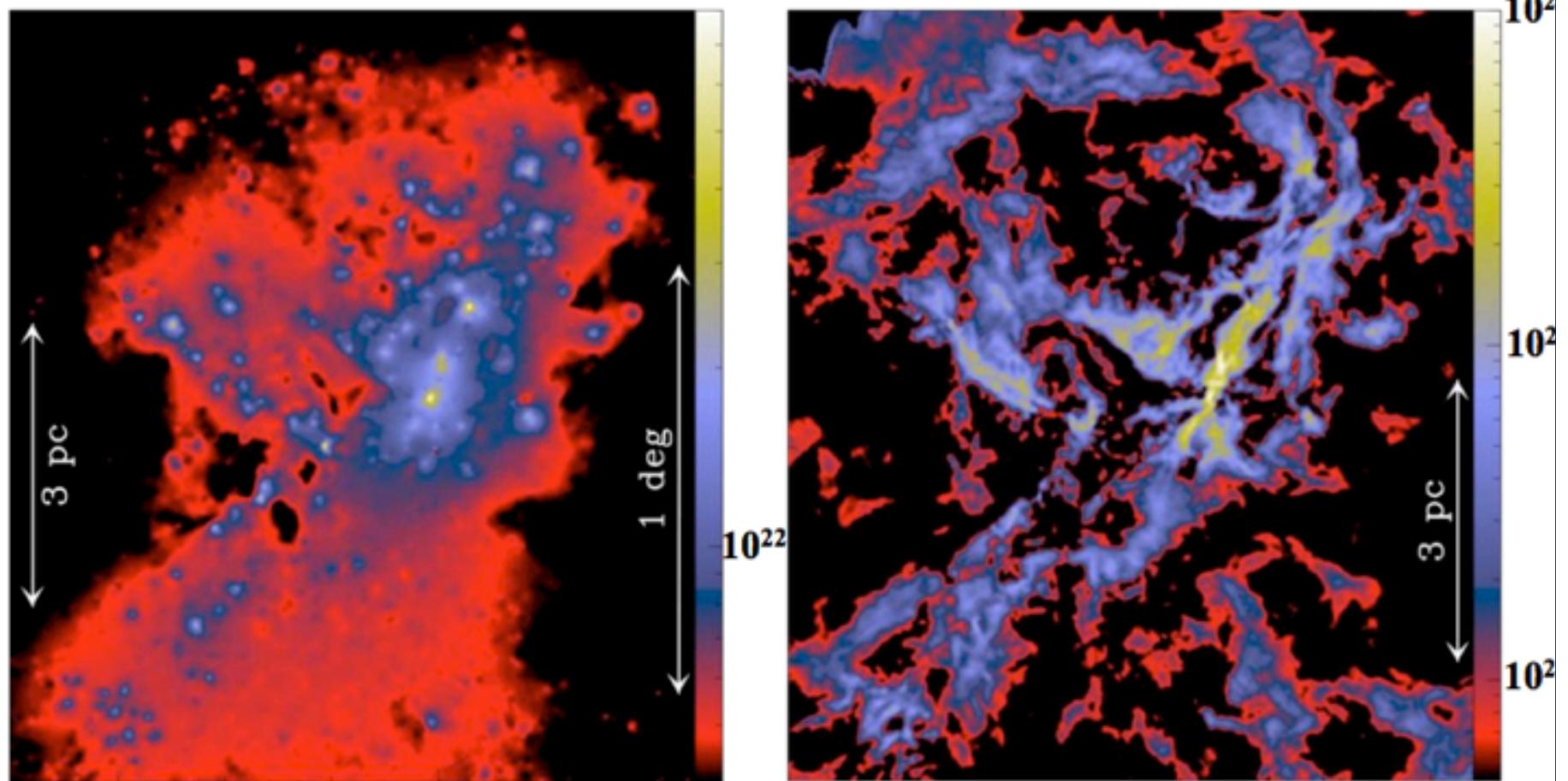
# Dense cores form primarily in filaments

## Morphological Component Analysis:

### *Herschel* Column density map

$$\text{Cores} \quad \text{Wavelet component } (\text{H}_2/\text{cm}^2) = \text{Filaments} + \text{Curvelet component } (\text{H}_2/\text{cm}^2)$$

(P. Didelon based on  
Starck et al. 2003)



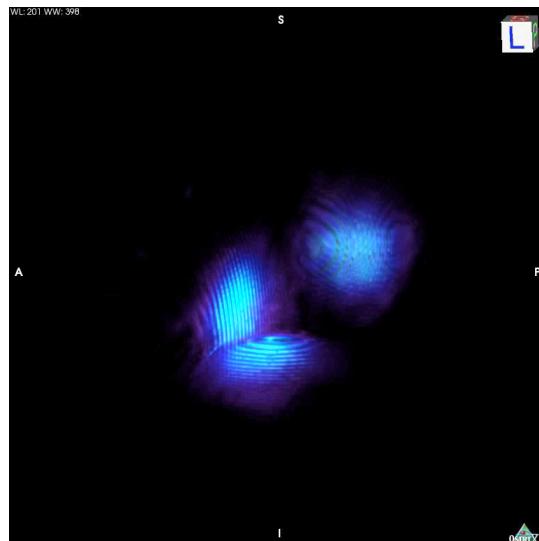
A. Menshchikov, Ph. André, P. Didelon, et al., "Filamentary structures and compact objects in the Aquila and Polaris clouds observed by Herschel", A&A, 518, id.L103, 2010.

# 3D Morphological Component Analysis

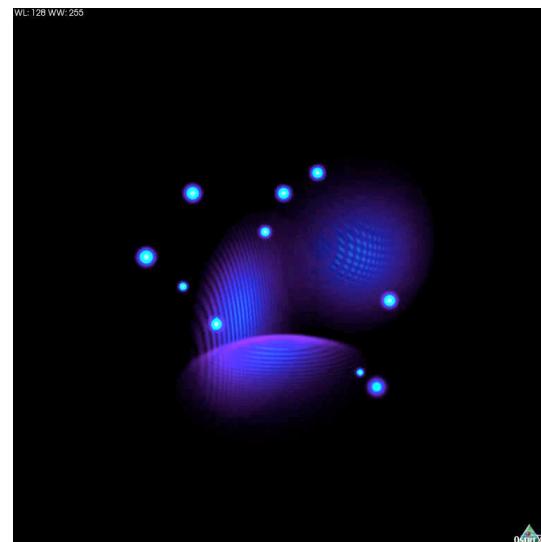


A. Woiselle

Shells

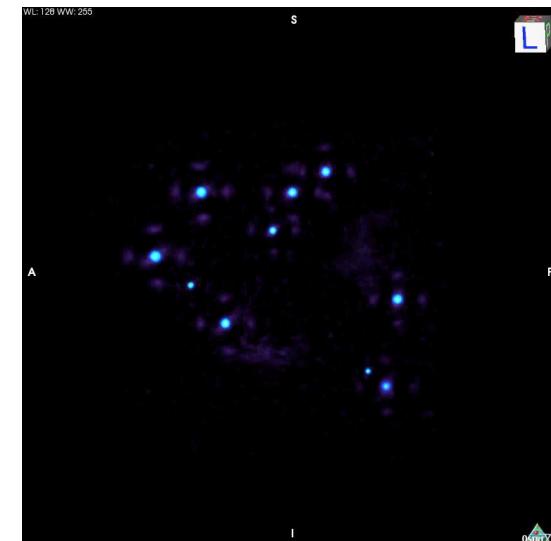


Original (3D shells + Gaussians)



Dictionary  
RidCurvelets + 3D UDWT.

Gaussians

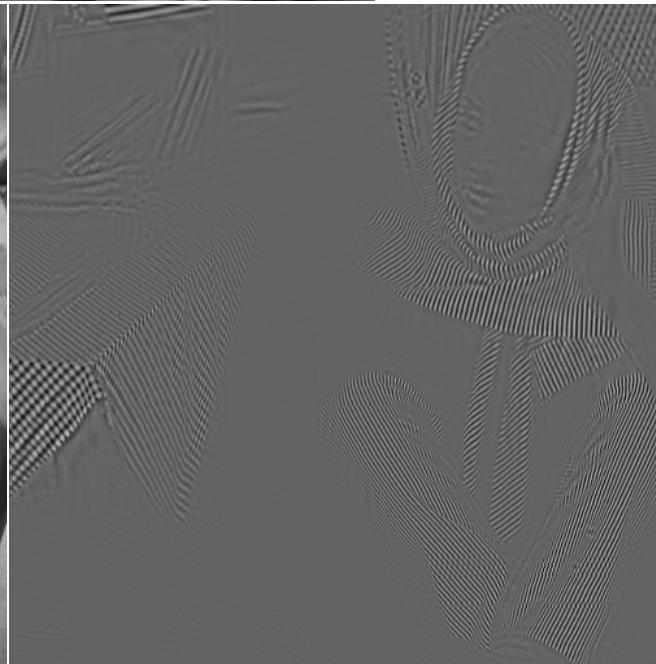


- A . Woiselle, J.L. Starck, M.J. Fadili, "[3D Data Denoising and Inpainting with the Fast Curvelet transform](#)", *JMIV*, 39, 2, pp 121-139, 2011.
- A. Woiselle, J.L. Starck, M.J. Fadili, "[3D curvelet transforms and astronomical data restoration](#)", *Applied and Computational Harmonic Analysis*, Vol. 28, No. 2, pp. 171-188, 2010.

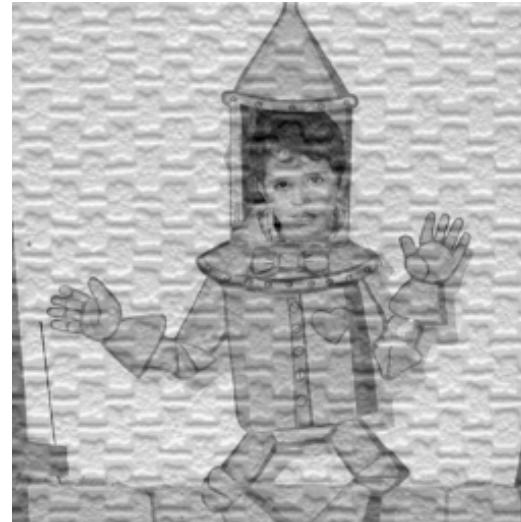
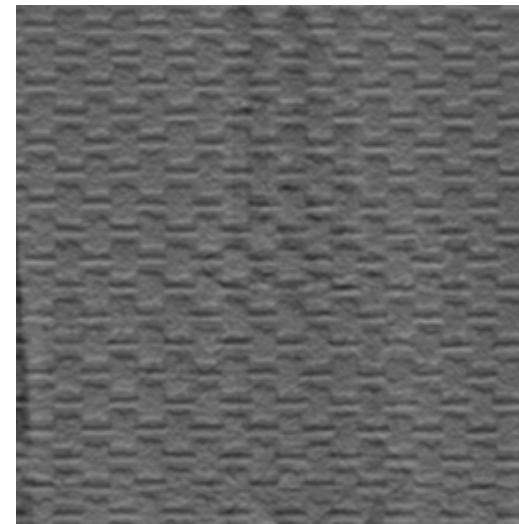
# Separation of Texture from Piecewise Smooth Content

The separation task: decomposition of an image into a texture and a natural (piecewise smooth) scene part.





## Texture Separation using MCA: Curvelet + DCT

 $X_n$  $X_t$ 

# Edge Detection





Inp



inting



- *M. Elad, J.-L. Starck, D.L. Donoho, P. Querre, "Simultaneous Cartoon and Texture Image Inpainting using Morphological Component Analysis (MCA)", ACHA, Vol. 19, pp. 340-358, 2005.*
- *M.J. Fadili, J.-L. Starck and F. Murtagh, "Inpainting and Zooming using Sparse Representations", The Computer Journal, 52, 1, pp 64-79, 2009.*

$$\min_{\alpha} \|\alpha\|_{\ell_0} \text{ s.t. } y = Mx$$

Where M is the mask:  $M(i,j) = 0 \implies$  missing data  
 $M(i,j) = 1 \implies$  good data

$$x^{(n+1)} = \mathcal{S}_{\Phi, \lambda^{(n)}} \left\{ x^{(n)} + M(y - x^{(n)}) \right\}$$

Iterative Hard Thresholding with a decreasing threshold.

**MCAlab available at:** <http://www.greyc.ensicaen.fr/~jfadili>

# Missing Data

Period detection in temporal series

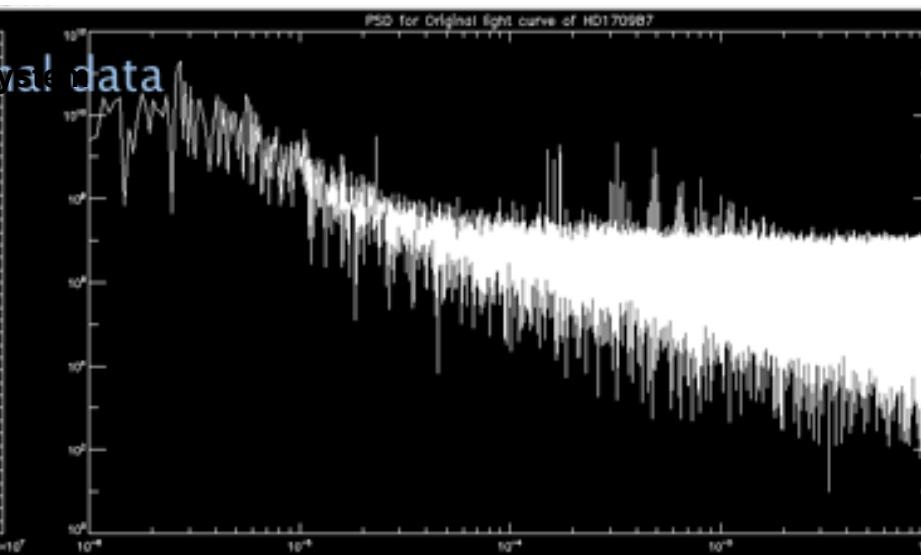
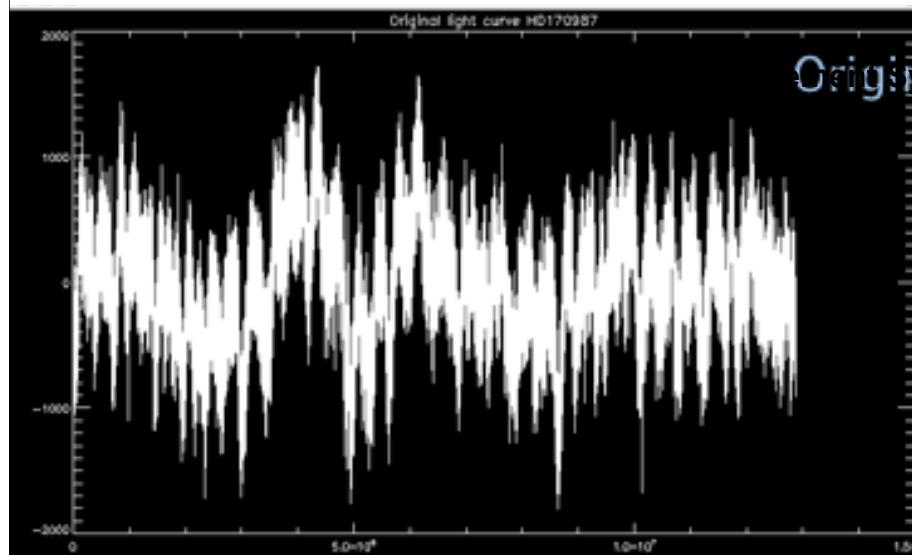
$$y = \Theta \Phi \alpha$$

Observation Mask  
Measurement System

FOURIER

$\alpha$

COROT: HD170987



- . Initialize all  $s_k$  to zero
- . Iterate  $j=1, \dots, N_{\text{iter}}$ 
  - Iterate  $k=1, \dots, L$
  - Update the  $k$ th part of the current solution by fixing all other parts and minimizing:

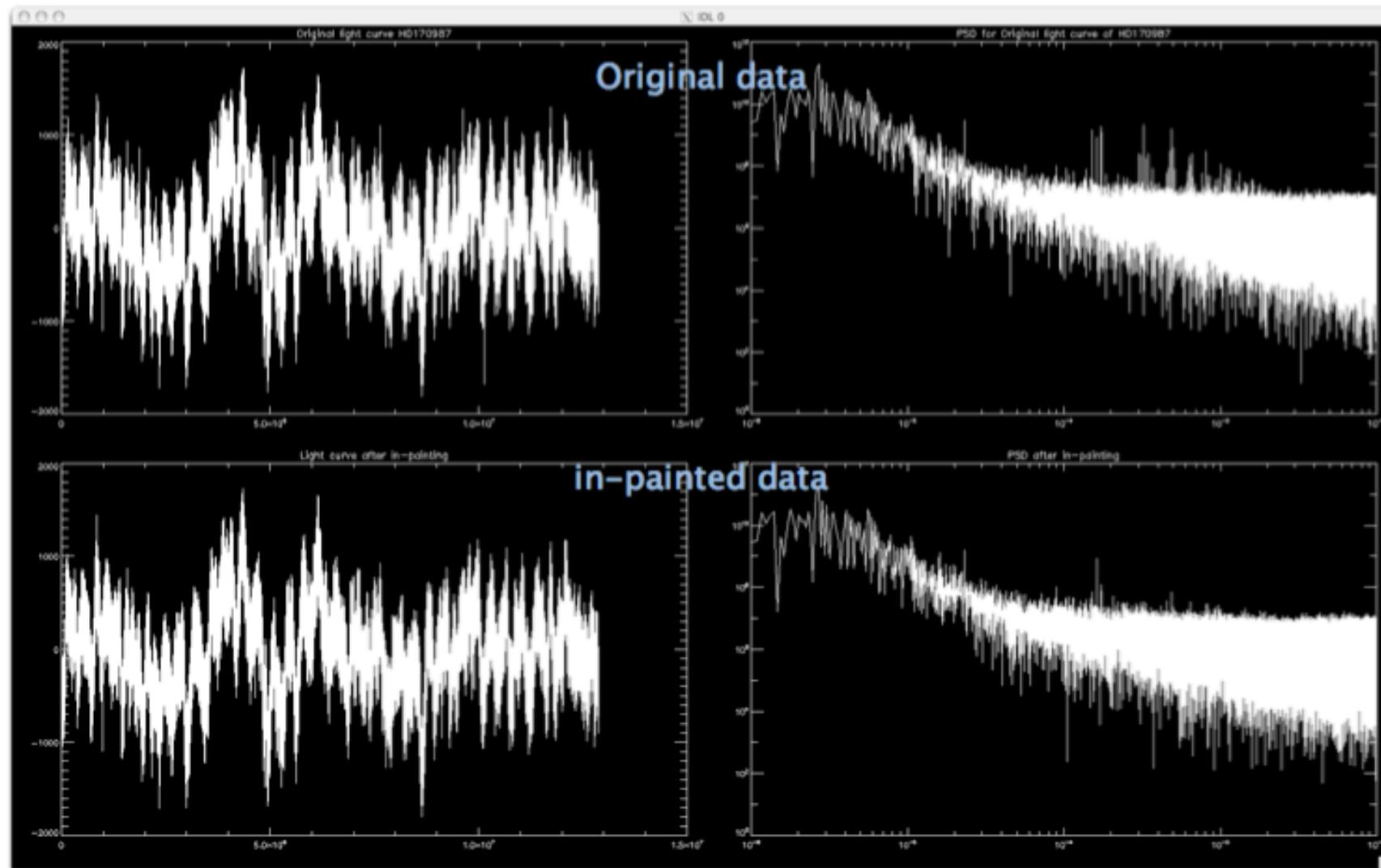
$$J(s_k) = \left\| M(s - \sum_{i=1, i \neq k}^L s_i - s_k) \right\|_2^2 + \lambda \|T_k s_k\|_1$$

Which is obtained by a simple soft thresholding of :

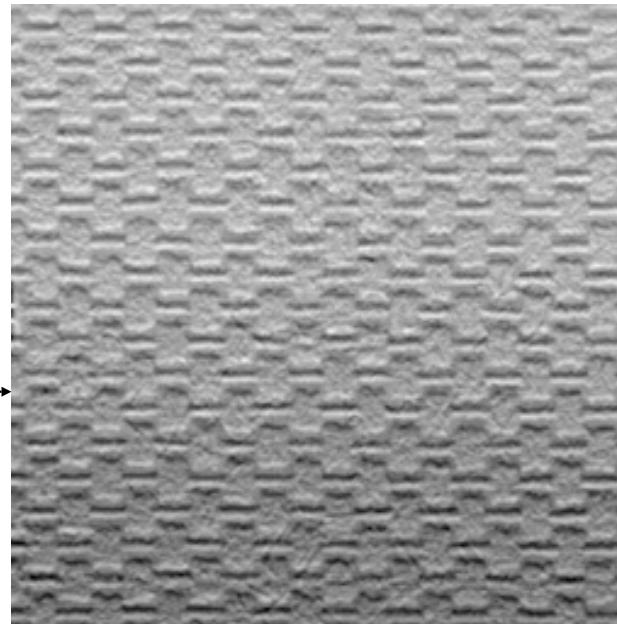
$$s_r = M(s - \sum_{i=1, i \neq k}^L s_i)$$

# COROT: HD170987 with in-painting

[arXiv:1003.5178](https://arxiv.org/abs/1003.5178)



*Image inpainting* [2, 10, 20, 38] is the process of restoring data in a designated region of a still or video frame. Applications range from removing objects from images to touch damaged paintings and photographs. Inpainting produces a revised image in which the restored area is seamlessly merged into the image in a way that is not detectable by a typical viewer. Traditionally, inpainting has been done by professional artists.<sup>7</sup> For photographs, inpainting is used to revert deterioration of images (e.g., scratches and dust spots in film), remove elements (e.g., removal of stamped date from photographs, the infamous “airbrushed” enemies [20]). A current active area of research is



20%



50%

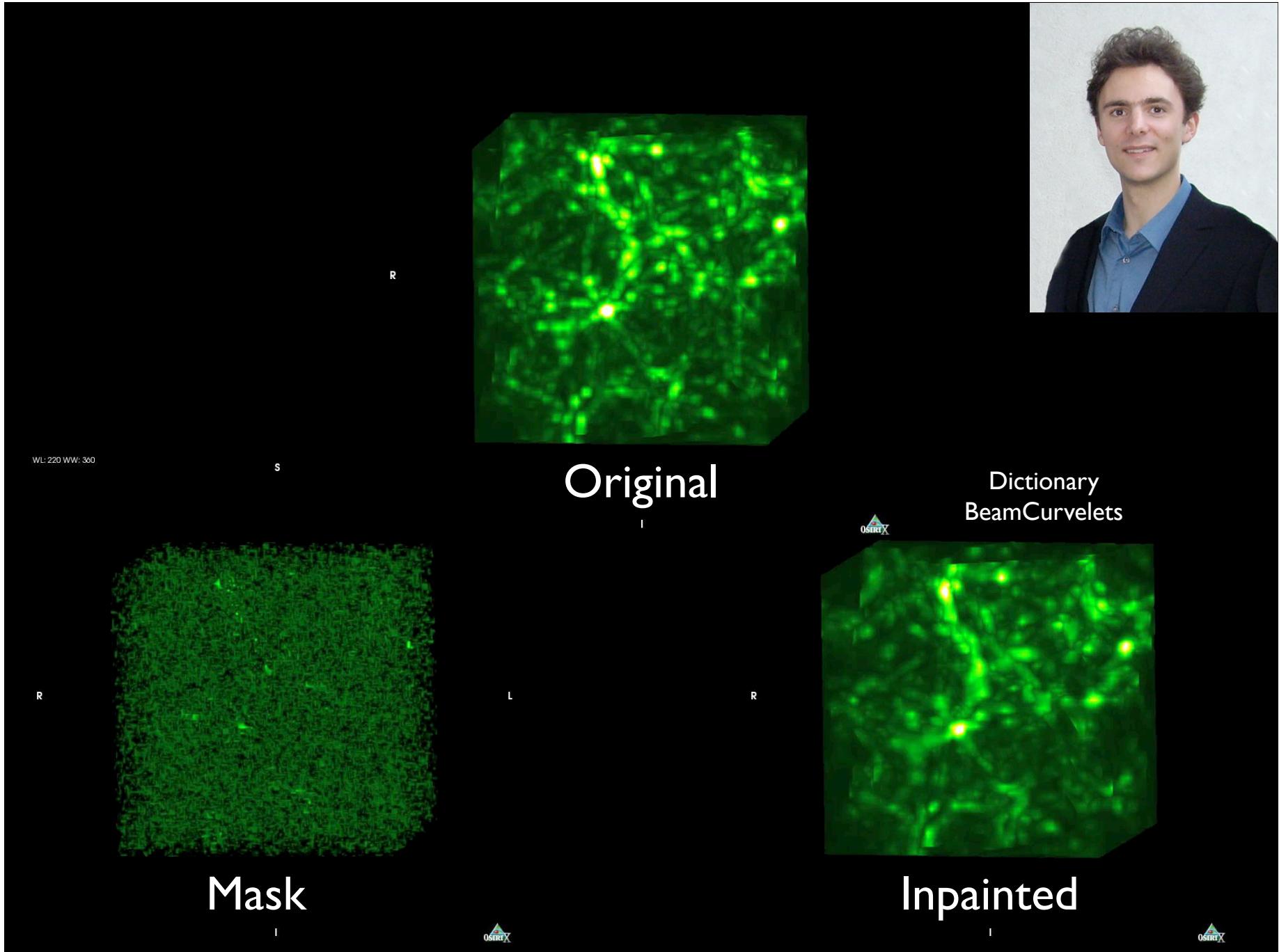


80%

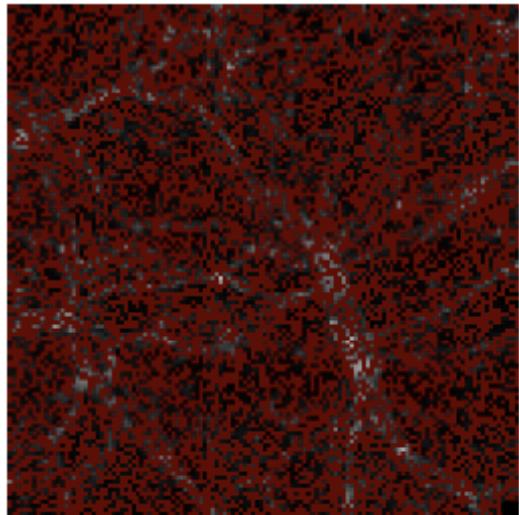




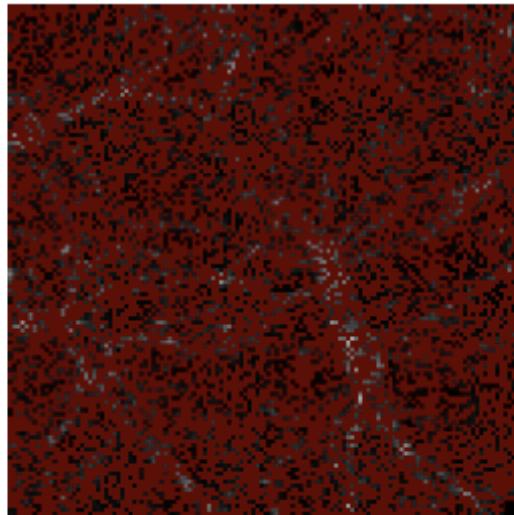




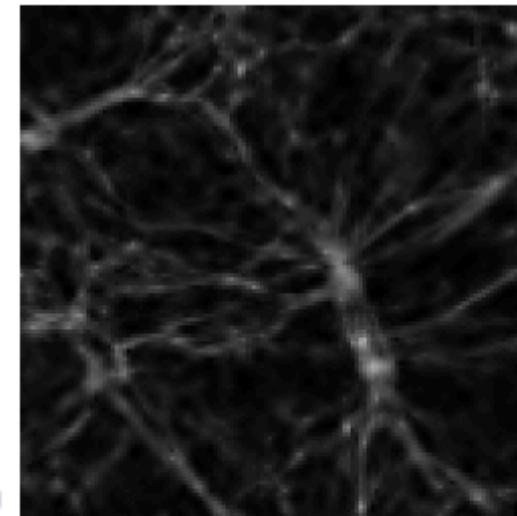
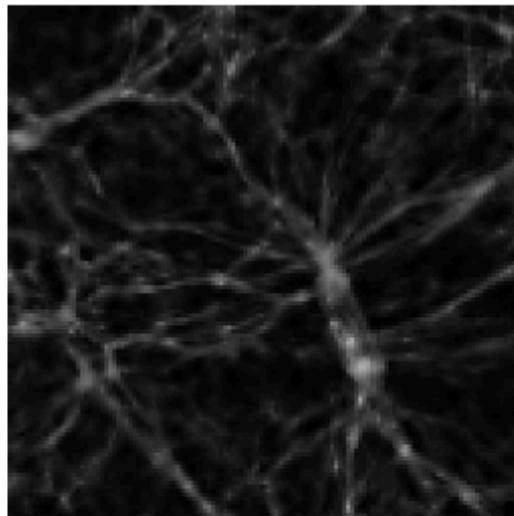
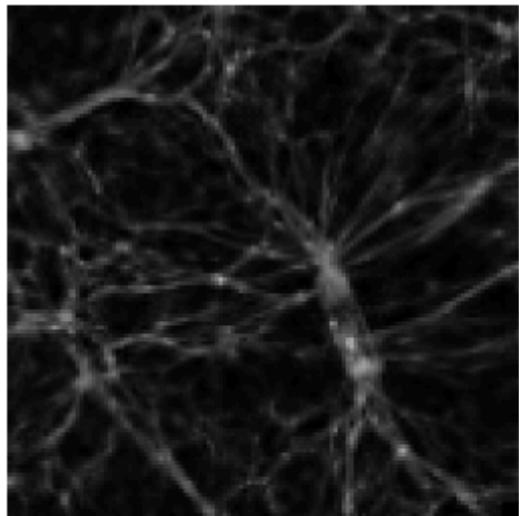
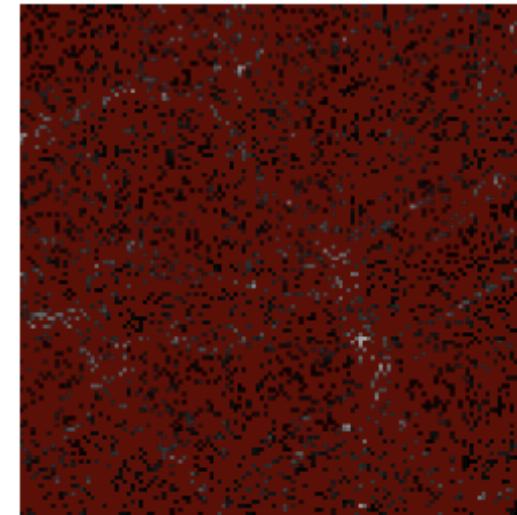
Masked (20%)



Masked (50%)

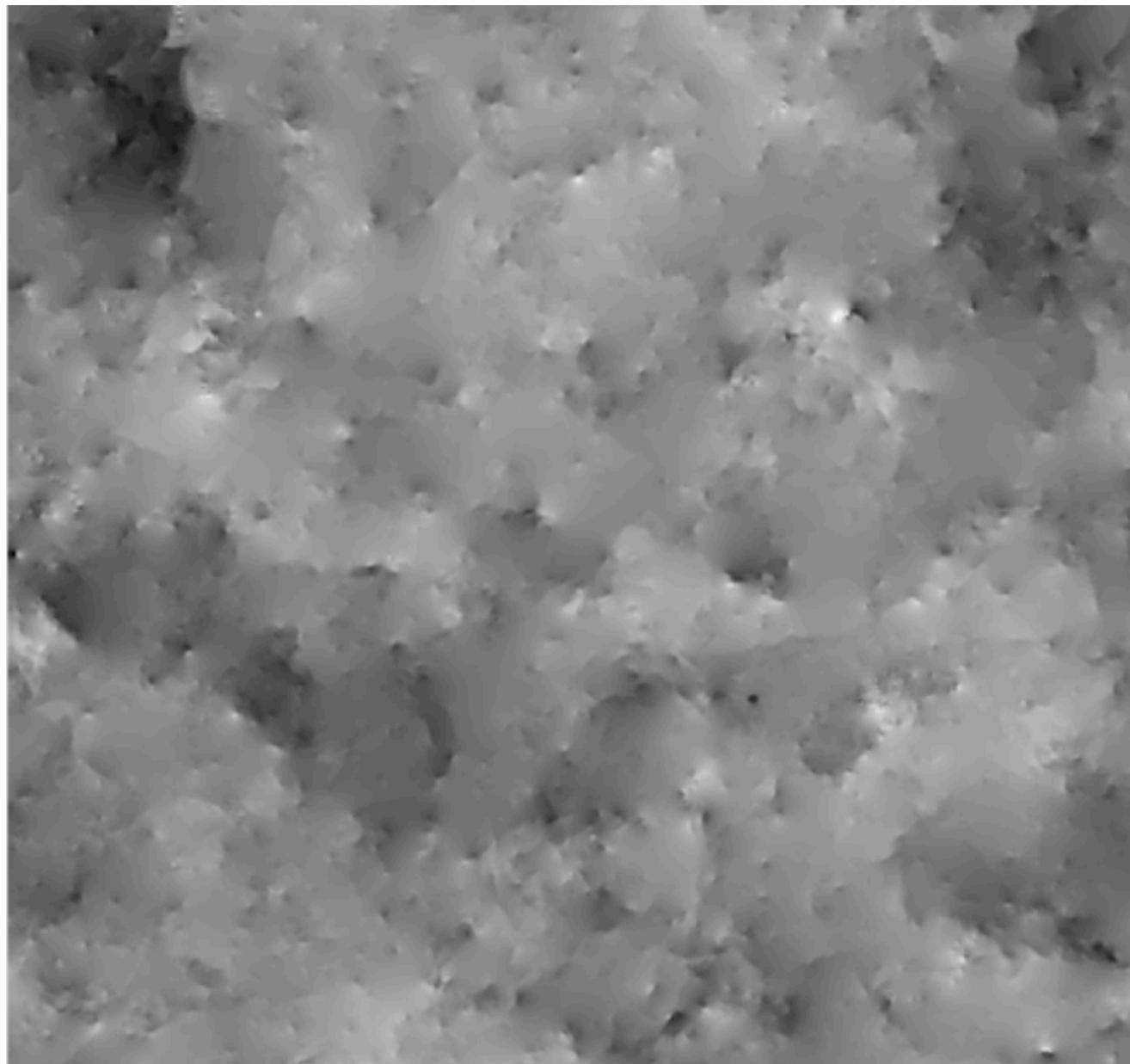


Masked (80%)

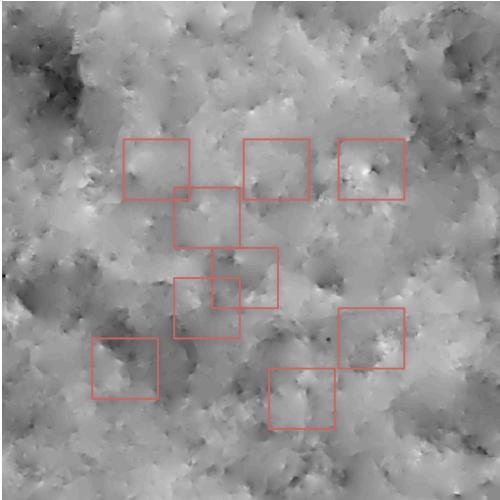


Central slice of the masked CDM data with 20, 50, and 80% missing voxels,  
and the inpainted maps. The missing voxels are dark red.

## Simulated Cosmic String Map

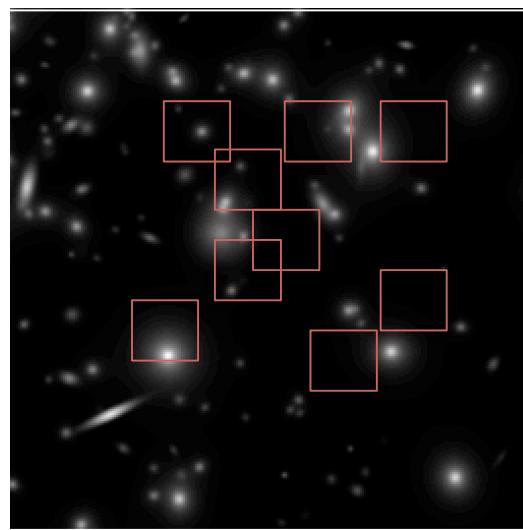


# Dictionary Learning



Training basis.

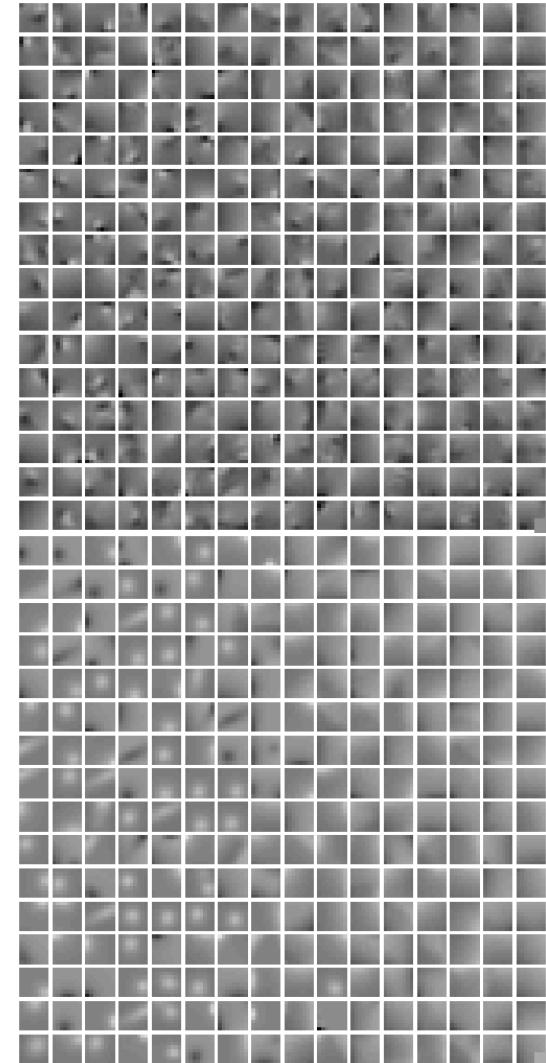
$$(\hat{D}, \hat{A}) = \arg \min_{\substack{D \in C_1 \\ A \in C_2}} (Y = DA)$$

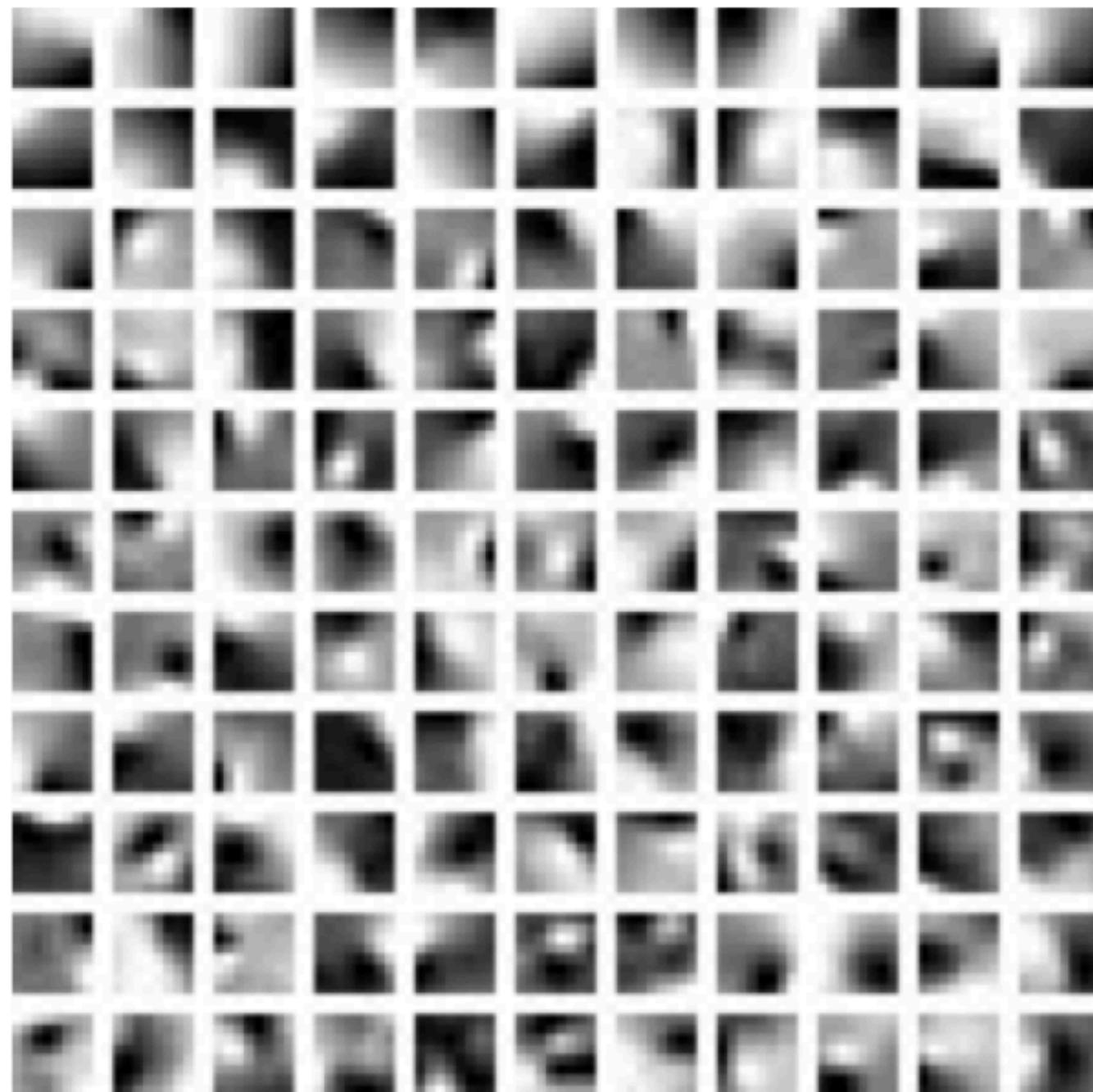


DL: Matrix Factorization problem

$C_1$ : Constraints on the Sparsifying dictionary D

$C_2$ : Constraints on the Sparse codes



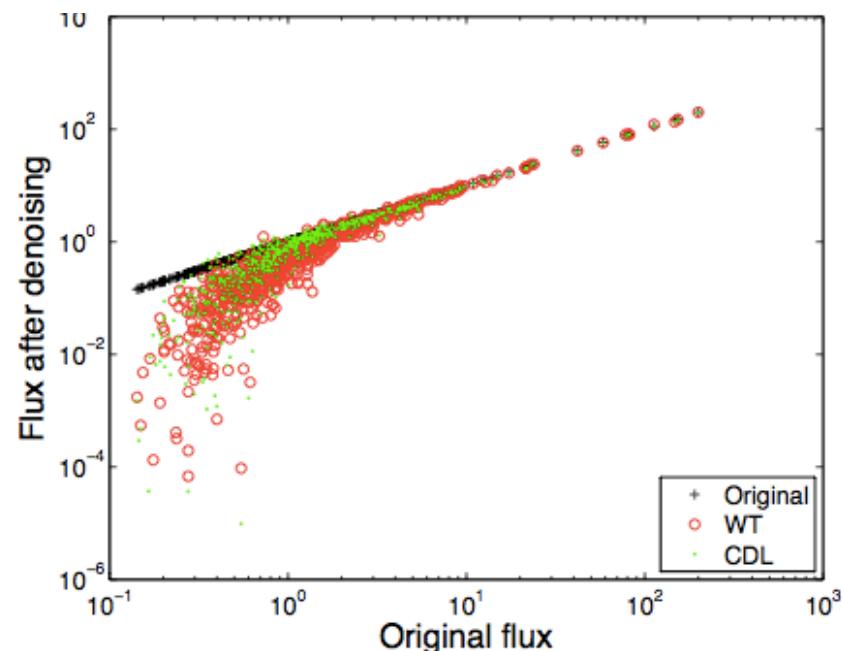
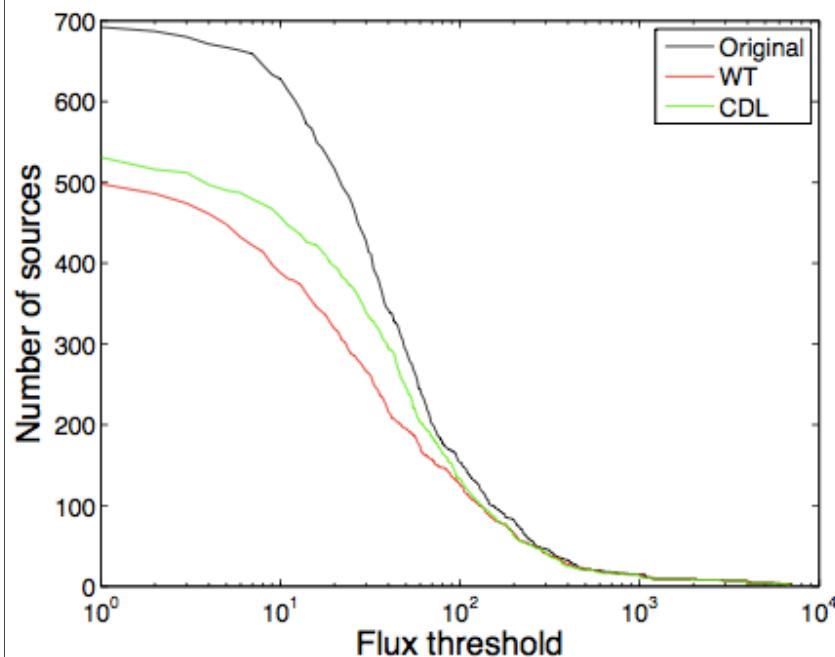
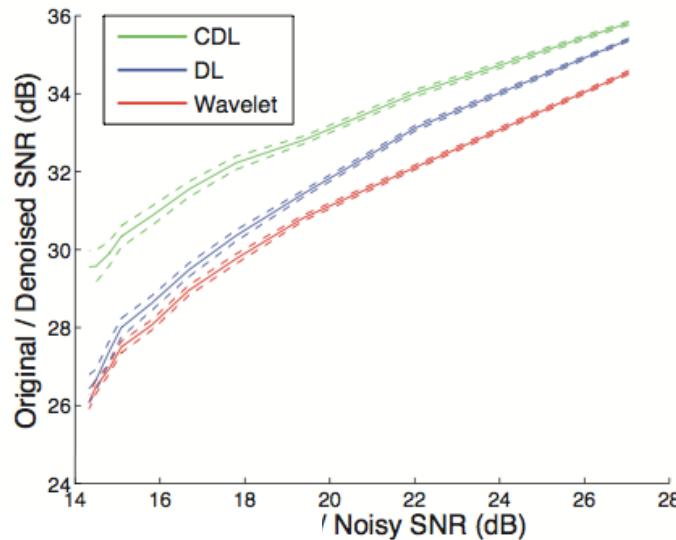






Astronomical Image Denoising Using Dictionary Learning, S. Beckouche, J.L. Starck, and J. Fadili, A&A, submitted.

S. Beckouche

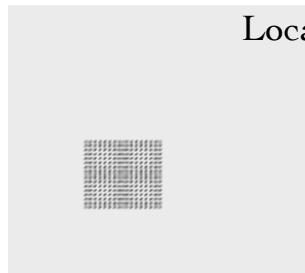


**Sparsity Model 1:** we consider a dictionary which has a fast transform/reconstruction operator:

$$\Phi = \{\phi_1, \dots, \phi_K\}$$

$$s = \sum_{k=1}^K \alpha_k \phi_k = \Phi \alpha$$

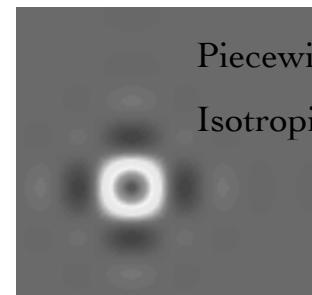
#### Local DCT



Stationary textures

Locally oscillatory

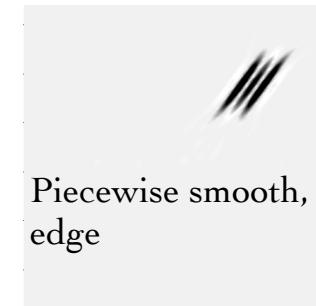
#### Wavelet transform



Piecewise smooth

Isotropic structures

#### Curvelet transform



Piecewise smooth,  
edge

**Sparsity Model 2:** Morphological Diversity:

$$\phi = [\phi_1, \dots, \phi_L], \quad \alpha = \{\alpha_1, \dots, \alpha_L\}, \quad s = \phi \alpha = \sum_{k=1}^L \phi_k \alpha_k$$

**Sparsity Model 3:** we adapt/learn the dictionary directly from the data

Model 3 can be also combined with model 2:

G. Peyre, M.J. Fadili and J.L. Starck, , "[Learning the Morphological Diversity](#)", SIAM Journal of Imaging Science, 3 (3) , pp.646-669, 2010.



**Advantages of model 1 (fixed dictionary)** : extremely fast.

**Advantages of model 2 (union of fixed dictionaries):**

- more flexible to model 1.
- The coupling of local DCT+curvelet is well adapted to a relatively large class of images.

**Advantages of model 3 (dictionary learning):**

atoms can be obtained which are well adapted to the data, and which could never be obtained with a fixed dictionary.

**Drawback of model 3 versus model 1,2:**

We pay the price of dictionary learning by being less sensitive to detect very faint features.

Complexity: Computation time, parameters, etc

# Morpho-Spectral Diversity

Data:  $X = [x_1, \dots, x_m]$

Source:  $S = [s_1, \dots, s_n]$

$$X = [x_1, \dots, x_m] = AS$$

$$x_l = \sum_{i=1}^n a_{i,l} s_i$$

$$\min_{\alpha} \|\alpha\|_p \text{ s.t } \mathbf{X} = \sum_{\gamma \in \Gamma} \alpha_\gamma \psi_\gamma$$

$$\begin{aligned} \Phi_A &= [\Phi_{A,1}, \Phi_{A,2}] \\ \Phi_S & \end{aligned}$$

Spatial Dictionary with  
Spectral Dictionary

$$\Psi = [\Phi_{A,1} \otimes \Phi_S, \Phi_{A,2} \otimes \Phi_S]$$

# Generalized MCA (GMCA)

- J. Bobin, J.-L. Starck, M.J. Fadili, and Y. Moudden, "Sparsity, Morphological Diversity and Blind Source Separation", IEEE Trans. on Image Processing, Vol 16, No 11, pp 2662 - 2674, 2007.
- J. Bobin, J.-L. Starck, M.J. Fadili, and Y. Moudden, "[Blind Source Separation: The Sparsity Revolution](#)", Advances in Imaging and Electron Physics , Vol 152, pp 221 -- 306, 2008.



Source:  $S = [s_1, \dots, s_n]$       Data:  $X = [x_1, \dots, x_m] = AS$

We now assume that the sources are linear combinations of morphological components :

$$s_i = \sum_{k=1}^K c_{i,k} \quad \text{such that } \alpha_{i,k} = T_{i,k} c_{i,k} \text{ sparse}$$

$$\Rightarrow X_l = \sum_{i=1}^n A_{i,l} s_i = \sum_{i=1}^n A_{i,l} \sum_{k=1}^K c_{i,k}$$

$\Rightarrow$  GMCA searches a sparse solution  $S$  in the dictionary subject to the constraint that the norm  $\|X\|$  is minimal.

$$\phi = [[\phi_{1,1}, \dots, \phi_{1,K}], \dots, [\phi_{n,1}, \dots, \phi_{n,K}]], \quad \alpha = S\phi^t = [[\alpha_{1,1}, \dots, \alpha_{1,K}], \dots, [\alpha_{n,1}, \dots, \alpha_{n,K}]]$$

GMCA aims at solving the following minimization:

$$\min_{A, c_{1,1}, \dots, c_{1,K}, \dots, c_{n,1}, \dots, c_{n,K}} = \sum_{l=1}^m \left\| X_l - \sum_{i=1}^n A_{i,l} \sum_{k=1}^K c_{i,k} \right\|_2^2 + \lambda \sum_{i=1}^n \sum_{k=1}^K \|T_{i,k} c_{i,k}\|_p$$

## Sparse Component Separation: the GMCA Method

---

A and S are estimated alternately and iteratively in two steps :

1) Estimate S assuming A is fixed (iterative thresholding) :

$$\{S\} = \operatorname{Argmin}_S \sum_j \lambda_j \|s_j \mathbf{W}\|_1 + \|\mathbf{X} - \mathbf{A}S\|_{F,\Sigma}^2$$

2) Estimate A assuming S is fixed (a simple least square problem) :

$$\{A\} = \operatorname{Argmin}_A \|\mathbf{X} - \mathbf{A}S\|_{F,\Sigma}^2$$

# BSS experiment : Noiseless case

Original  
Sources



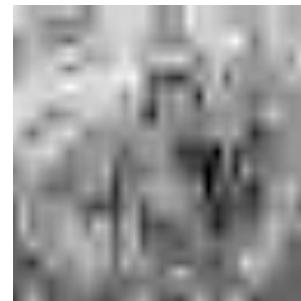
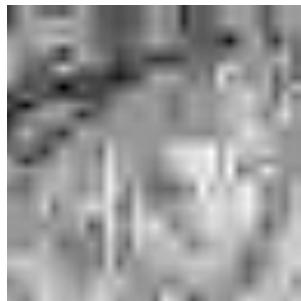
2 of 4 Mixtures



Noiseless experiment, 4 random mixtures, 4 sources

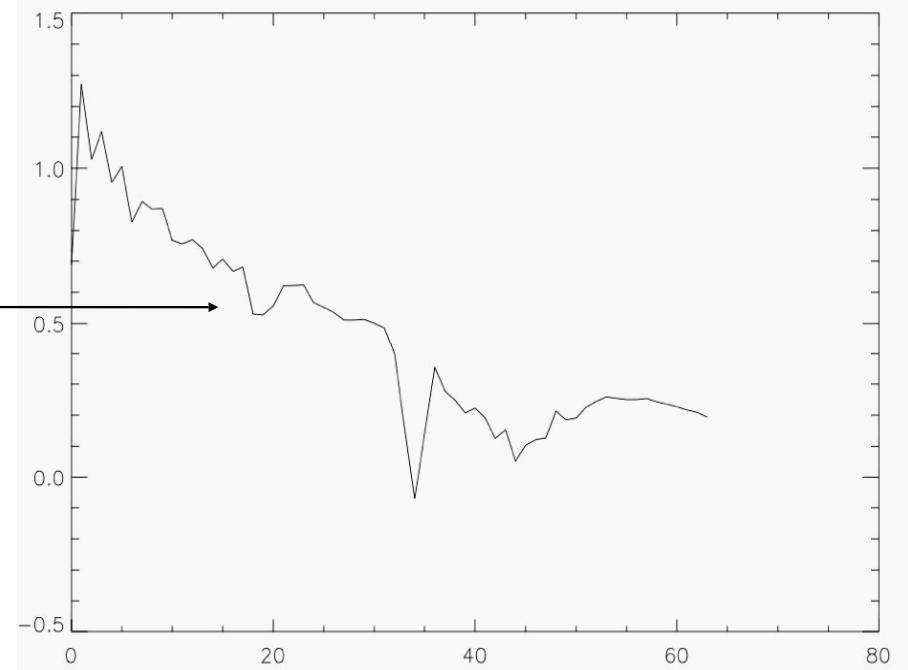
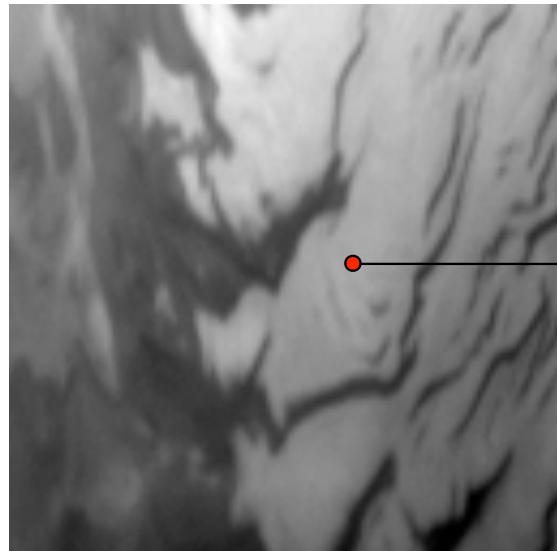
# GMCA Experiment

•J. Bobin, J.-L. Starck, M.J. Fadili, and Y. Moudden, "Sparsity, Morphological Diversity and Blind Source Separation", IEEE Trans. on Image Processing, Vol 16, No 11, pp 2662 - 2674, 2007.



# Hyperspectral Data

***Morphological Component Analysis for Sparse Multichannel Data: Application to Inpainting,***  
*Journal of Mathematical Imaging and Vision, submitted.*



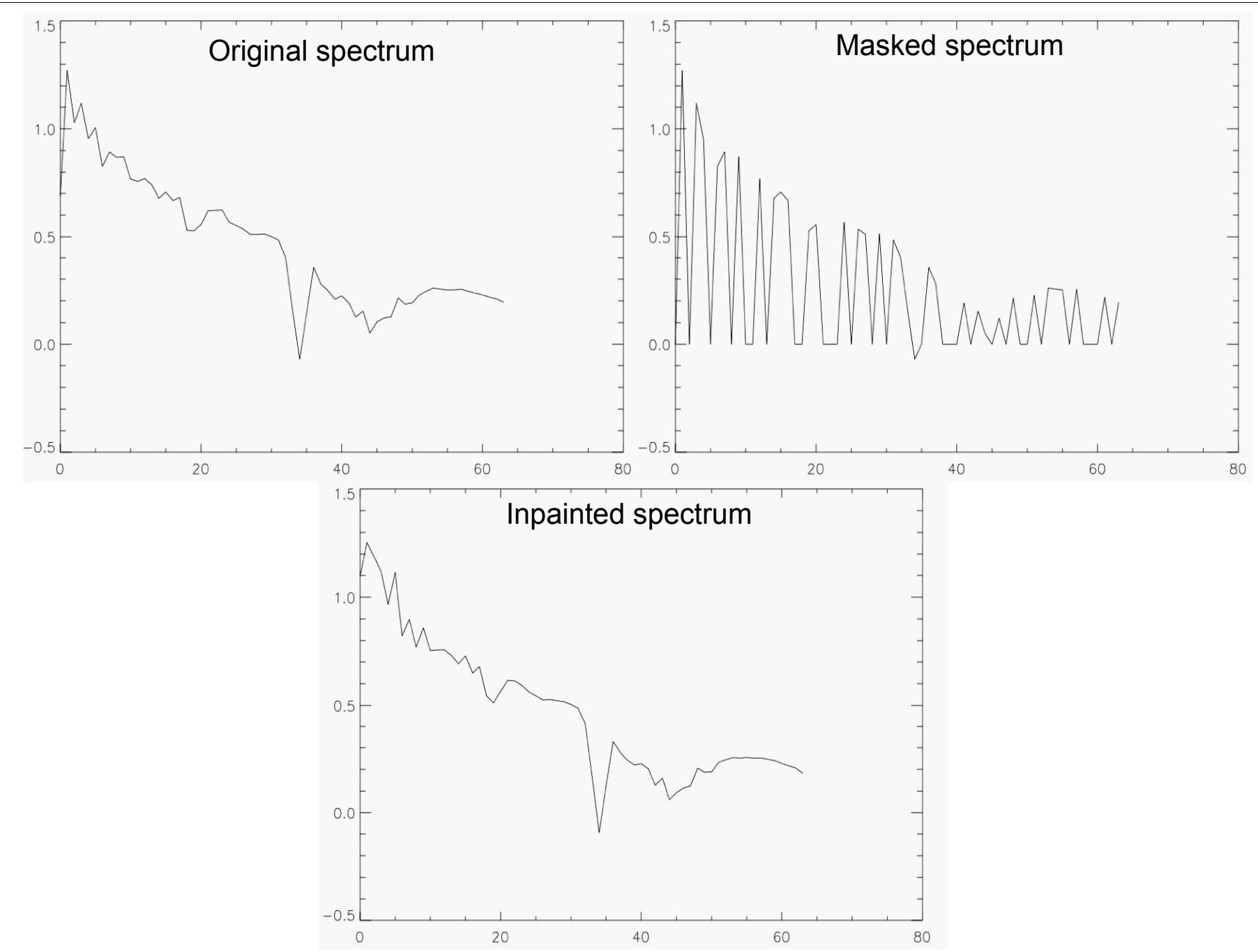
$$\min_{A, c_{1,1}, \dots, c_{1,K}, \dots, c_{n,1}, \dots, c_{n,K}} = \sum_{l=1}^m \left\| M_l \left( X_l - \sum_{i=1}^n A_{i,l} \sum_{k=1}^K c_{i,k} \right) \right\|_2^2 + \lambda \sum_{i=1}^n \sum_{k=1}^K \| T_{i,k} c_{i,k} \|_p + \lambda \sum_{i=1}^n \| W^{(1D)} A_i \|_p$$

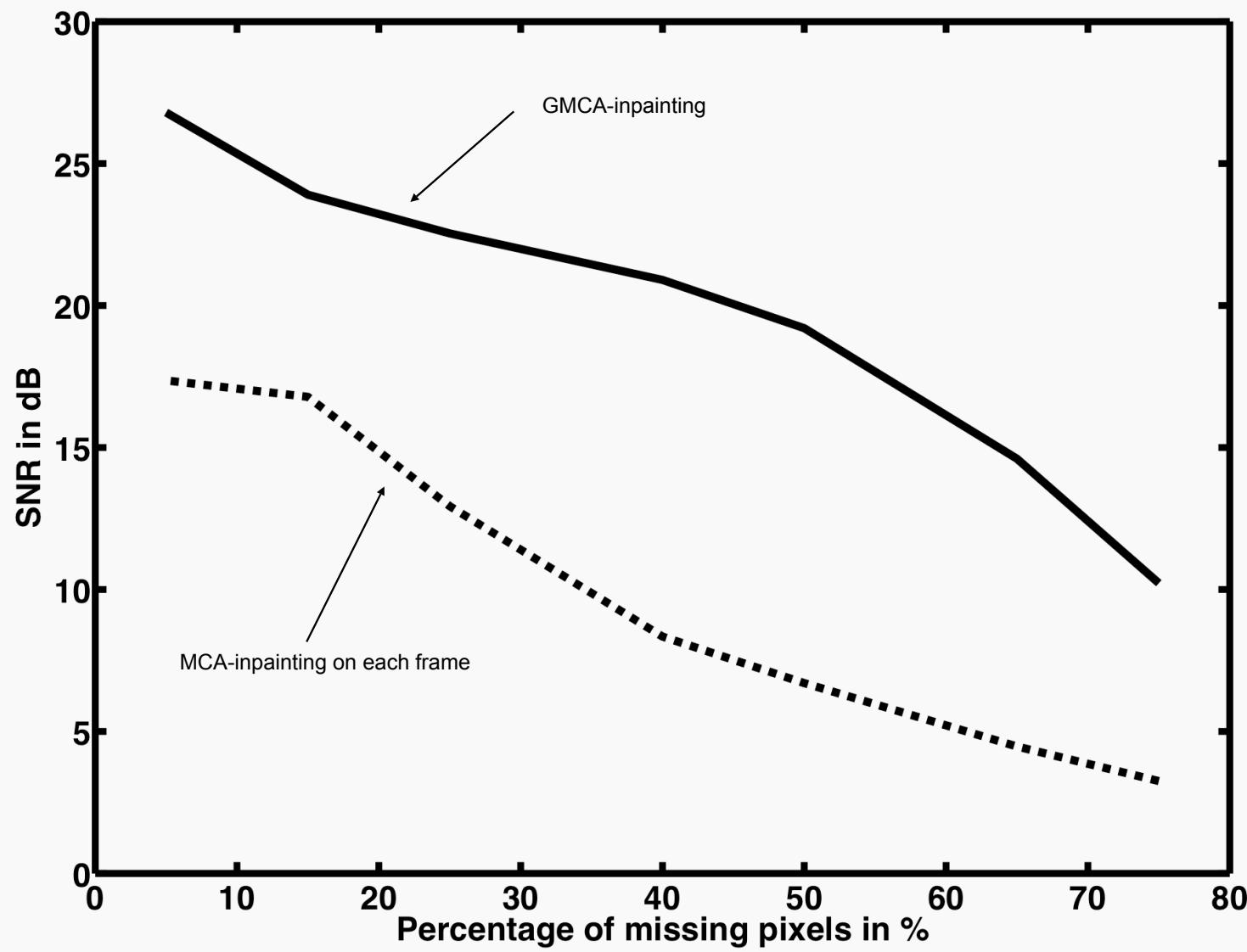
# Inpainting hyperspectral data

Omega Camera on Mars Orbiter: 128 x128 x 64 channels



50% missing pixels





# Inpainting color images

3 color channels

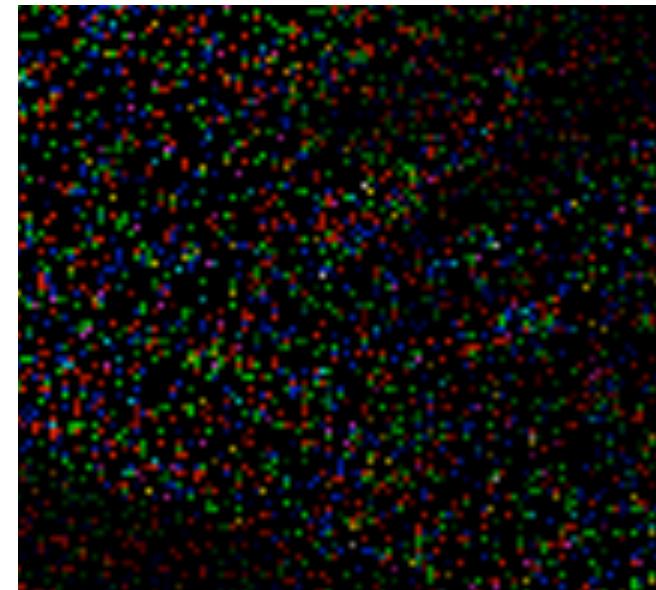
Dictionary  
Curvelets + LDCT



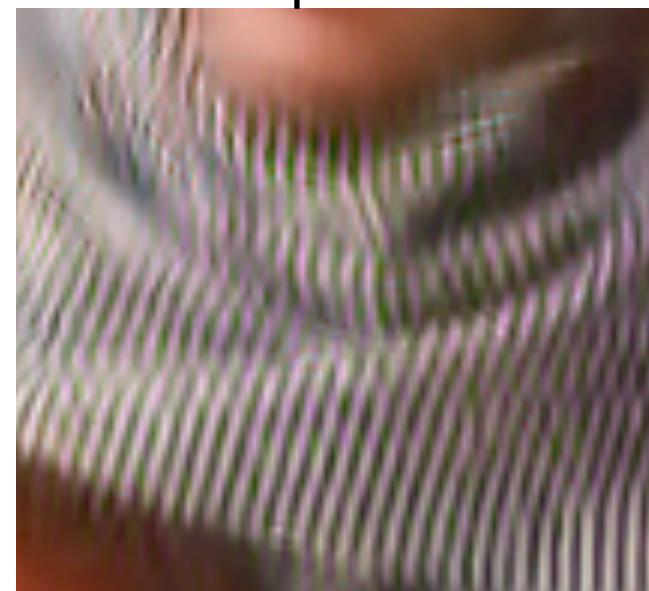
Original



Masked



Inpainted





Jean-Luc Starck  
Fionn Murtagh

# Astronomical Image and Data Analysis

Second Edition



 Springer

Jean-Luc Starck  
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# SPARSE IMAGE and SIGNAL PROCESSING

Wavelets, Curvelets,  
Morphological Diversity

CAMBRIDGE