

Challenges in Dynamic Imaging Data - 9-11 June 2015 TGM - Isaac Newton Institute - Cambridge

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Introduc	tion					

What is inpainting?



What is inpainting?

- Removal and filling of a region in an image or video
- The inpainted region should be visually convincing/pleasing



Image to inpaint



Inpainted image



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What is inpainting useful for?

- Restoring/improving/modifying images/videos
- Post-production of films



Original

Restored

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Video inpainting



Inpainted video

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Video inpainting



Original video



Challenges in *image* inpainting

 Filling-in geometric structures (amodal completion) [Masnou & Morel 1998], [Bertalmio et al. 2000]





Challenges in *image* inpainting

- Filling-in geometric structures (amodal completion) [Masnou & Morel 1998], [Bertalmio et al. 2000]
- Texture synthesis [Efros & Leung 1999]





Challenges in *image* inpainting

- Filling-in geometric structures (amodal completion) [Masnou & Morel 1998], [Bertalmio et al. 2000]
- Texture synthesis [Efros & Leung 1999]
- Geometry + conditional texture synthesis

[Cao et al. 2011]





Additional challenges of video inpainting

- Temporal coherency
- Dynamic geometry (reconstruction of moving objects)
- *Dynamic texture* (water pouring, flowing, flames)
- Simultaneous foreground/background reconstruction
- Extremely long computational times



Inpainting example (from Wexler *et al.* 2007)

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 Proposed inpainting algorithm
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Exemplar-based inpainting Similar to [Wexler 2004] (video inpainting) and [Arias et al. 2012] (image inpainting)

Key ingredients

- spatio-temporal patches
- alternated minimization of bi-convex energy
- multi-scale coarse-to-fine model
- accelerated ANN search
- texture-aware distance between patches
- how many scales?
- motion compensation



Video inpainting notation







 $\phi \quad \begin{array}{l} \text{Shift map (nearest} \\ \text{neighbour offsets)} \end{array}$

 ${\mathcal D}$ Unoccluded region

 ${\mathcal H}$ Occlusion

 W_p : a patch centered at p





Input: $u|_{\mathcal{D}}$ Output: $u|_{\mathcal{H}}$ Find $u|_{\mathcal{H}}$ by minimizing

$$E(u,\phi) = \sum_{p \in \mathcal{H}} ||W_p^u - W_{p+\phi(p)}^u||_2^2$$



 W_p : a patch centered at p



Inpainting Principle

Input: $u|_{\mathcal{D}}$ Output: $u|_{\mathcal{H}}$ Find $u|_{\mathcal{H}}$ by minimizing

$$E(u,\phi) = \sum_{p \in \mathcal{H}} ||W_p^u - W_{p+\phi(p)}^u||_2^2$$



 $W_p\colon$ a patch centered at p

Challenges

- non-convex energy
- high dimensionality (dimension = $5 \times 5 \times 5 \times 3 \approx 500$)

Solutions

- alternate (convex) minimization w.r.t. u and ϕ
- coarse-to-fine processing
- approximate nearest neighbours
- fine-level texture features in coarsest level



Inpainting Principle

Input: $u|_{\mathcal{D}}$ Output: $u|_{\mathcal{H}}$ Find $u|_{\mathcal{H}}$ by minimizing

$$E(u,\phi) = \sum_{p \in \mathcal{H}} ||W_p^u - W_{p+\phi(p)}^u||_2^2$$



 $W_p\colon$ a patch centered at p

Denoising Principle

Input: noisy \tilde{u} Output: denoised \hat{u} Find u by minimizing

$$E(u,w) = \sum_{p,q} w(p,q) ||W_p^{\tilde{u}} - W_q^{u}||_2^2$$
$$+ h \sum_p H(w(p,\cdot))$$





Inpainting Principle

Input: $u|_{\mathcal{D}}$ Output: $u|_{\mathcal{H}}$ Find $u|_{\mathcal{H}}$ by minimizing

$$E(u,\phi) = \sum_{p \in \mathcal{H}} ||W_p^u - W_{p+\phi(p)}^u||_2^2$$



 $W_p\!\!:$ a patch centered at p

Algorithm (inspired by \dagger and \ddagger):

Alternate Minimization on u and ϕ :

 $\begin{array}{l} u^{0} \leftarrow \text{Initialisation}(u|_{\mathcal{D}},\mathcal{H}) \\ 1/ \ \phi^{k+1} \leftarrow \text{NearestNeighbourSearch}(u^{k}) \\ 2/ \ u^{k+1} \leftarrow \text{VideoReconstruction}(\phi^{k+1}) \\ (\text{aggregation of patches}) \end{array}$

(Carried out in a Multiresolution scheme)

[†] Y. Wexler, E. Schechtman, M. Irani, Space-Time Completion of Video, PAMI 2007 [‡] P. Arias, G. Facciolo, V. Caselles, G. Sapiro, A Variational Framework for Exemplar-Based Image Inpainting, IJCV 2011



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Approximate Nearest Neighbour (ANN) search



High dimensionality of problem means NN search is very slow

- Previously used ANN search algorithm (kdTrees) very slow
- We extend the PatchMatch [Barnes *et al.* 2009][†] algorithm to spatio-temporal case.
- $\bullet\,$ PatchMatch based on piecewise constancy of the shift map ϕ



[†] C. Barnes, E. Schechtman, A. Finkelstein, D. B. Goldman, PatchMatch: a randomized correspondence algorithm for structural image editing, ACM Transactions on Graphics (2009)

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 Visual comparisons
 [Granados et al. 2012]
 Image: Comparison of the second second

High definition example (1120 \times 754)



- 10-50 times speedup with 3D PatchMatch
- 10 times speedup compared to Granados *et al.*

M. Granados, J. Tompkin, K.I. Kim, O. Grau, J. Kautz, C. Theobalt, How Not to Be Seen - Object Removal from Videos of Crowded Scenes, Computer Graphics Forum, 2012



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 Visual comparisons
 [Granados et al. 2012]
 Image: Comparison of the second second

	One matching pass at full res.					
	Beach umbrella (265x68x200)	Crossing ladies (170x80x87)	Jumping girl (1120x754x200)			
Wexler (kd-tree)	$\sim \! 1000 s$	~1000s	~8000s			
Ours (PatchMatch3D)	$\sim 50 s$	~30s	~150s			
		Total timing				
	Beach umbrella (265x68x200)	Duo (960x704x154)	Museum (1120x754x200)			
Granados (graph-cut)	11h		90h			
Ours w/o texture	14mn	4h	4h			
Ours	24mn	6h	6h			

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Textures in image/video inpainting



Why do textures pose a problem ?



Original image



Why do textures pose a problem ?



Inpainted image



Why do textures pose a problem ?



Incorrect approximate nearest neighbours





Imagine we want to find the ANN of a random patch:





Imagine we want to find the ANN of a *random* patch:

$$\begin{array}{c} \mathbf{X} \\ x_i \sim \mathcal{N}(\mu, \sigma^2) \\ i = 1 \cdots N \end{array} \qquad \begin{array}{c} \mathbf{Y} \\ \mathbf{y}_i \sim \mathcal{N}(\mu, \sigma^2) \\ \text{Which patch is} \\ \text{most similar to } \mathbf{X}? \end{array} \qquad \begin{array}{c} \mathbf{Y} \\ \mathbf{y}_i \sim \mathcal{N}(\mu, \sigma^2) \\ i = 1 \cdots N \end{array}$$

$$E[d(X, Y)] = 2N\sigma^2$$
$$E[d(X, Z)] = N\sigma^2$$



Imagine we want to find the ANN of a *random* patch:



 $E[d(X, Y)] = 2N\sigma^2$ $E[d(X, Z)] = N\sigma^2$

On average, d(X, Y) is *twice* as large as d(X, Z). On average, constant patch Z is preferred !



Imagine we want to find the ANN of a *random* patch:



On average, d(X, Y) is *twice* as large as d(X, Z). On average, constant patch Z is preferred ! Solution ? Change patch distance !



We wish to include some information pertaining to the texture.

Idea : include an estimation of the local variance



We wish to include some information pertaining to the texture.

Idea : include an estimation of the local variance

Different possibilities were tested. Finally, we chose (inspired by Liu and Caselles $2013^\dagger)$:

SSD:
$$[\mathsf{R}, \mathsf{G}, \mathsf{B}, \alpha g_{\nu} * |\nabla_x I|, \alpha g_{\nu} * |\nabla_y I|]$$

 $\alpha:$ a weighting scalar

 $g_{
u}$ in a gaussian kernel of size u .

[†] Y. Liu, V. Caselles, Exemplar-Based Image Inpainting Using Multiscale Graph Cuts, IEEE TIP (2013) [‡] J. Bruna & S. Mallat (2013). Invariant scattering convolution networks. IEEE TPAMI, 35(8), 187286 Introduction

n ANN Search

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Modified patch distance



Example of image created by $|\nabla_x I|_{\nu}$



Example of the impact of the modified distance



PatchMatch with regular SSD



Example of the impact of the modified distance



PatchMatch with modified SSD

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Inpainting with unmodified patch distance

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Image e	xample					



Inpainting with "Image Melding" (Darabi et al. 2012)

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Inpainting with modified patch distance

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Image e	example					



Original image

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Noise ex	xample					



Inpainting with unmodified patch distance

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Noise ex	xample					



Inpainting with modified patch distance

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Noise e	xample					



Inpainting with unmodified patch distance

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Noise ex	xample					



Inpainting with modified patch distance

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Video e	xample					



Original video

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Video ex	xample					



Unmodified patch distance

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Video ex	xample					



Modified patch distance

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Local minima, convergence and binary inpainting



The *multi-resolution* scheme is necessary to correctly inpaint



Occluded image



structures.

Result with one pyramid level



Result with three pyramid levels



The *multi-resolution* scheme is necessary to correctly inpaint structures.



Occluded image



Result with one pyramid

level



Result with three pyramid levels

Some interesting questions:

- Can we quantify the amount of subsampling needed ?
- Can we guarantee convergence to a desirable solution ?

Such questions are difficult to answer in general, so we use a simple situation !



The *multi-resolution* scheme is necessary to correctly inpaint structures.



Occluded image



Result with one pyramid

level



Result with three pyramid levels

- Study (very) simple situation
- Behaviour of the algorithm is easier to study



Main theoretical results in simple 1D case :

- Algorithm converges if the occlusion size is less than $2N 2\sqrt{N} + 1$
 - *N* is the patch size
- Otherwise, algorithm may be stuck in a local minimum



Main theoretical results in simple 1D case :

- Algorithm converges if the occlusion size is less than $2N 2\sqrt{N} + 1$
 - N is the patch size
- Otherwise, algorithm may be stuck in a local minimum

Verified for simple 2D situations.

Simple structure example. Patch size = 11×11



Occlusion size = 16 Occlusion size = 17

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Original video

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Our inpainting result

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Original video

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Our inpainting result



- complex motions
- long temporal occlusions
- select the patch size



Input image (occlusion border in red)



Patch size = 3×3



Patch size = 5×5



Patch size = 7×7



Patch size = 9×9



Patch size = 11×11



- More general features to discriminate dynamic textures and shapes
 - Motion features
 - True multi-scale criterion
 - Scattering transform [Bruna & Mallat 2013][†]
- Generative vs. deterministic inpainting:
 - Sample from a local conditional gaussian model instead of NN [Raad *et al.* 2015][‡]
 - Accelerated learning/querying of local Gaussian models [Guillemot *et al.* 2014]*

[†] Bruna, J., & Mallat, S. (2013). Invariant scattering convolution networks. IEEE TPAMI, 35(8), 187286

L. Raad, A. Desolneux, J-M. Morel (2014), Locally Gaussian Exemplar-Based Texture Synthesis

^{*} T. Guillemot, A. Almansa, T. Boubekeur, **Covariance Trees for 2D and 3D processing**, CVPR 2014. http://perso.telecom-paristech.fr/~boubek/papers/CovTree/



THANK YOU FOR LISTENING !

- More videos / paper / source-code: http://perso.enst.fr/~almansa/video_inpainting/
- Come see our **poster** on

Single-Shot High Dynamic Range Imaging !!

Open PhD Position

Subject Video Inpainting Location Paris and/or Lyon Supervisors A. Almansa, Y. Gousseau, S. Masnou